

## Klassen $C^1$ & Kedjetegeln

Definition: Låt  $f: D \subset \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $D$  öppen mängd.

Vi säger att  $f$  är av klass  $C^1$  eller att  $f \in C^1(D)$  om  $f$  är partiellt derivierbar och om alla partiella derivater är kontinuerliga.

Sats: Om  $f \in C^1(D)$  så är den differentierbar i  $D$ .

Beweis: (Vtför beniset i  $d=3$ ) .

$$f \text{ differentierbar} \Leftrightarrow f(a+h) - f(a) = A_1 h_1 + A_2 h_2 + \dots + A_n h_n + \|h\| g(h)$$

där  $g(h) \rightarrow 0$ , då  $h \rightarrow 0$ .

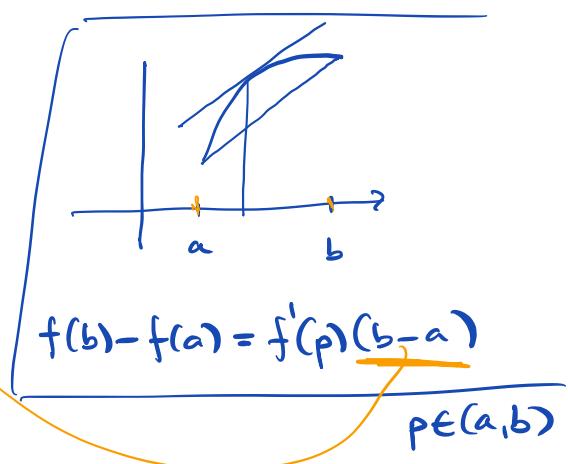
Enligt medelvärdessatsen för derivator ( $d=1$ )

$$\begin{aligned} & f(a_1+h_1, a_2+h_2, a_3+h_3) - f(a_1, a_2, a_3) \\ &= f(a_1+h_1, a_2+h_2, a_3+h_3) - \underline{f(a_1+h_1, a_2+h_2, a_3)} \\ &\quad + \underline{f(a_1+h_1, a_2+h_2, a_3)} - \underline{f(a_1+h_1, a_2, a_3)} \\ &\quad + \underline{f(a_1+h_1, a_2, a_3)} - f(a_1, a_2, a_3) \end{aligned}$$

$[\theta_j \in (0,1)]$

$$\begin{aligned} &= f'_z(a_1+h_1, a_2+h_2, a_3+\theta_3 h_3) \cdot h_3 \\ &\quad + f'_y(a_1+h_1, a_2+\theta_2 h_2, a_3) \cdot h_2 \\ &\quad + f'_x(a_1+\theta_1 h_1, a_2, a_3) \cdot h_1 \end{aligned}$$

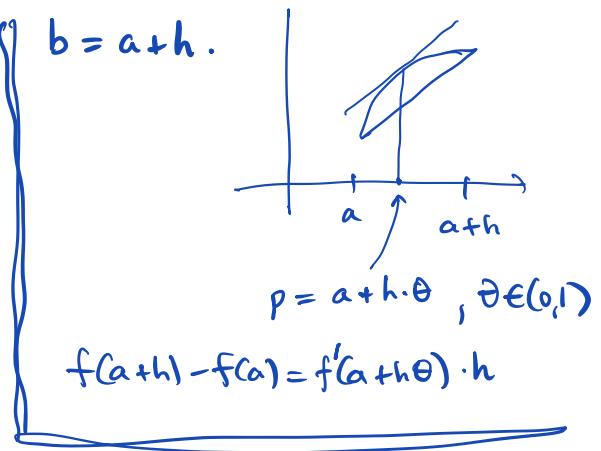
$$= \star$$



Nu vet vi att  $f'_x, f'_y, f'_z$  är kontinuerliga ( $f \in C^1(D)$ ).

$$\begin{aligned} f'_z(a_1+h_1, a_2+h_2, a_3+\theta_3 h_3) \\ = f'_z(a_1, a_2, a_3) + g_3(h). \end{aligned}$$

för någon funktion  $g_3$ .



Antag för vi

$$\begin{aligned} \textcircled{*} &= (f'_z(a_1, a_2, a_3) + g_3(h)) h_3 \\ &\quad + (f'_y(a_1, a_2, a_3) + g_2(h)) h_2 \\ &\quad + (f'_x(a_1, a_2, a_3) + g_1(h)) h_1 \quad a = (a_1, a_2, a_3) \\ &= f'_x(a) h_1 + f'_y(a) h_2 + f'_z(a) h_3 + \underbrace{g_1(h) h_1 + g_2(h) h_2 + g_3(h) h_3}_{= |h| g(h)}. \end{aligned}$$

$$\text{där } g(h) = \frac{1}{|h|} (h_1 g_1(h) + h_2 g_2(h) + h_3 g_3(h))$$

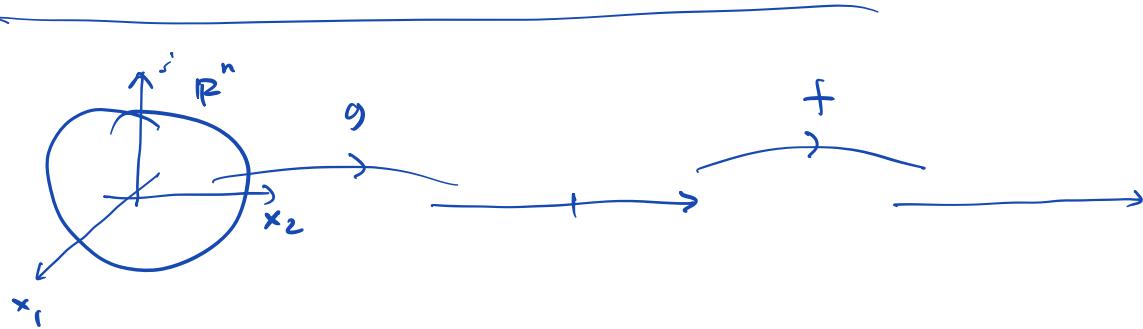
Vi vill visa att  $g(h) \rightarrow 0$ , då  $h \rightarrow 0$ .

$$\begin{aligned} 0 \leq |g(h)| &\leq \frac{|h_1| |g_1(h)| + |h_2| |g_2(h)| + |h_3| |g_3(h)|}{|h|} \quad |h_j| \leq |h| \\ &= |g_1(h)| + |g_2(h)| + |g_3(h)| \end{aligned}$$

$$g_1(h) = f'_x(a_1+h_1, a_2, a_3) - f'_x(a_1, a_2, a_3) \rightarrow 0, \text{ då } h \rightarrow 0.$$

Kedjeregeln:

d=1:  $\frac{d}{dx}(f(g(x))) = f'(g(x)) \cdot g'(x).$

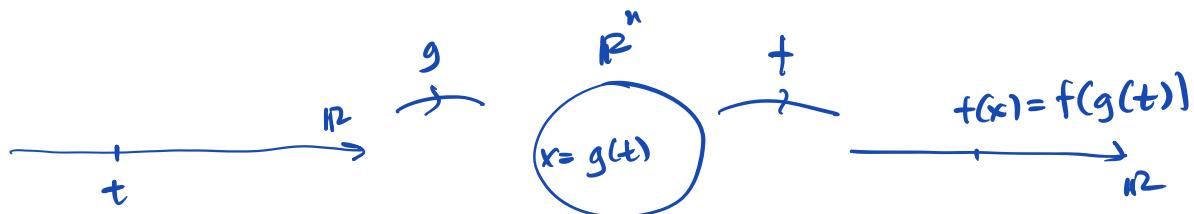


Om  $f: \mathbb{R} \rightarrow \mathbb{R}$ ,  $g: \mathbb{R}^n \rightarrow \mathbb{R}$ .

$$\frac{\partial}{\partial x_j}(f(g(x))) = f'(g(x)) \cdot g'_{x_j}(x)$$

Frys de andra  
variablerna.

Låt nu  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  och  $g: \mathbb{R} \rightarrow \mathbb{R}^n$



Sats: (Kedjeregeln)

Låt  $f(x) = f(x_1, x_2, \dots, x_n)$  vara differentierbar och  
antag att funktionerna  $g_1, g_2, g_3, \dots, g_n$  är deniverbara.  
Då gäller att

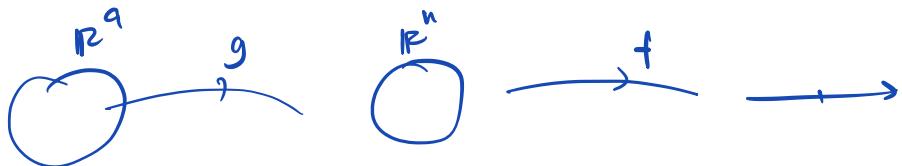
$$g(t) = (g_1(t), \dots, g_n(t))$$

$$\vec{x} = (x_1, x_2, \dots, x_n)$$

$$\frac{d}{dt} (f(g(t))) = f'(x_1(g(t))g'_1(t) + \dots + f'(x_n(g(t))) \cdot g'_n(t).$$

$$= \frac{\partial f}{\partial x_1} \cdot \frac{dg_1}{dt} + \dots + \frac{\partial f}{\partial x_n} \cdot \frac{dg_n}{dt}.$$

1 allmänta fallet  $g: \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  $f: \mathbb{R}^m \rightarrow \mathbb{R}$ .



$$\frac{\partial f}{\partial t_j}(x) = \frac{\partial f}{\partial x_1} \cdot \frac{\partial x_1}{\partial t_j} + \frac{\partial f}{\partial x_2} \cdot \frac{\partial x_2}{\partial t_j} + \dots + \frac{\partial f}{\partial x_n} \cdot \frac{\partial x_n}{\partial t_j}.$$

Ex:  $z = \sin(x^2y)$ , där  $x = x(s,t) = st^2$ ,  $y = s^2 + \frac{1}{t}$ .

Beräkna  $\frac{\partial z}{\partial s}$  och  $\frac{\partial z}{\partial t}$ .

Lösning:

$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial s} = \cos(x^2y) \cdot 2xy \cdot t^2$$

$$+ \cos(x^2y) \cdot x^2 \cdot 2s$$

$$= \cos(s^2t^4(s^2 + \frac{1}{t})) \cdot 2st^2(s^2 + \frac{1}{t})t^2$$

$$+ \cos(s^2t^4(s^2 + \frac{1}{t})) \cdot s^2t^4 \cdot 2s$$

$$= \cos(s^4t^4 + s^2t^3) t (2s^3t^4 + 2st^3 + 2s^3t^4)$$

$$= (4s^3t^4 + 2st^3) \cos(s^4t^4 + s^2t^3).$$

$$\sin(x^2y)$$

$$\begin{aligned}\frac{\partial z}{\partial t} &= \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial t} = \cos(x^2y) \cdot 2xy \cdot 2st \\ &\quad + \cos(x^2y) \cdot x^2 \left(-\frac{1}{t^2}\right) = \dots = \cos(s^4t^4 + s^2t^3) (4s^4t^3 + 4s^2t^2 - s^2t^3).\end{aligned}$$

Ex: Transformera uttrycket  $f: \mathbb{R}^2 \setminus \{(0,0)\} \rightarrow \mathbb{R}$

$$\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2 \quad \text{genom övergång till polära koordinater.}$$

Lösning:  $\begin{cases} x = r \cdot \cos\theta \\ y = r \cdot \sin\theta \end{cases}$

$$\begin{cases} \frac{\partial f}{\partial r} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial r} = \cos\theta \frac{\partial f}{\partial x} + \sin\theta \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial \theta} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial \theta} = -r\sin\theta \frac{\partial f}{\partial x} + r\cos\theta \frac{\partial f}{\partial y} \end{cases}$$

$$(1) \cdot r\cos\theta - (2) \cdot \sin\theta :$$

$$r\cos\theta \cdot \frac{\partial f}{\partial r} - \sin\theta \frac{\partial f}{\partial \theta} = +\cos^2\theta \underbrace{\frac{\partial f}{\partial x}}_{\text{trigonometriska etan}} + r\sin^2\theta \underbrace{\frac{\partial f}{\partial y}}_{\cos^2\theta + \sin^2\theta = 1} + 0$$

$\Leftrightarrow$

$$\frac{\partial f}{\partial x} = \cos\theta \frac{\partial f}{\partial r} - \frac{\sin\theta}{r} \frac{\partial f}{\partial \theta}.$$

$$(1) \cdot r\sin\theta + (2) \cos\theta :$$

$$r \cdot \sin\theta \cdot \frac{\partial f}{\partial r} + \cos\theta \frac{\partial f}{\partial \theta} = 0 + r \sin^2\theta \underbrace{\frac{\partial f}{\partial y}}_{= r \frac{\partial f}{\partial y}} + r \cos^2\theta \underbrace{\frac{\partial f}{\partial y}}_{= r \frac{\partial f}{\partial y}}$$

$$\Leftrightarrow \frac{\partial f}{\partial y} = \sin\theta \frac{\partial f}{\partial r} + \frac{\cos\theta}{r} \frac{\partial f}{\partial \theta}.$$

Ahrt sin

$$\begin{aligned} \left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2 &= \left(\cos\theta \frac{\partial f}{\partial r} - \frac{\sin\theta}{r} \frac{\partial f}{\partial \theta}\right)^2 + \left(\sin\theta \frac{\partial f}{\partial r} + \frac{\cos\theta}{r} \frac{\partial f}{\partial \theta}\right)^2 \\ &= \cos^2\theta \left(\frac{\partial f}{\partial r}\right)^2 - \cancel{2 \sin\theta \cos\theta \frac{\partial f}{\partial r} \frac{\partial f}{\partial \theta}} + \frac{\sin^2\theta}{r^2} \left(\frac{\partial f}{\partial \theta}\right)^2 \\ &\quad + \sin^2\theta \left(\frac{\partial f}{\partial r}\right)^2 + \cancel{2 \sin\theta \cos\theta \frac{\partial f}{\partial r} \cdot \frac{\partial f}{\partial \theta}} + \frac{\cos^2\theta}{r^2} \left(\frac{\partial f}{\partial \theta}\right)^2 \\ &= \left(\frac{\partial f}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial f}{\partial \theta}\right)^2. \end{aligned}$$

Ex:  $y \cdot \frac{\partial u}{\partial x} - x \cdot \frac{\partial u}{\partial y} = 0 \quad , \quad x > 0, y > 0.$

inför variablerna  $\begin{cases} s = x^2 + y^2 \\ t = x^2 - y^2 \end{cases} \quad \begin{matrix} s = s(x,y) \\ t = t(x,y) \end{matrix}$

Vi söker den lösning som uppfyller att  
 $u(0,y) = e^y$ .

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial s} \cdot \frac{\partial s}{\partial x} + \frac{\partial u}{\partial t} \cdot \frac{\partial t}{\partial x} = \frac{\partial u}{\partial s} \cdot 2x + \frac{\partial u}{\partial t} \cdot 2x$$

$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial s} \cdot \frac{\partial s}{\partial y} + \frac{\partial u}{\partial t} \cdot \frac{\partial t}{\partial y} = \frac{\partial u}{\partial s} \cdot 2y - \frac{\partial u}{\partial t} \cdot 2y.$$

$$y \frac{\partial u}{\partial x} - x \frac{\partial u}{\partial y} = \cancel{2xy \frac{\partial u}{\partial s}} + 2xy \frac{\partial u}{\partial t} - \cancel{2xy \frac{\partial u}{\partial s}} + 2xy \frac{\partial u}{\partial t}$$

$$= 4xy \frac{\partial u}{\partial t} = 0 \quad \Leftrightarrow \quad \frac{\partial u}{\partial t} = 0.$$

Antsin är  $u(s,t) = \varphi(s)$ , för någon funktion  $\varphi$ .

$$u(0,y) = e^y = e^{\sqrt{y^2}} = \varphi(y^2)$$

$$u(x,y) = \varphi(x^2+y^2)$$

$$\text{Ants} \quad \varphi(s) = e^{\sqrt{s}} \quad \text{och} \quad u(x,y) = \varphi(x^2+y^2) = e^{\sqrt{x^2+y^2}}$$