

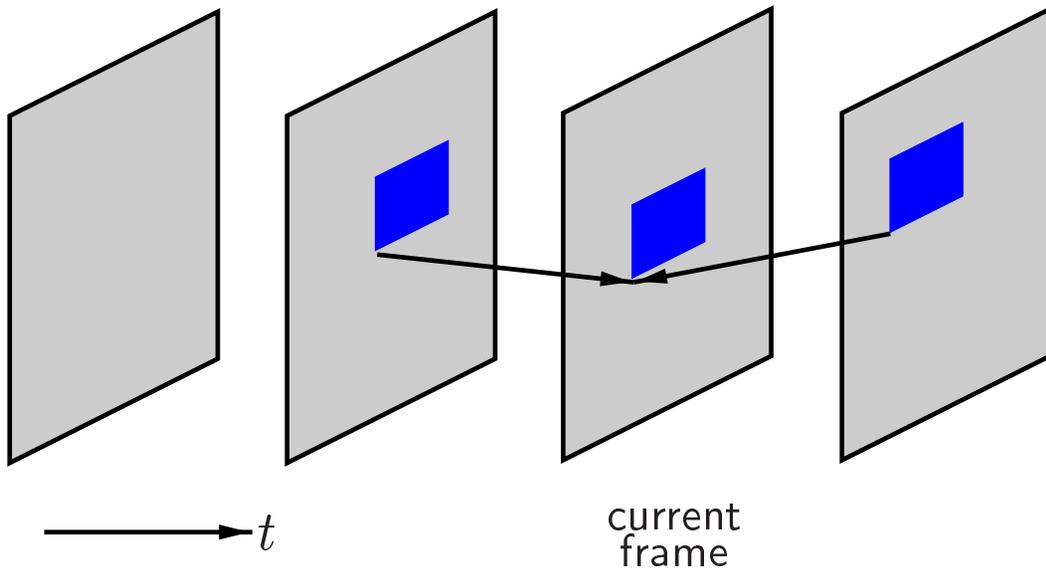
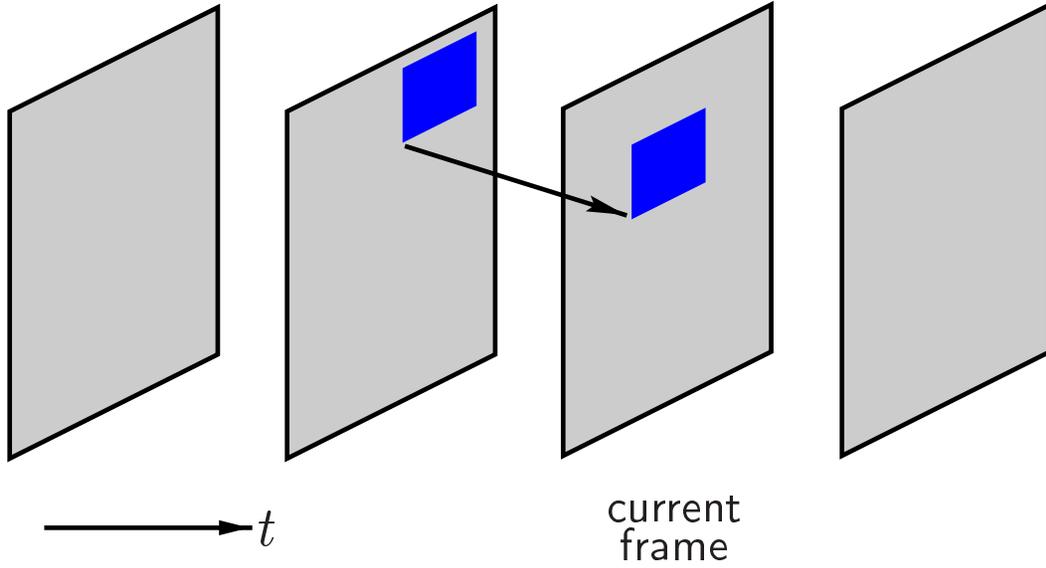
A Locally Optimal Design Algorithm for Block-Based Multi-Hypothesis Motion-Compensated Prediction

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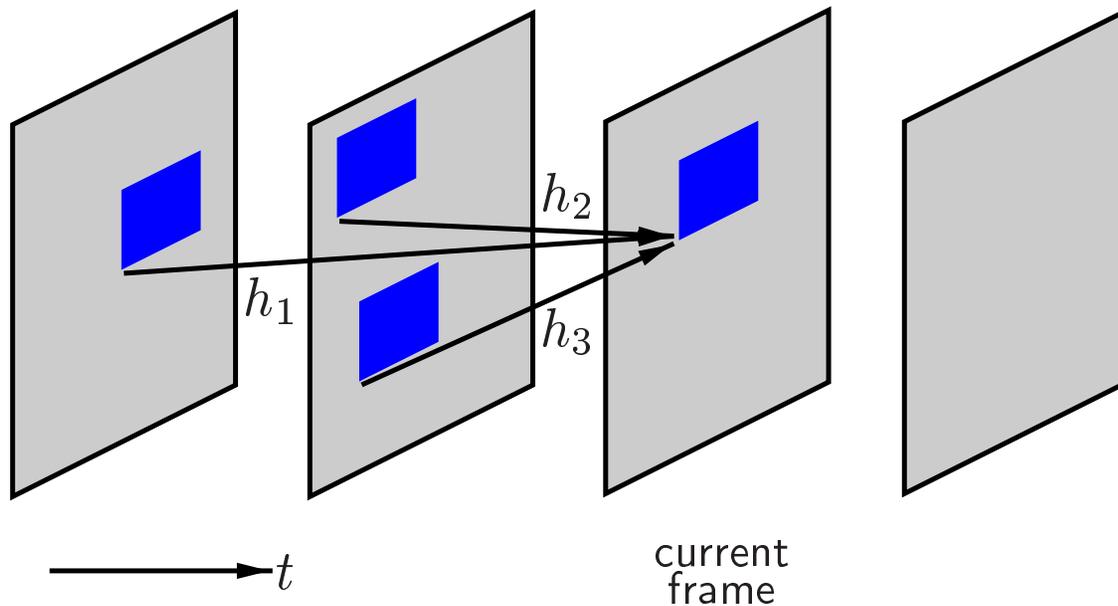
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Motivation



How about combining an arbitrary number of hypotheses?

Multi-Hypothesis Motion-Compensated Prediction



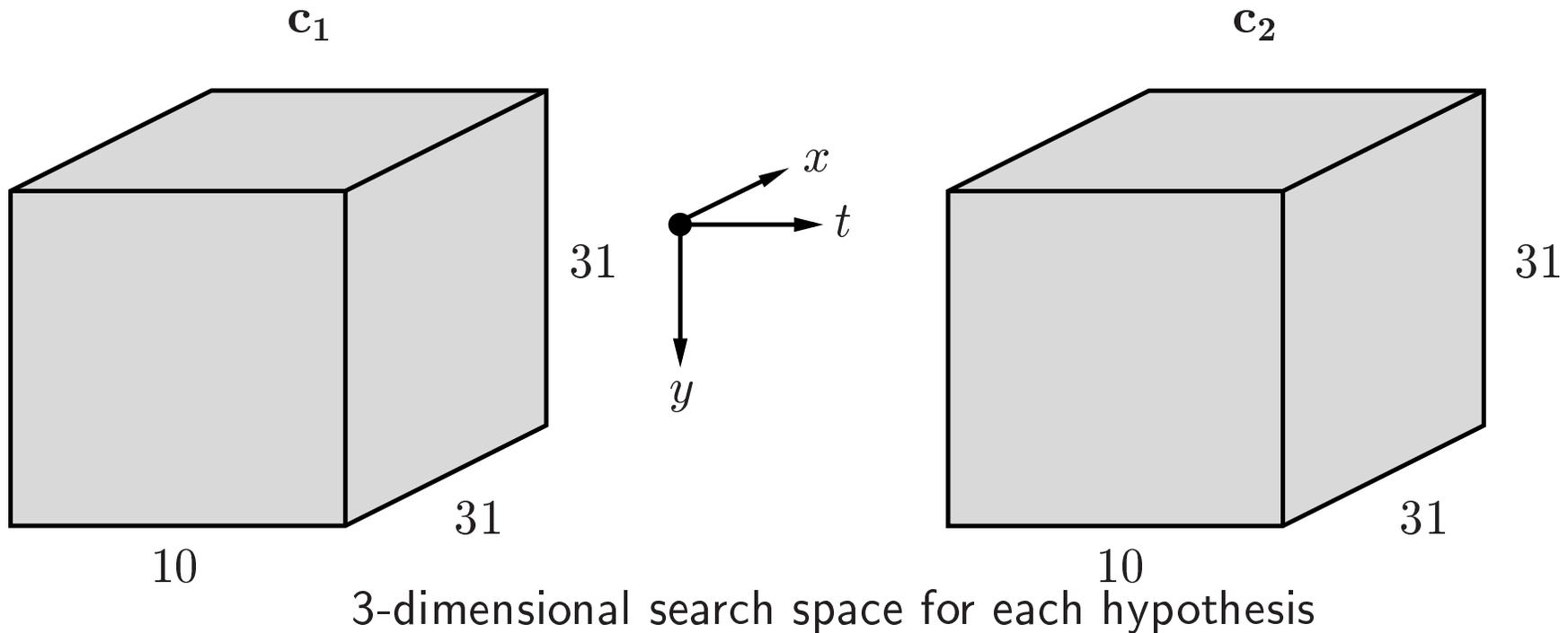
Each hypothesis c_ν is assigned a relative spatio-temporal displacement $(\Delta x_\nu, \Delta y_\nu, \Delta t_\nu)$ and is weighted by a constant scalar h_ν .

Hypotheses are selected only from previous frames!

Multi-hypothesis: Array of hypotheses

How to Select an Optimal Multi-Hypothesis?

Example: 2-Hypothesis



Full search for a n -hypothesis:

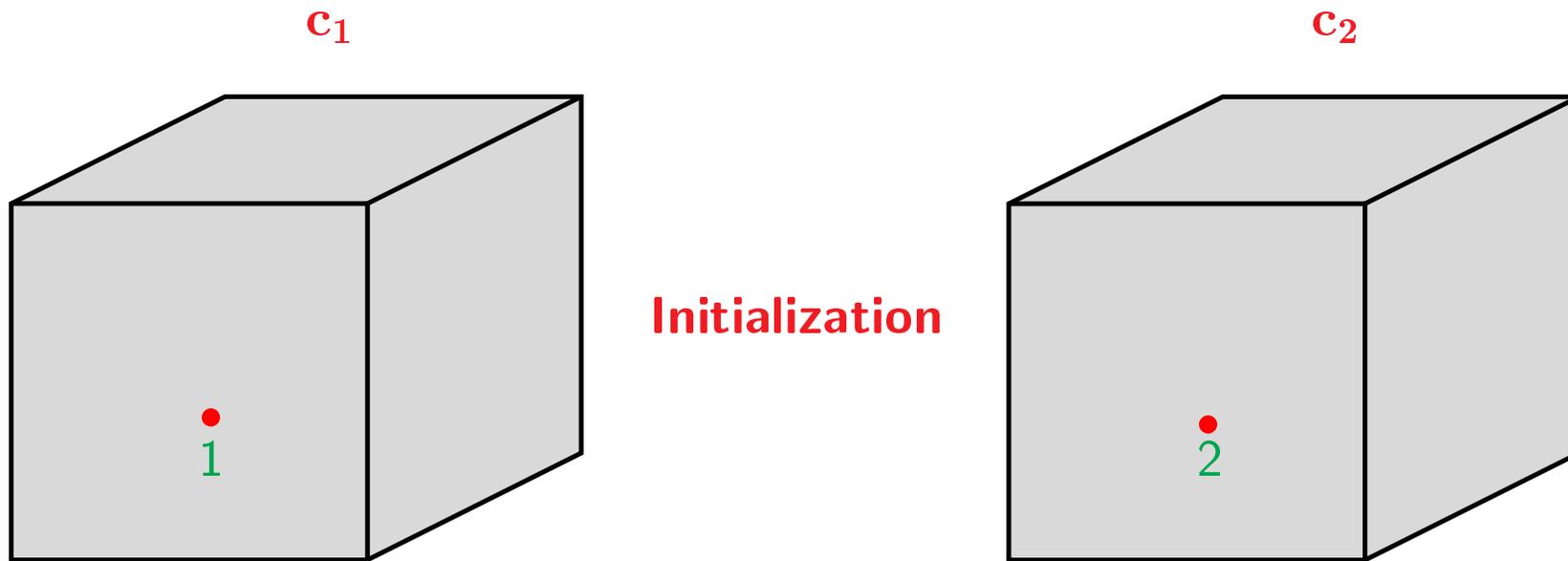
Complexity $\sim (\cdot)^n$

Too demanding!!

↪ Successive improvement of n optimal conditional solutions.

Hypothesis Selection Algorithm I

An iterative algorithm, which is inspired by the *Iterated Conditional Modes*.

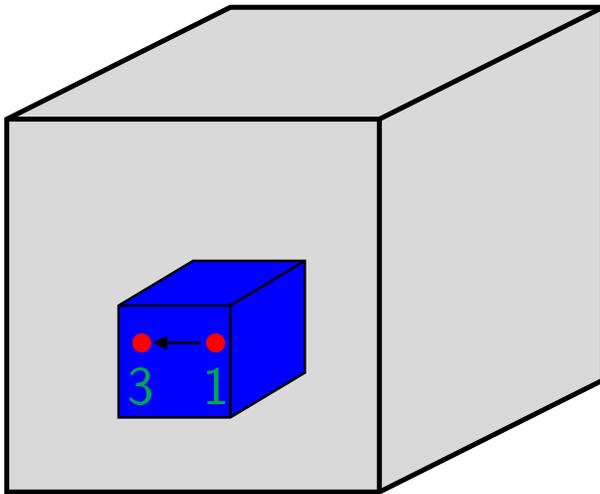


- ⇒ Find the optimal 1-hypothesis in search space.
- ⇒ Repeat the optimal 1-hypothesis n times to generate the initial n -hypothesis.

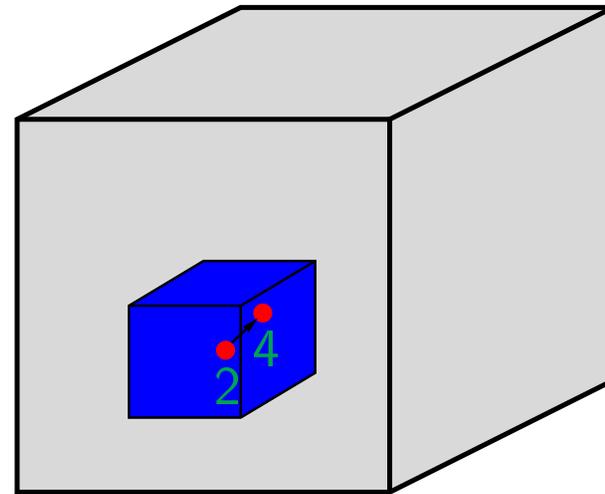
Hypothesis Selection Algorithm II

3-dimensional conditional search space: $[-b, b] \times [-b, b] \times [-b, b]$

\mathbf{c}_1



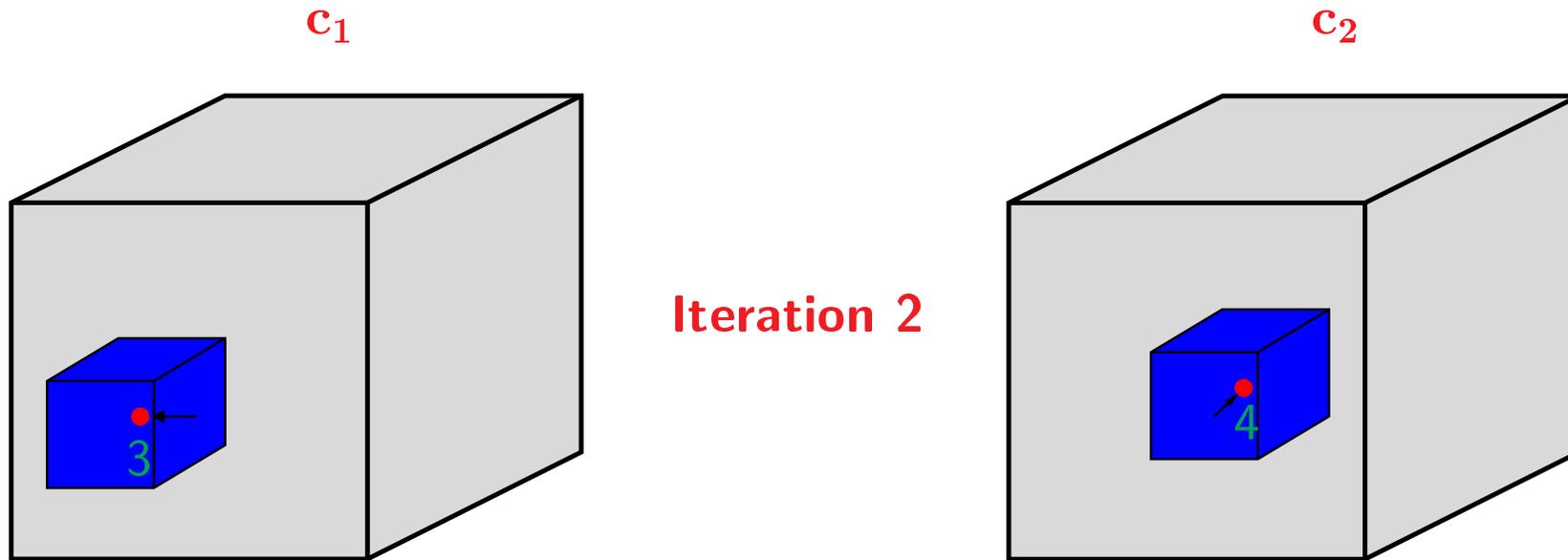
\mathbf{c}_2



Iteration 1

- \Rightarrow 1 and 2 are centers of the conditional search spaces.
- \Rightarrow Hypothesis \mathbf{c}_2 is fixed. Optimize hypothesis \mathbf{c}_1 by full search within its conditional search space (3).
- \Rightarrow Hypothesis \mathbf{c}_1 is fixed. Optimize hypothesis \mathbf{c}_2 by full search within its conditional search space (4).

Hypothesis Selection Algorithm III

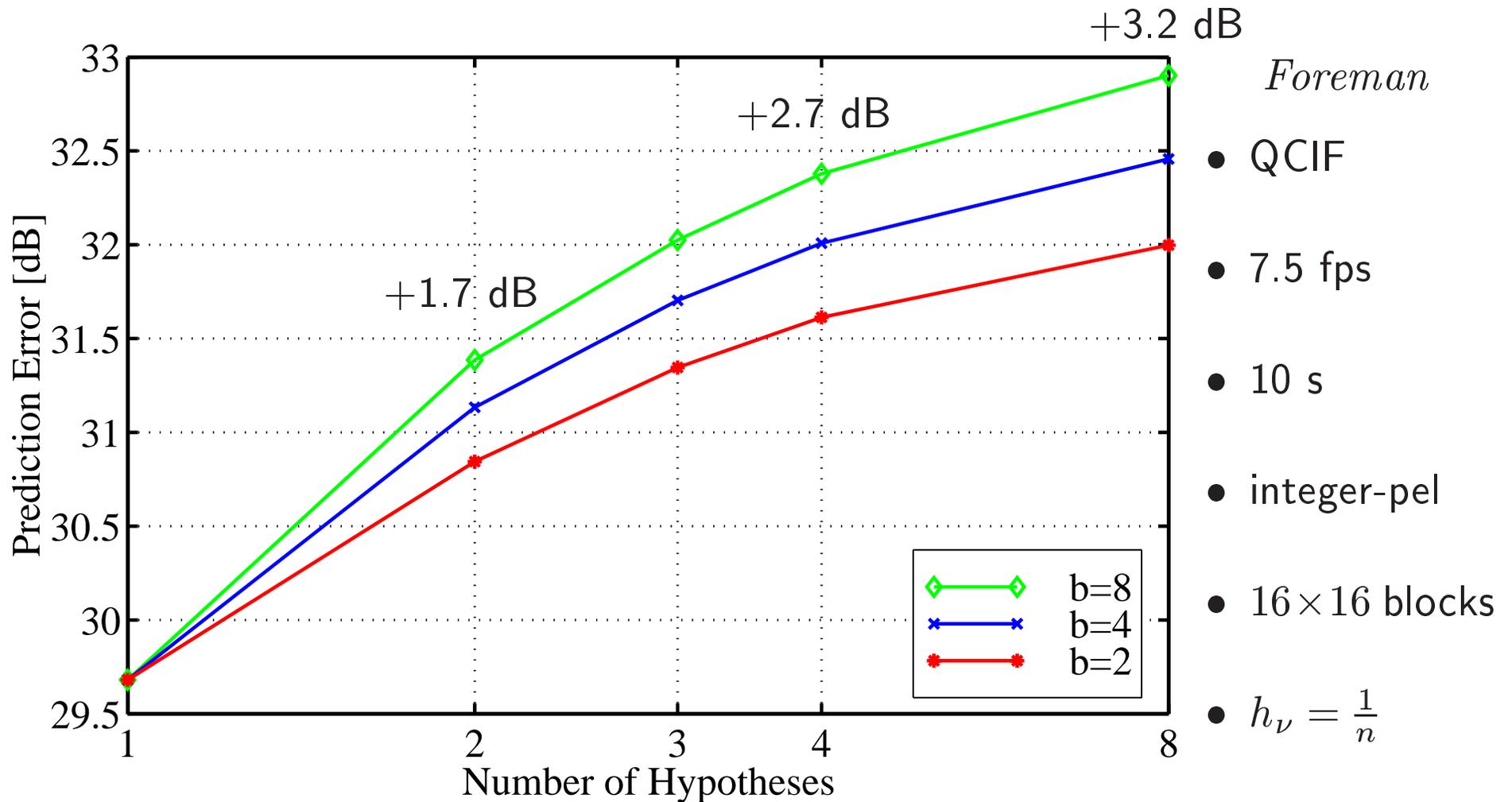


⇒ 3 and 4 are centers of the conditional search spaces.

⇒ ...

Continue until convergence.

Hypothesis Selection Algorithm IV



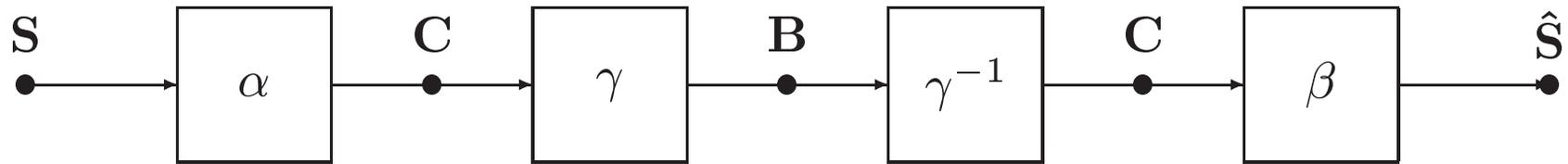
Trade-off between complexity and prediction gain

Rate-Constrained Multi-Hypothesis MCP

- ⇒ Multi-hypothesis MCP quantizes the original blocks and generates a multi-hypothesis code.
- ⇒ Improved prediction performance and higher data rate due to more than one hypothesis per block

↪ **Rate-constrained vector quantization for modeling multi-hypothesis MCP**

Predictor Model



α : Multi-hypothesis search
 β : Weighted superposition
 γ : Entropy code

The optimal predictor $\{\alpha^*, \beta^*, \gamma^*\}$ minimizes the average rate-distortion measure

$$J(\alpha, \beta, \gamma, \lambda, \mathbf{S}) = E \left\{ \|\mathbf{S} - \beta \circ \alpha(\mathbf{S})\|_2^2 + \lambda |\gamma \circ \alpha(\mathbf{S})| \right\}$$

for given distribution of the original blocks \mathbf{S}_c and constant Lagrange multiplier λ_c .

$$\min_{\alpha, \beta, \gamma} J(\alpha, \beta, \gamma, \lambda_c, \mathbf{S}_c).$$

Iterative Design Algorithm

1: Given: Entropy code γ and predictor coefficients h

$$\min_{\mathbf{c}} \left\{ \|\mathbf{s} - \mathbf{c}h\|_2^2 + \lambda |\gamma(\mathbf{c})| \right\} \quad \text{Optimal multi-hypothesis } \mathbf{c} \text{ for each original block } \mathbf{s}$$

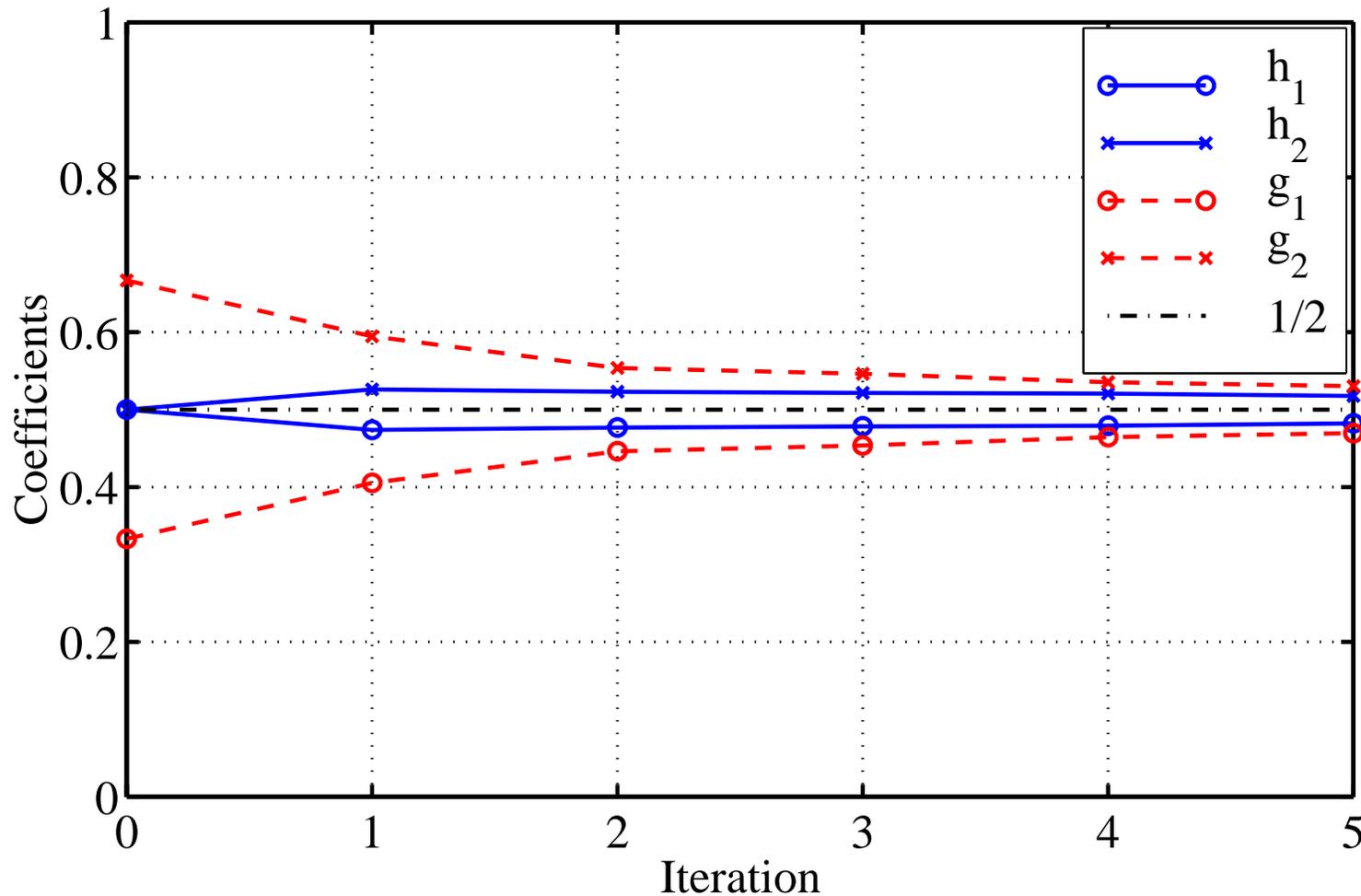
2: Given: New distribution of multi-hypotheses \mathbf{C} from Step 1

$$\min_{\gamma} E \{ |\gamma(\mathbf{C})| \} \quad \text{Optimal entropy code } \gamma$$

3: Given: Multi-hypotheses \mathbf{C} from Step 1

$$\min_h E \left\{ \|\mathbf{S} - \mathbf{C}h\|_2^2 \right\} \quad \text{Optimal predictor coefficients } h$$

Optimal Predictor Coefficients



18 Sequences

● QCIF

● 7.5 fps

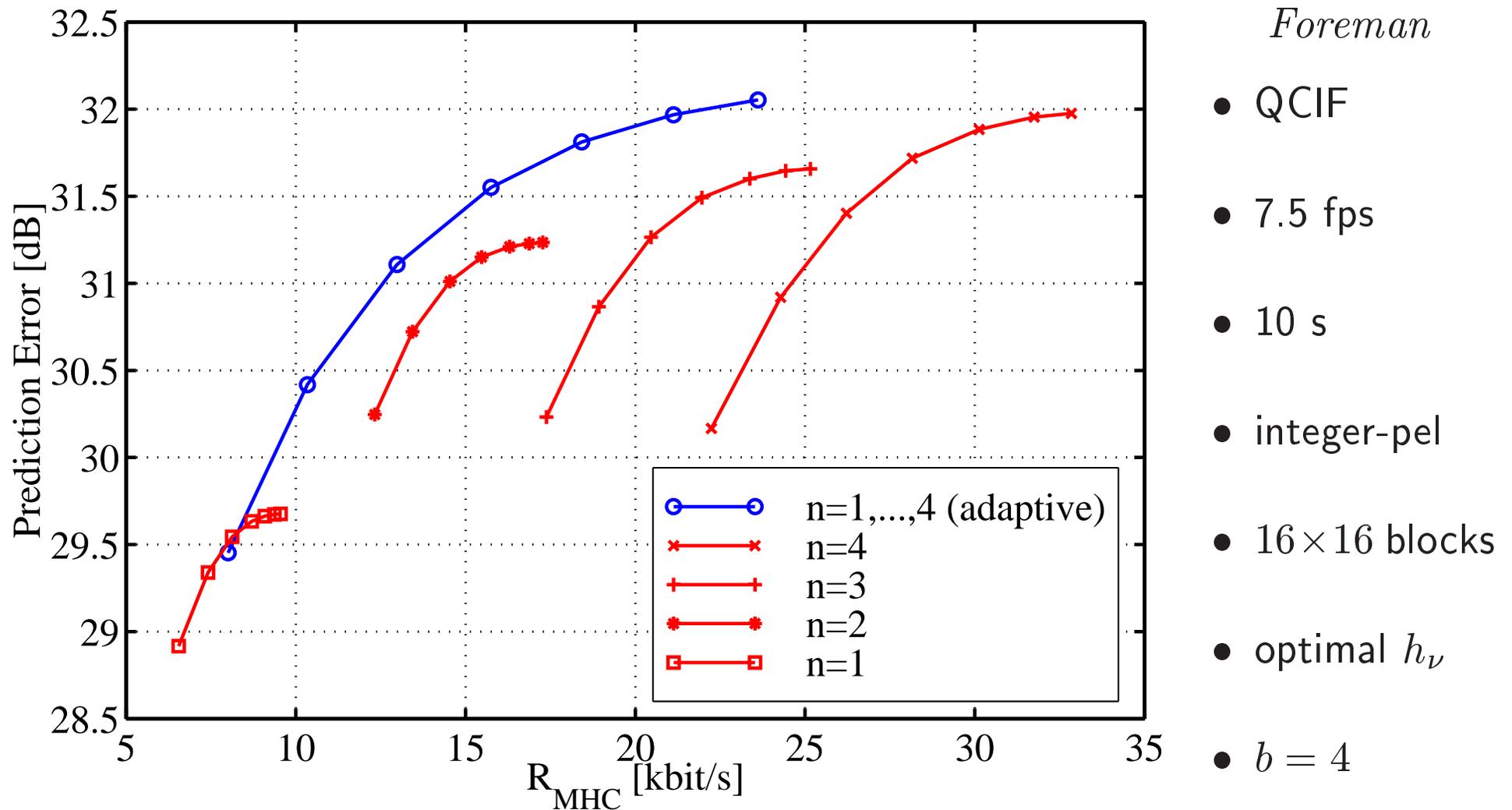
● 10 s

● integer-pel

● 16×16 blocks

For our parameters, the optimum predictor coefficients are approximately $\frac{1}{n}$ for n linear combined hypotheses.

Optimal Number of Hypotheses



Dependent on the rate constraint,
each block has its individual number of hypotheses.

Conclusions

- ⇒ Multi-hypothesis prediction increases prediction gain.
- ⇒ The hypothesis selection algorithm reduces the complexity of the underlying joint optimization problem to a feasible size.
- ⇒ We observed that the optimum predictor coefficients are approximately $\frac{1}{n}$ for n linear combined hypotheses.
- ⇒ Dependent on the rate constraint, each block has its individual number of hypotheses.