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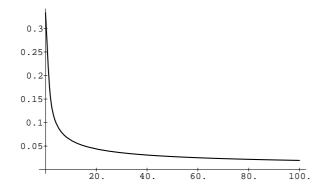
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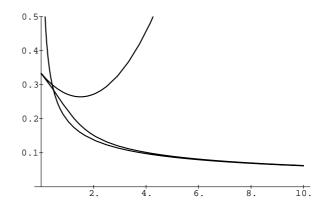
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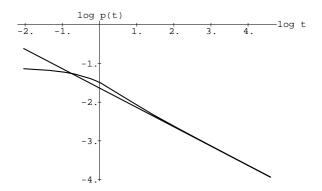
 $\alpha \approx$

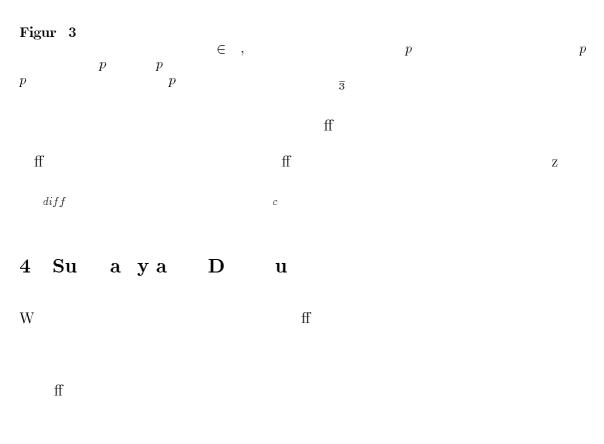
 $d \qquad \qquad \begin{matrix} & & & & & \\ & & & & & \\ d & & & & & \\ d^N \sim x & & ^N \sim \sigma & ^N, \end{matrix}$ $,\ \sigma =\sqrt{t},$ $\begin{array}{cc}t&\mathbf{M}\\x\end{array}$ $t^{N/2}$











function of the ordinary scale parameter .

$$p_d = \frac{1}{\pi} \sqrt{\frac{3}{2}} \left(+ - + O_{\frac{1}{2}} \right)$$
 3

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ff $d p = \frac{1}{3}$

$$_{d} \quad = \quad \left(\frac{p_{d}}{p_{d}}\right) = \quad \left(\frac{\pi}{3}\sqrt{\frac{1}{3}}\right) + - \qquad + \quad \left(\begin{array}{c} - - + O & \frac{1}{2} \end{array}\right) \qquad \qquad 33$$

ff

Corollary 8 (Effective scale at coarse scales (1D))

At coarse scales the effective scale—for one-dimensional discrete signals is approximately (up to an arbitrary affine transformation) a logarithmic function of the ordinary scale parameter .

$$-\frac{1}{t} + O \frac{1}{t^2}$$

ff ff

A B

$$f 3 \ 4 \qquad \qquad f B \ \ W \qquad \qquad f D \qquad \ \ R$$

ff

$$_{c}$$
 p p_{d} $m F$

F 3 A ff

$$_{
m W}$$

$$diff = \frac{d - c}{c - c} = \frac{d - c}{\frac{\log(2)}{2}}$$

$$c_{-d} = \frac{7}{\pi^2} \approx -34$$

$$\sigma = -5 - 4$$

$$P = -5 - P$$

Corollary 6 (Effective scale for discrete signals (1D))

For discrete one-dimensional signals the effective scale parameter d as function of the ordinary scale parameter d is given by

$$_{d} = A' + B'' \qquad \left(\frac{4\pi}{3\pi + 6\arctan\left(\frac{a(t)}{\sqrt{a^{2}(t)} \ a^{2}(t)}\right)}\right)$$

for some arbitrary constants A'' and $B'' > with a_0$ and a are given by (22) and (23).

W ff
$$d$$
 = $\frac{1}{4}$ Z W $A = B = \frac{1}{4}$

3 3 y B v F

A M dp $A = 55$
 $p_d = \frac{1}{3} - \frac{1}{\sqrt{3}\pi} + \frac{1}{6\sqrt{3}\pi} + \frac{1}{2} + O^{-3}$

3 3 M $A = \frac{1}{3} + \frac{1}{6\sqrt{3}\pi} + \frac{1}{3} + O^{-3}$

Corollary 7 (Effective scale at fine scales (1D))

At fine scales the effective scale for one-dimensional discrete signals is approximately an affine

 $d = \left(\frac{p_d}{p_d}\right) = \frac{\sqrt{3}}{\pi} + \left(\frac{3}{\sqrt{3}\pi} + \frac{3}{\pi^2}\right)^2 + O^{-3}$

$$a_1 = C \eta, \eta_2 = C \eta_2, \eta_1 = T ; - T ; + T ;$$

$$p_{d} = \int \int_{\{\eta = (\eta, \eta_{2}): (\eta \geq 0) \land (\eta_{2} \geq 0)\}} \frac{1}{\sqrt{\pi^{2} |C_{2D}|}} e^{-\frac{1}{2}\eta^{T} C_{2D} \eta} d\eta_{1} d\eta_{2}$$

$$4$$

A] A A 5 4

$$p_d = \frac{1}{4} + \frac{1}{\pi} \qquad \left(\frac{a_1}{\sqrt{a_0^2 - a_1^2}}\right) \qquad 5$$

 a_1

$$\left[\begin{array}{cc},\frac{1}{2}\right] \quad \mathrm{W} \qquad \qquad 0 \quad a \qquad \qquad a \quad \qquad a$$

$$p_d = \frac{1}{3}$$

Proposition 5 (Density of local extrema in discrete scale-space (1D))

In the scale-space representation (17) of a one-dimensional discrete signal generated by a white noise stationary normal process, the expected density of local maxima (minima) in a smoothed signal at a certain scale is given by (25) with a_0 and a according to (22) and (23).

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= :

$$p = p$$

$$\frac{1}{\pi}\sqrt{\frac{3}{\sqrt{1}}} = \frac{1}{3}$$

f

 $_{i}$ $_{1},L_{i},\!\!L_{i+1}$ T

 $\xi = \xi_1, \xi_2, \xi_3^T$ j

 ξ z f z

L C L

 $C_L \cdot ; = T \cdot ; *T \cdot ; *fC \cdot = T \cdot ; *fG \cdot$

 C_f f

 $T \cdot ; s * T \cdot ; = T \cdot ; s +$

 $_{f}C$ $_{L}\cdot C=T\cdot ;$

T - n; = T n; ξ

 m_{3D} :

 $\eta = \xi_2 - \xi_1$ $\eta_2 = \xi_2 - \xi_3$ $\eta = \eta_1, \eta_2^T$

j

 $m_{2D} = \left(\begin{array}{c} \\ \\ \end{array} \right); \qquad C_{2D} = \left(\begin{array}{ccc} a_0 & a_1 \\ \\ a_1 & a_0 \end{array} \right)$

 Γ C ·,·

 $a_0 = C \eta, \eta_1 = C \eta_2, \eta_2 = T ; -T ;$

normal process with spectral density $\omega^{-\beta}$, the expected density of local maxima (minima) in a smoothed signal at a certain scale decreases with scale as $-\frac{1}{2}$.

3 D y

 \mathbf{F}

z A

 $L: Z \times R_+ \to R$

 $L x; = \sum_{n=-\infty}^{\infty} T n; \quad f x - n$

 $T n; = e^{t} I_{n}$

] [

z ff]

 \mathbf{C}

7

 $P x_i =$

 $P \quad L \ \ x; \qquad \geq L \ \ x_{-1}; \qquad \wedge \quad L \ \ x; \qquad \geq L \ \ x_{+1};$

a graph showing the density of local maxima (minima) as

function of scale can be expected⁶ to be a straight line in a log-log diagram

$$p_c = -\frac{3}{-} - \pi - - = cons \ an \ - -$$

Corollary 3 (Effective scale for continuous signals (1D))

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P

For continuous one-dimensional signals the effective scale parameter $\ _{c}$ as function of the ordinary scale parameter is (up to an arbitrary affine transformation, i.e., for some arbitrary constants A^\prime and $B^\prime >~)$ given by a logarithmic transformation

$$_{c} = A + B'$$
 5

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Α

Proposition 4 (Density of local extrema in scale-space (fractal noise, 1D))

In the scale-space representation of a one-dimensional continuous signal generated by a stationary

$$h$$
 g F G

$$g \ \xi; \quad = \frac{1}{\sqrt{\pi}} e^{-\xi^2/2t}; \quad G \ \omega; \quad = -e^{-\omega^2 t/2}$$

A
$$f S v =$$

$$S_L \omega = \frac{1}{4}e^{-\omega^2 t}$$

$$\int_0^\infty x^m e^{-ax^2} dx = \frac{\Gamma \frac{m+1}{2}}{a^{\frac{m+}{2}}}$$

c : p

$$p_{c} = -\frac{1}{\pi} \sqrt{\frac{\int_{-\infty}^{\infty} \omega^{4} \frac{1}{4} e^{-\omega^{2} t} d\omega}{\int_{-\infty}^{\infty} \omega^{2} \frac{1}{4} e^{-\omega^{2} t} d\omega}} = -\frac{1}{\pi} \sqrt{\frac{\frac{\Gamma(\frac{5}{2})}{2t^{\frac{5}{2}}}}{\frac{\Gamma(\frac{3}{2})}{2t^{\frac{3}{2}}}}} = -\frac{3}{\pi} \sqrt{\frac{3}{2}} \sqrt{\frac{3}{2}}$$

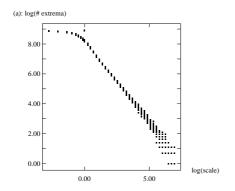
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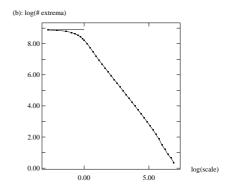
Proposition 2 (Density of local extrema in scale-space (white noise, 1D))

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In the scale-space representation of a one-dimensional continuous signal generated by a white noise stationary normal process, the expected density of local maxima (minima) in a smoothed signal at a certain scale decreases with scale as $\bar{2}$.

 $H \ \omega = \int_{-\infty}^{\infty} h - e^{i\omega t} d$





Figur

A inner scale

outer scale [7]

Z

ff C

ff j

ff

m W

ff

 ${f Ex}$ ${f Ex}$ ${f R}$

F $\mathbf{M}^{"} \quad] \quad [\ 5 \quad]$ $\mathbf{g} \quad = \ /$

 $= A + B \quad p \quad = A + B \qquad -\alpha B \qquad 6$

 $m ff \qquad \qquad R$

 ${
m ff}$

ff

 ${f F}$

 $\qquad \qquad \text{ff} \qquad \qquad ;$

 $f D \qquad \qquad f D \qquad f v$ A

4

$$p = \{$$

W
$$h$$
 ff $= h$:

Requirement 1 (Uniform relative decay rate for local extrema)

The probability that a certain extremum point (or equivalently a certain blob) disappears after a small increment d in effective scale should be independent of both the effective scale and the current number of local extrema in the signal. That is

$$\frac{\frac{dp}{d\tau}}{p} = \frac{d}{d} \frac{p}{d} = C_1 = cons \ an$$

3 :

$$p = C_1 + C_2 4$$

 \mathcal{C} A B

Proposition 1 (Effective scale)

Assume that we know how the expected density of local extrema p behaves as a function of scale and let—be the effective scale parameter given by Req. 1. Then, for some arbitrary constants A and B >, the effective scale as function of the ordinary scale parameter is given by

$$=h = A+B p 5$$

p(t) x t

j A W ${\rm ff}$ ff j [3] 2 T a Pa a : Eff \mathbf{h} a S a A " ff W "? ff z ? 3 Μ certain Δ ff the relative decay rate of local extrema should be constant over scales

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X X

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x

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) x

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discrete

continuous scale paràn[eter

W

 $inner\,scale\hspace{-.1cm}][7$

 $_1$ $_2$ $_{life} =$ $_2 _1$

F

Z

 $_{life} = _{2} - _{1}$

"

A ff W

ff

ff

 ${
m A}$

ff

 $(H \quad , \quad q \quad z \qquad \qquad q \qquad)$

 $1 \quad I \qquad \quad u$

ff

W W [] scale-space

- -

:

lifetime of structures

ff

 $\frac{\partial L}{\partial} = -\nabla^2 L$

L : ; = f $^{N} \times LR_{+}R \rightarrow R$

 $f: \c R o R \ [\hspace{1cm} 7 \hspace{1cm}]$

 $[1,\ 2]$ h:R o R

 $_{life}=h_{-2}$ $-h_{-1}$

effective scale

F continuous A

A A ff

A x A 1

Eff v S a : Na u a U M a u S a -S a L

Tony Lindeberg

C V A P CVAP

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 $W \hspace{1cm} w \hspace{1cm} f \hspace{1cm} w$

w fi w

 $f\!f$