

Explicit solitary-wave ground states in one dimension

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2004-05-14

Abstract

We give explicit solutions, that decay to zero at infinity, to the class of equations

$$-\partial_x^2 Q + cQ - \beta Q^{2p+1} - \alpha Q^{p+1} = 0,$$

where $c > 0$, $\beta > 0$, $p > 0$ and $\alpha \in \mathbb{R}$. This class of equations appears as the equation for the ground state for a solitary wave in the generalized nonlinear Schrödinger equation in one dimension and in the generalized KdV equation.

Keywords: explicit solutions, solitons, solitary waves, ground state, nonlinear scalar field equations.

1 Explicit solutions

Consider the class of one dimensional equations

$$-\partial_x^2 Q + cQ - Q^{2p+1} - \alpha Q^{p+1} = 0, \quad (1)$$

with $p > 0$, $c > 0$, $\alpha \in \mathbb{R}$. See Remark 2 for the general case. These equations belong to the class of nonlinear scalar field equations see *e.g.*, Berestycki & Lions (1983) [1] and references therein. Applications include the ground state to the nonlinear Schrödinger equation see *e.g.*, Chaio *et al.* (1964) [2] and to the Korteweg–de Vries (1894) [3] equation. We have the following lemma:

Proposition 1. *For fixed $p > 0$, $c > 0$ and $\alpha \in \mathbb{R}$ the equation (1) has solutions that decay to zero as $|x| \rightarrow \infty$ of the form*

$$Q(x) = \left(\frac{\alpha}{c(2+p)} + \sqrt{\frac{1}{c(1+p)} + \frac{\alpha^2}{c^2(2+p)^2} \cosh(p\sqrt{c}(x-x_0))} \right)^{-1/p}, \quad (2)$$

for any translation constant $x_0 \in \mathbb{R}$.

Proof. Equation (1) is translational invariant, and hence it suffice to consider the case $x_0 = 0$. To verify that (2) is a solution to (1) we substitute it into (1). First consider the term $\partial_x^2 Q$. We have

$$\partial_x Q(x) = -\sqrt{\frac{1}{1+p} + \frac{\alpha^2}{c(2+p)^2}} \sinh(p\sqrt{cx}) Q^{p+1}(x), \quad (3)$$

and hence

$$\begin{aligned} -\partial_x^2 Q(x) &= p\sqrt{c} \sqrt{\frac{1}{1+p} + \frac{\alpha^2}{c(2+p)^2}} \cosh(p\sqrt{cx}) Q^{p+1}(x) \\ &\quad - \left(1 + \frac{\alpha^2(p+1)}{c(2+p)^2}\right) \sinh^2(p\sqrt{cx}) Q^{2p+1}(x). \end{aligned} \quad (4)$$

To the end of comparing $\partial_x^2 Q$ with the remaining terms in (1) we break out Q^{2p+1} and use the explicit form of Q^p to obtain

$$\begin{aligned} -\partial_x^2 Q(x) &= Q^{2p+1}(x) \left(\left(\frac{\alpha}{c(2+p)} + \sqrt{\frac{1}{c(1+p)} + \frac{\alpha^2}{c^2(2+p)^2}} \cosh(p\sqrt{cx}) \right) \right. \\ &\quad \left. p\sqrt{c} \sqrt{\frac{1}{1+p} + \frac{\alpha^2}{c(2+p)^2}} \cosh(p\sqrt{cx}) - \left(1 + \frac{\alpha^2(p+1)}{c(2+p)^2}\right) \sinh^2(p\sqrt{cx}) \right). \end{aligned} \quad (5)$$

Recalling that $\cosh^2(y) - \sinh^2(y) = 1$ and collecting equal powers of $\cosh(\cdot)$ together, gives

$$\begin{aligned} -\partial_x^2 Q(x) &= Q^{2p+1}(x) \left(\frac{\alpha p}{\sqrt{c}(2+p)} \sqrt{\frac{1}{1+p} + \frac{\alpha^2}{c(2+p)^2}} \cosh(p\sqrt{cx}) \right. \\ &\quad \left. - \left(\frac{1}{1+p} + \frac{\alpha^2}{c(2+p)^2} \right) \cosh^2(p\sqrt{cx}) + 1 + \frac{\alpha^2(p+1)}{c(2+p)^2} \right). \end{aligned} \quad (6)$$

Re-writing the remaining terms of (1) using the explicit form of Q^p yields

$$\begin{aligned} cQ(x) - Q^{2p+1}(x) - \alpha Q^{p+1}(x) &= Q^{2p+1}(x) \cdot \\ &\quad \left(-1 + c \left(\frac{\alpha}{c(2+p)} + \sqrt{\frac{1}{c(1+p)} + \frac{\alpha^2}{c^2(2+p)^2}} \cosh(p\sqrt{cx}) \right)^2 \right. \\ &\quad \left. - \alpha \left(\frac{\alpha}{c(2+p)} + \sqrt{\frac{1}{c(1+p)} + \frac{\alpha^2}{c^2(2+p)^2}} \cosh(p\sqrt{cx}) \right) \right). \end{aligned} \quad (7)$$

Expanding the square and collecting terms of equal powers in $\cosh(\cdot)$, we find

$$cQ(x) - Q^{2p+1}(x) - \alpha Q^{p+1}(x) = Q^{2p+1}(x) \left(\left(\frac{1}{1+p} + \frac{\alpha^2}{c(2+p)^2} \right) \cosh^2(p\sqrt{c}x) - \frac{p\alpha}{\sqrt{c}(2+p)} \sqrt{\frac{1}{1+p} + \frac{\alpha^2}{c(2+p)^2}} \cosh(p\sqrt{c}x) - 1 - \frac{\alpha^2(1+p)}{c(2+p)^2} \right). \quad (8)$$

Since (6) is minus (8), summing them yields zero. \square

Remark 1. For $\alpha = 0$ we recover the well known solution, see von Sz.-Nagy (1941) [4], Titchmarsh (1946) [5]

$$Q(x) = (c(1+p))^{1/2p} \operatorname{sech}^{1/p}(p\sqrt{c}(x+m)). \quad (9)$$

Remark 2. The class of equations

$$-\partial_x^2 Q + cQ - \beta Q^{2p+1} - \alpha Q^{p+1} = 0, \quad (10)$$

with $\beta > 0$, $c > 0$, and $\alpha \in \mathbb{R}$ have solutions, that decay to zero as $|x| \rightarrow \infty$, of the form

$$Q(x) = \left(\frac{\alpha}{c(2+p)} + \sqrt{\frac{\beta}{c(1+p)} + \frac{\alpha^2}{c^2(2+p)^2}} \cosh(p\sqrt{c}(x-x_0)) \right)^{-1/p}, \quad (11)$$

for any translation constant x_0 . This result follows directly from Proposition 1 as the rescaling transformation $\{\alpha, c, x - x_0\} \mapsto \{\alpha\beta, c\beta, (x - x_0)\beta^{-1/2}\}$ maps (10) to (1). Furthermore, in the limit $\beta \rightarrow 0$, $\alpha > 0$, using the ‘half-angle formula’ for $\cosh(\cdot)$ we once again recover the solution (9), with $p \mapsto p/2$.

Remark 3. For the nonlinear eigenvalue parameter, c , the solution is a one bump solution for all positive values of c . Thus there are no excited states.

Remark 4. Consider the decaying-to-zero at infinity solutions to the class of equations

$$-\partial_x^2 Q + cQ - \sum_{j \in I} a_j Q^{p_j} = 0, \quad (12)$$

for constants $\{a_j, p_j\}_{j \in I}$, with $a_j \in \mathbb{R}$ and $p_j > 0$ where $I \subset \mathbb{Z}$. That equation (12) is translational invariant suggest the change of variable $v = \partial_x Q$, $\partial_x v = \partial_Q v \partial_x Q = v \partial_Q v$. Replace $\partial_x^2 Q$ in terms of v yields a separable equation, integration gives

$$2^{-1}v^2 = \int cQ - \sum_{j \in I} a_j Q^{p_j} dQ = 2^{-1}cQ^2 - \sum_{j \in I} (p_j + 1)^{-2} a_j Q^{p_j+1} + k, \quad (13)$$

for some constant k . For functions that decay at infinity both Q and $v = \partial_x Q$ are zero at infinity, thus $k = 0$. When the solution, Q , exists and is smooth, the critical points of Q are at $\partial_x Q = 0$ and (13) gives the explicit value of Q at these points as the solution to the polynomial equation

$$2^{-1}cQ^2 = \sum_{j \in I} (p_j + 1)^{-2} a_j Q^{p_j+1}. \quad (14)$$

This has applications as the starting point for a shooting algorithm, when numerically solving (13).

References

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