

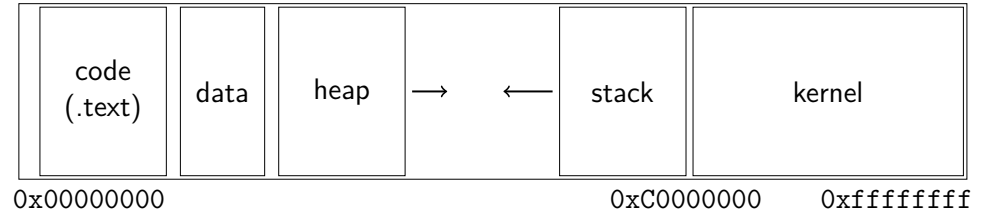
The process

Memory

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KTH

2020



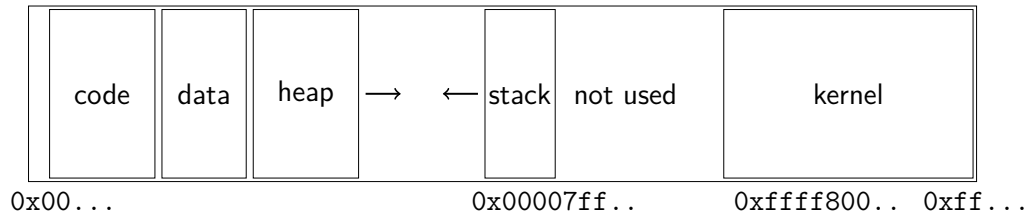
Memory layout for a 32-bit Linux process

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64-bit Linux on a x86_64 architecture

Memory virtualization



Every process has an address space from zero to some maximal address.

A program contains instructions that of course rely on that code and data can be found at expected addresses.

We only have one physical memory.



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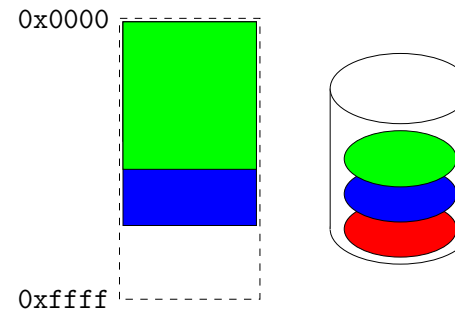


IBM System 360

- 1964, 8-64 Kbyte memory
- 12+12 bit address space
- batch operating system

Chief architect: Gene Amdahl

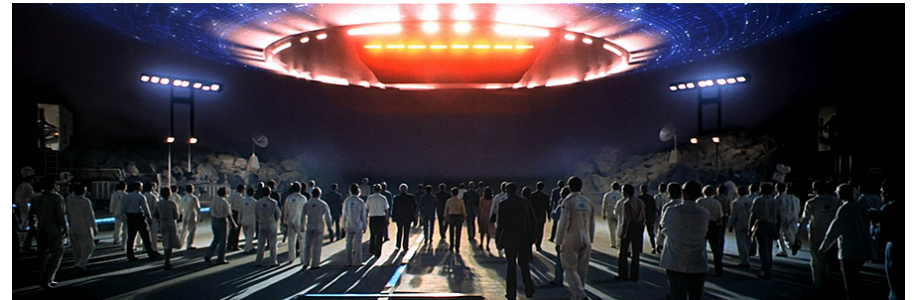
Batch processing:



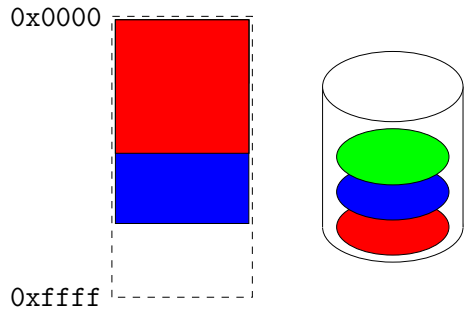
GE-235

- 1964
- 20-bit word
- 8 Kword address space

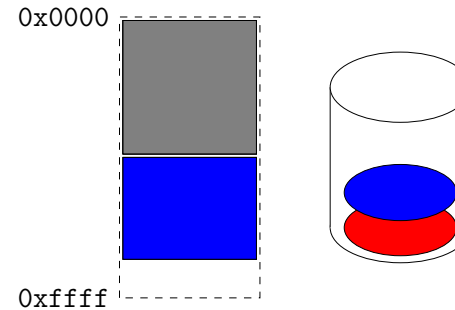
Arnold Spielberg was in the team that designed the GE-235



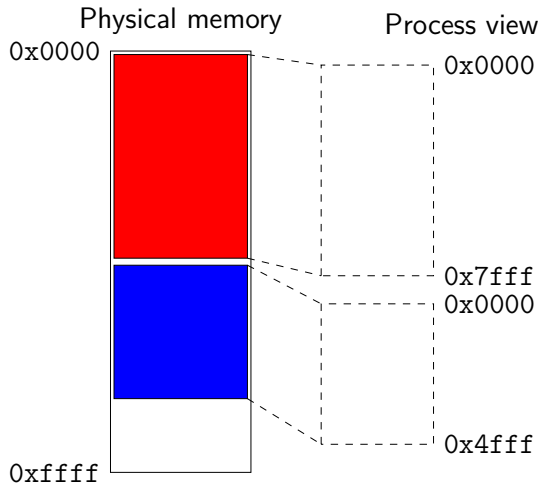
Time-sharing:



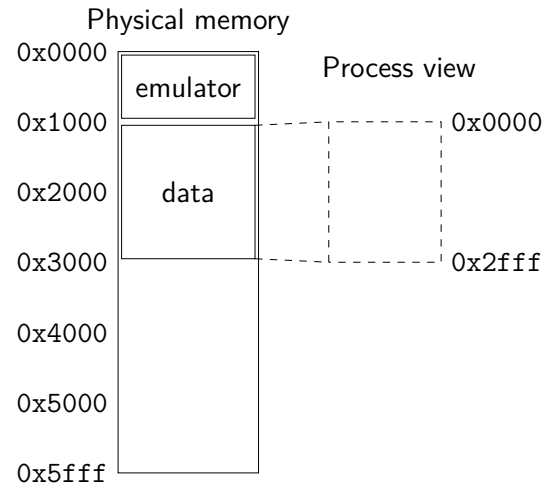
If both programs will fit in memory:



What is the problem?



- Transparent: processes should be unaware of virtualization.
- Protection: processes should not be able to interfere with each other.
- Efficiency: execution should be as close to real execution as possible.

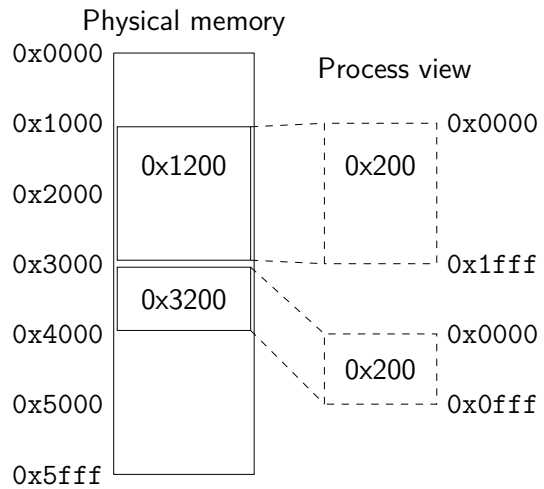


Let the operating system run an *emulator* that interprets the operations of the process and changes the memory addresses as needed.

This is similar to how the JVM works

Static relocation - eh, static

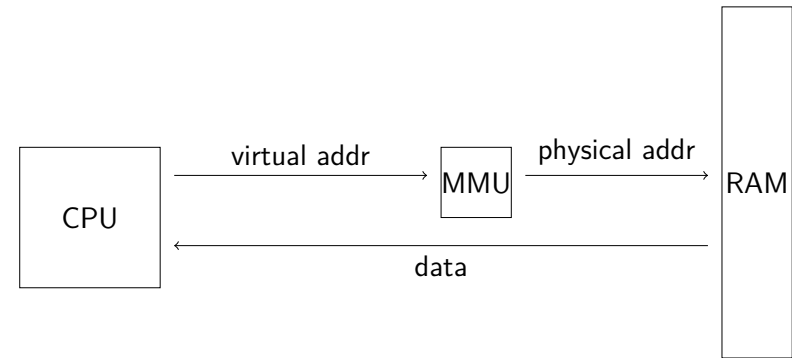
Dynamic relocation



When a program is loaded, all references to memory locations are changed so that they correspond to the actual location in RAM where the program is loaded.

How do we know we have changed all addresses?

Change every memory reference, on the fly, to a region in memory allocated for the process.

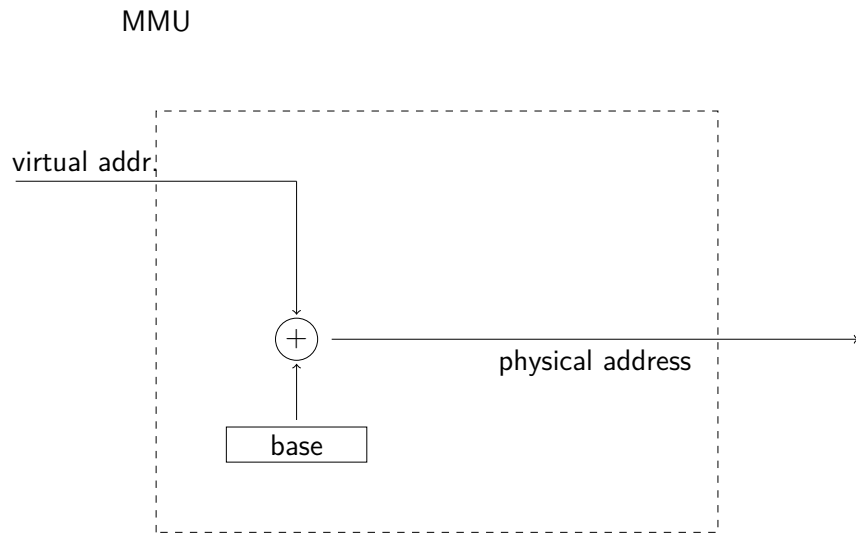


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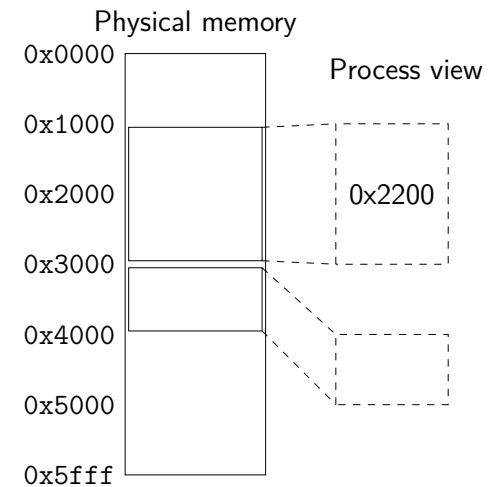
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Base register

Base problem



- Who is allowed to change the base register?
- How do we prevent one process from overwriting another process?

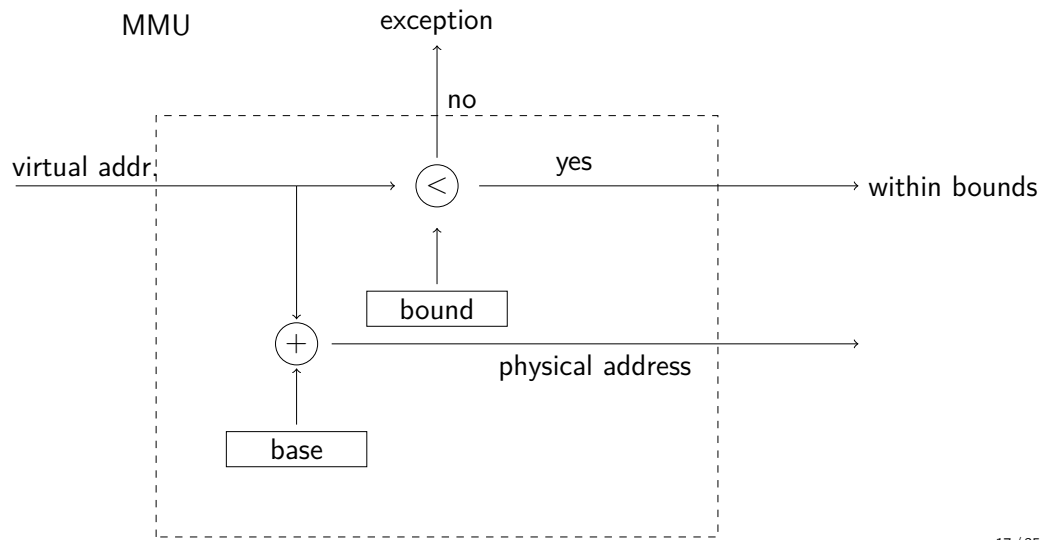


Can we prevent this at compile or load time?

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Base and bound



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Base and bound

Pros:

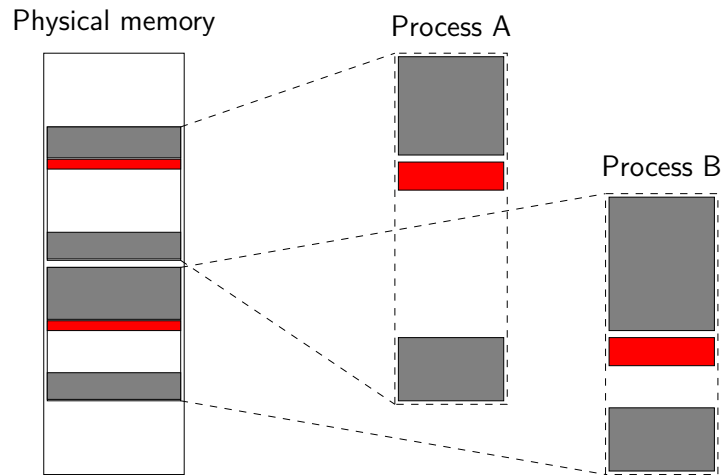
- Transparent to a process.
- Simple to implement.
- Easy to change process.

Cons:

- How do we share data?
- Wasted memory.

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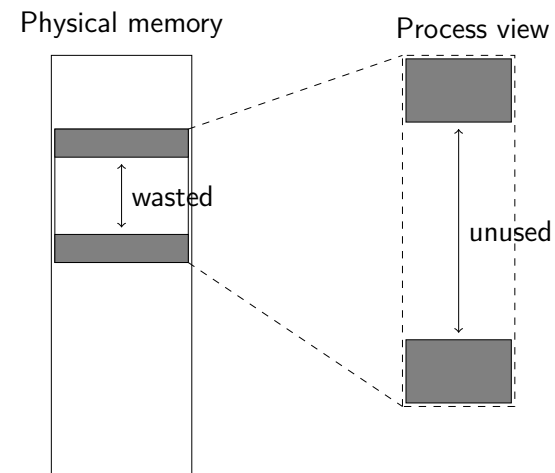
shared read-only segments



How do we write code that can be shared?

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Internal fragmentation



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- 1961
- Designed for high-level languages: ALGOL-60
- Memory access through a set of segment *descriptors* i.e. the view of a process is not a consecutive memory rather a set of individual memory segments.

Donald Knuth was part of the design team.

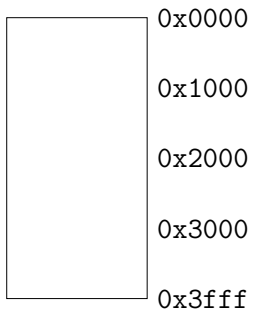
```

procedure Absmax(a) Size:(n, m) Result:(y) Subscripts:(i, k);
    value n, m; array a; integer n, m, i, k; real y;

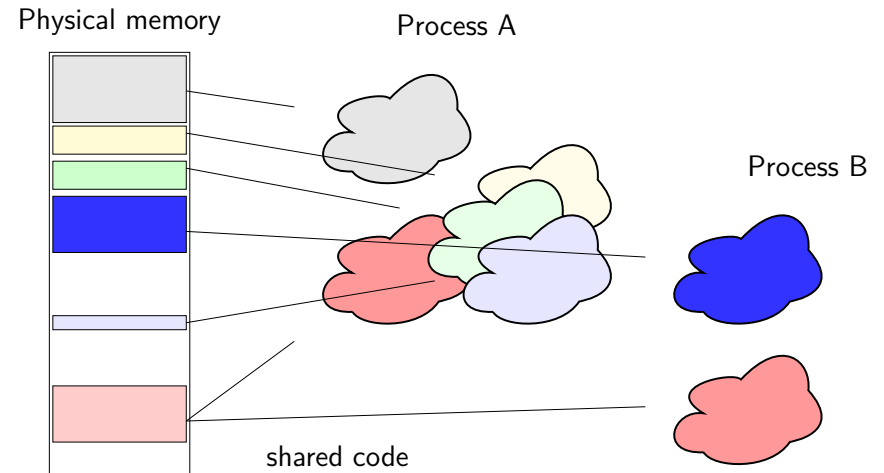
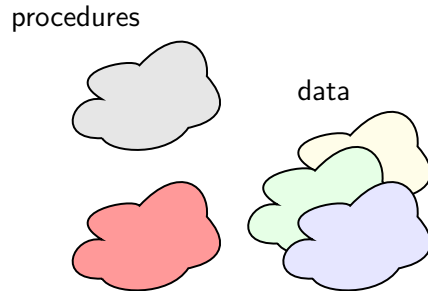
comment The absolute greatest element of the matrix a ...

begin
    integer p, q;
    y := 0; i := k := 1;
    for p := 1 step 1 until n do
        for q := 1 step 1 until m do
            if abs(a[p, q]) > y then
                begin y := abs(a[p, q]);
                    i := p; k := q
                end
            end
        end
    end Absmax
    
```

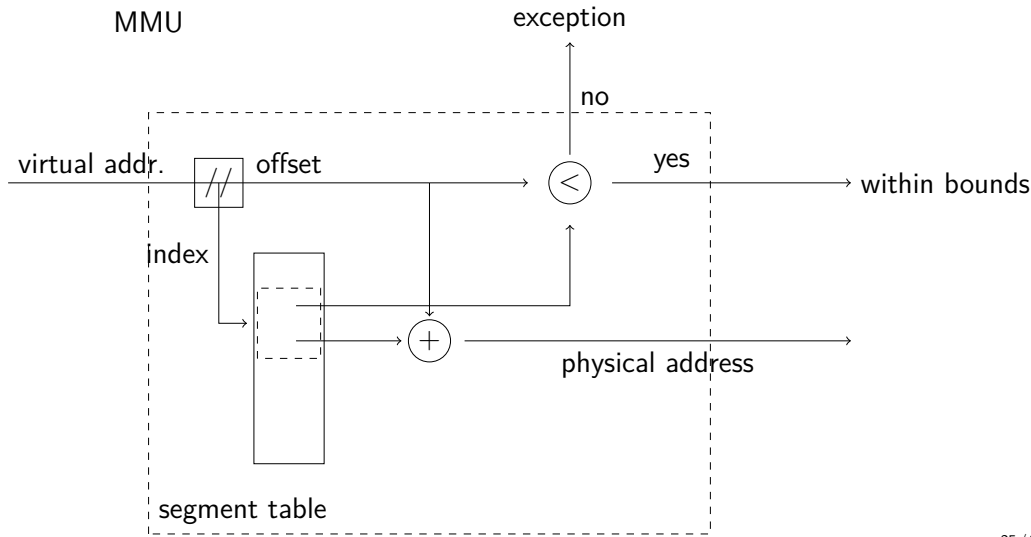
The view of the assembler programmer.



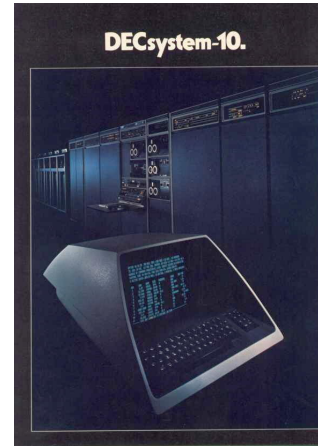
The view of the ALGOL programmer.



Segmented MMU



DECsystem10

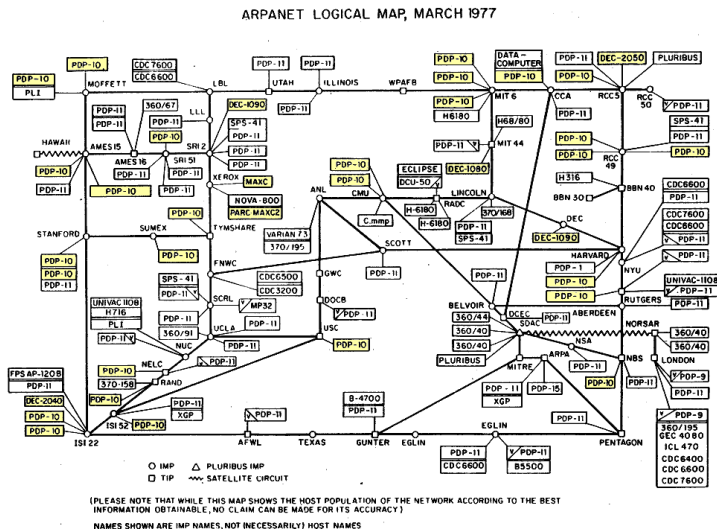


PDP-10

- 1966, 1 MHz
- 36 bit words
- 16 bit process address space (64Kword)
- 18 bit physical address (256 Kword)
- base and bound

The PDP10 had two segments per process, one read only code segment and one read/write for data.

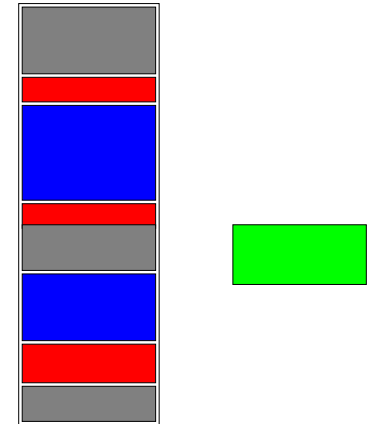
ARPANET 1977



(PLEASE NOTE THAT WHILE THIS MAP SHOWS THE MOST POPULATION OF THE NETWORK ACCORDING TO THE BEST INFORMATION OBTAINABLE, NO CLAIM CAN BE MADE FOR ITS ACCURACY.)
 NAMES SHOWN ARE IMP NAMES, NOT NECESSARILY HOST NAMES

Segmentation: the solution - not

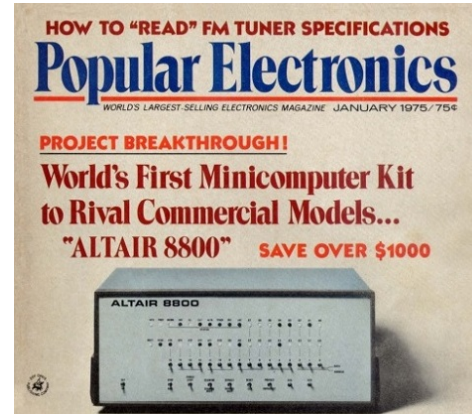
- Segments have variable size.
- Reclaiming segments will cause holes (external fragmentation).
- Compaction needed.



Is it possible to do compaction?

Using few large segments is easier to implement.

Using many small segments would allow the compiler and operating system to do a better job.



Intel 8080

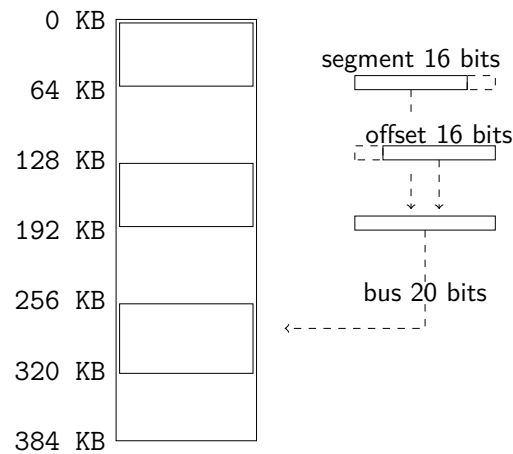
- 1972
- 2 MHz
- 16 bit address space (64 Kbyte)

Altair 8800 would have 4 or 8 Kbytes of memory.

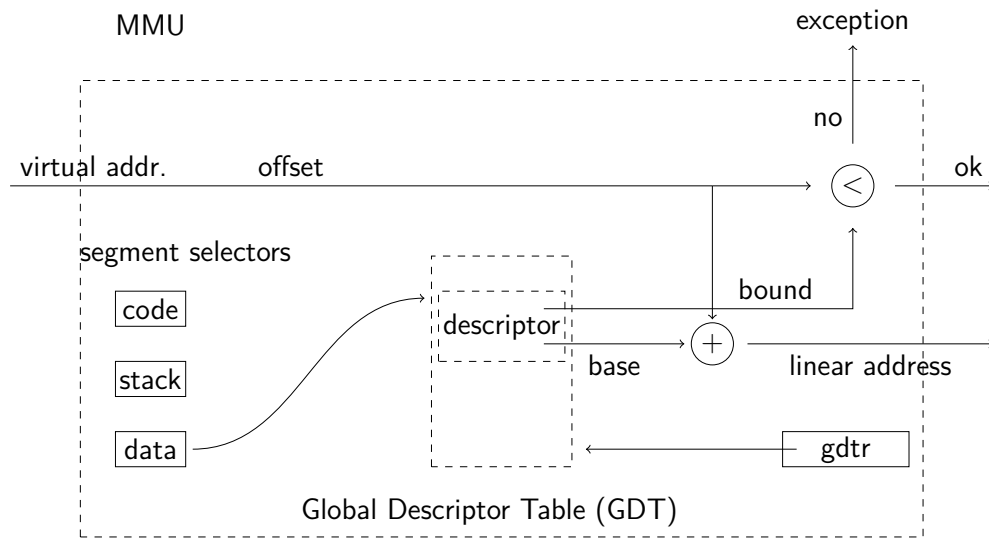


Intel 8086

- 1978, 5 MHz
- 16 bit address space (64 Kbyte)
- 20 bit memory bus (1 Mbyte)
- no protection of segments
- segments for: code, data, stack, extra



- Segment register chosen based on instruction: *code segment, stack segment, data segment* (and the *extra segment*).
- The segment architecture available still today in *real mode* i.e. the 16-bit mode that the CPU is initially in.



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- The segments descriptors of code, data and stack all have base address set to 0x0 and limit to 0xffffffff i.e. they all refer to the same 4 Gbyte linear address space.
- In x86_64 long mode (64 bit mode) Intel removed some support for segments and enforce that these segments are set to 0x0 and 0xff..ff.
- Segmentation is still used to refer to memory that belongs to a *specific core* or to *thread specific memory*.

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Summary

Virtual address space: provide a process with a view of a private address space.

- Transparent: processes should be unaware of virtualization.
- Protection: processes should not be able to interfere with each other.
- Efficiency: execution should be as close to real execution as possible.
- Emulator - too slow.
- Static relocation - not flexible.
- Dynamic relocation:
 - base and bound - simple to implement
 - segmentation - more flexible
 - problems: fragmentation, sharing of code

Cliffhanger - paging, the solution.

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