

Definition: Låt $u = (u_1, u_2, u_3)$ vara ett C^1 -fält. Vi definierar **rotationen** av u som vektorfältet

$$\text{rot } u = \left(\frac{\partial u_3}{\partial x_2} - \frac{\partial u_2}{\partial x_3}, \frac{\partial u_1}{\partial x_3} - \frac{\partial u_3}{\partial x_1}, \frac{\partial u_2}{\partial x_1} - \frac{\partial u_1}{\partial x_2} \right).$$

Fältet u kallas **virvelfritt** om $\text{rot } u = 0$.

Notera att vi symboliskt kan se

$$\text{rot } u = \nabla \times u = \begin{vmatrix} e_1 & e_2 & e_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ u_1 & u_2 & u_3 \end{vmatrix} = \left(\frac{\partial u_3}{\partial x_2} - \frac{\partial u_2}{\partial x_3}, \frac{\partial u_1}{\partial x_3} - \frac{\partial u_3}{\partial x_1}, \frac{\partial u_2}{\partial x_1} - \frac{\partial u_1}{\partial x_2} \right)$$

Sats: (Stokes sats)

Låt $u = (u_1, u_2, u_3)$ vara ett C^1 -fält definierat i en öppen mängd $\Omega \subset \mathbb{R}^3$. Om Y är ett orienterat ytstykke i Ω med orienterad rand ∂Y så gäller att

$$\iint_{\partial Y} u \cdot d\mathbf{n} = \iint_Y (\text{rot } u) \cdot \mathbf{N} dS.$$

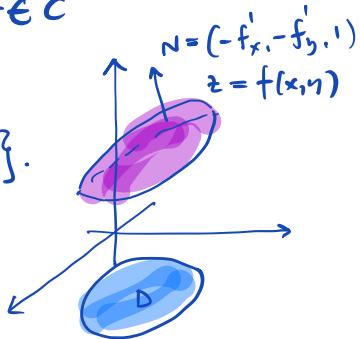
Anmärkning: Om Y är en plan yta i xy-planet och $u = (u_1, u_2, 0)$ så blir ovanstående

$$\iint_{\partial Y} u_1 dx + u_2 dy = \iint_Y \left(-\frac{\partial u_2}{\partial z}, \frac{\partial u_1}{\partial z}, \frac{\partial u_2}{\partial x} - \frac{\partial u_1}{\partial y} \right) \cdot (0, 0, 1) dx dy$$

$$= \iint_Y \left(\frac{\partial u_2}{\partial x} - \frac{\partial u_1}{\partial y} \right) dx dy \quad (\text{Greens formel}).$$

Beris: Ärterigen är en speciell fall, då Y är en funktionssyta $z = f(x, y)$, med $f \in C^2$

$$Y = \{(x, y, z) : z = f(x, y), (x, y) \in D\}.$$



$$\begin{aligned} \oint_{\partial Y} u \cdot d\mathbf{r} &= \int_{\partial D} u_1 dx + u_2 dy + u_3 dz \\ &= \int_{\partial D} u_1 dx + u_2 dy + u_3 \left(\frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy \right) \\ &= \int_{\partial D} \underbrace{(u_1 + u_3 \frac{\partial f}{\partial x})}_{P} dx + \underbrace{(u_2 + u_3 \frac{\partial f}{\partial y})}_{Q} dy \\ &\stackrel{\text{Greens formel}}{\downarrow} \\ &= \iint_D \left(\frac{\partial}{\partial x} (u_2 + u_3 \frac{\partial f}{\partial y}) - \frac{\partial}{\partial y} (u_1 + u_3 \frac{\partial f}{\partial x}) \right) dx dy \end{aligned}$$

Nära nu att $\frac{\partial}{\partial x}(u_2) = \frac{\partial u_2}{\partial x} + \frac{\partial u_2}{\partial z} \cdot \frac{\partial z}{\partial x}$ eftersom
 $u_2 = u_2(x, y, f(x, y))$

$$\begin{aligned} &= \iint_D \left(\frac{\partial u_2}{\partial x} + \frac{\partial u_2}{\partial z} \cdot \frac{\partial z}{\partial x} + \left(\frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial z} \cdot \frac{\partial z}{\partial x} \right) \left(\frac{\partial f}{\partial y} \right) + u_3 \frac{\partial^2 f}{\partial x \partial y} \right. \\ &\quad \left. - \frac{\partial u_1}{\partial y} - \frac{\partial u_1}{\partial z} \cdot \frac{\partial z}{\partial y} - \left(\frac{\partial u_3}{\partial y} + \frac{\partial u_3}{\partial z} \cdot \frac{\partial z}{\partial y} \right) \left(\frac{\partial f}{\partial x} \right) - u_3 \frac{\partial^2 f}{\partial x \partial y} \right) dx dy \end{aligned}$$

$$= \iint_D \left(\frac{\partial u_2}{\partial x} - \frac{\partial u_1}{\partial y} + \left(\frac{\partial f}{\partial x} \right) \left(\frac{\partial u_2}{\partial z} - \frac{\partial u_3}{\partial y} \right) + \left(\frac{\partial f}{\partial y} \right) \left(\frac{\partial u_3}{\partial x} - \frac{\partial u_1}{\partial z} \right) \right) dx dy$$

Normal till funktionsytan är $(-f'_x, -f'_y, 1)$.

$$\begin{aligned} &= \iint_D \left(\frac{\partial u_3}{\partial y} - \frac{\partial u_2}{\partial z}, \frac{\partial u_1}{\partial z} - \frac{\partial u_3}{\partial x}, \frac{\partial u_2}{\partial x} - \frac{\partial u_1}{\partial y} \right) \cdot (-f'_x, -f'_y, 1) dx dy \\ &= \iint_Y ((\text{rot } u) \cdot N) dS \quad \text{III} \end{aligned}$$

Ex: Beräkna $\int_{\gamma} (-y^3, x^3, -z^3) \cdot d\gamma$, där γ är skärmningen

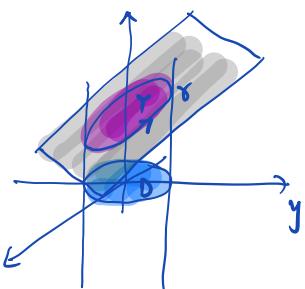
av cylindern $x^2+y^2=1$ och planet $2x+2y+z=3$ orienterad moturs (vid projektionen på xy -planet).

Lösning: $N dS = (2, 2, 1) dx dy$

$$I = \int_{\gamma} u \cdot d\gamma = \iint_Y (\text{rot } u) \cdot N dS$$

$$\text{rot } u = \begin{vmatrix} e_1 & e_2 & e_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y^3 & x^3 & -z^3 \end{vmatrix} = (0, 0, 3x^2 + 3y^2) \times$$

$$I = \iint_D (0, 0, 3x^2 + 3y^2) \cdot (2, 2, 1) dx dy = 3 \int_0^{2\pi} \int_0^1 r^3 dr dp = 3 \cdot 2\pi \frac{1}{4} = \frac{3\pi}{2}.$$

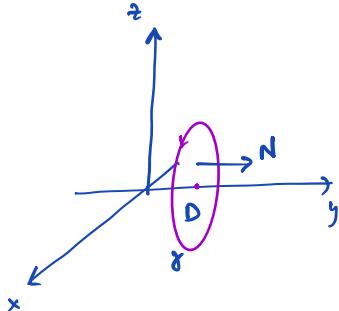


6. (4 poäng) Bestäm kurvintegralen av vektorfältet

$$\mathbf{F}(x, y, z) = (x^2 y^3, e^{xy-x+z}, x + z^2)$$

längs cirkeln $x^2 + z^2 = 1$ i planet $y = 1$, där cirkeln är orienterad medurs sedd från origo.

$$\begin{aligned} \text{rot } \mathbf{F} &= \begin{vmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 y^3 & e^{xy-x+z} & x + z^2 \end{vmatrix} = \\ &= \left(-e^{xy-x+z}, -1, (y-1)e^{xy-x+z} - 3x^2 y^2 \right) \end{aligned}$$

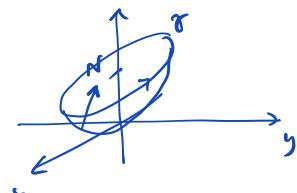


$$N dS = (0, 1, 0) dx dz$$

$$\int_S \mathbf{F} \cdot d\mathbf{r} = \iint_D (\text{rot } \mathbf{F}) \mathbf{N} dS = - \iint_D dx dz = -\pi.$$

8. (4 poäng) Ytan S består av den delen av paraboloiden $z = x^2 + 4y^2$ som ligger under planet $z = 1$ orienterad så att normalvektorn \mathbf{N} får positiv z -komponent. Bestäm flödet av vektorfältet $\nabla \times \mathbf{F}$ genom S där $\mathbf{F} = (y, -xz, xz^2)$.

$$\begin{aligned} \iint_S (\text{rot } \mathbf{F}) \mathbf{N} dS &= \int_S \mathbf{F} \cdot d\mathbf{r} \\ &= \int_0^{2\pi} \left(\frac{\sin \theta}{2}, -\cos \theta, \cos^2 \theta \right) \cdot \left(-\sin \theta, \frac{\cos \theta}{2}, 0 \right) d\theta \\ &= \int_0^{2\pi} \left(-\frac{\sin^2 \theta}{2} - \frac{\cos^2 \theta}{2} \right) d\theta = -\frac{1}{2} \int_0^{2\pi} d\theta = -\pi \end{aligned}$$



$$\begin{aligned} x &= \cos \theta \\ y &= \frac{\sin \theta}{2} \\ z &= 1 \end{aligned}$$

$$\begin{aligned} \mathbf{r}(\theta) &= \left(\cos \theta, \frac{\sin \theta}{2}, 1 \right) \\ \mathbf{r}'(\theta) &= \left(-\sin \theta, \frac{\cos \theta}{2}, 0 \right) \end{aligned}$$