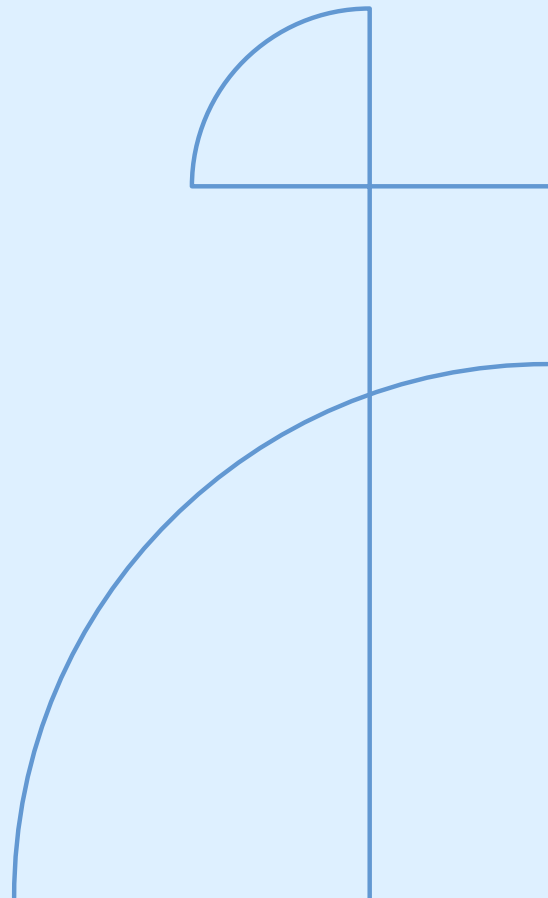




# Morse theory of distance functions between algebraic hypersurfaces

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## Summary

- We (re)develop **Morse theory for distance functions** between subsets of  $\mathbf{R}^n$ .
- We establish that the **nondegeneracy** of distance functions between algebraic hypersurfaces is **generic**.
- We also compute bounds for the number of **critical points** of such functions.



# Differential theory for locally Lipschitz functions

## Subdifferential

- Let  $X \subseteq \mathbf{R}^n$  be a smooth submanifold,  $f: X \rightarrow \mathbf{R}$  a locally Lipschitz function, and  $x \in X$ .
- Denote by  $\Omega(f)$  the set of differentiable points of  $f$ , of full measure by Rademacher's theorem.
- The **subdifferential of  $f$  at  $x$**  is the convex body

$$\partial_x f := \text{conv} \left\{ \lim_{\substack{x_k \rightarrow x \\ x_k \in \Omega(f)}} D_{x_k} f \mid \text{the limit exists} \right\}.$$

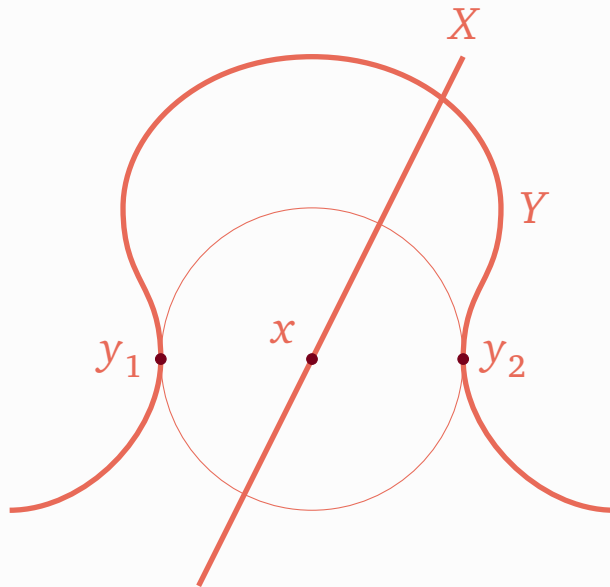
- The point  $x$  is **critical** if  $0 \in \partial_x f$ .

## Proposition

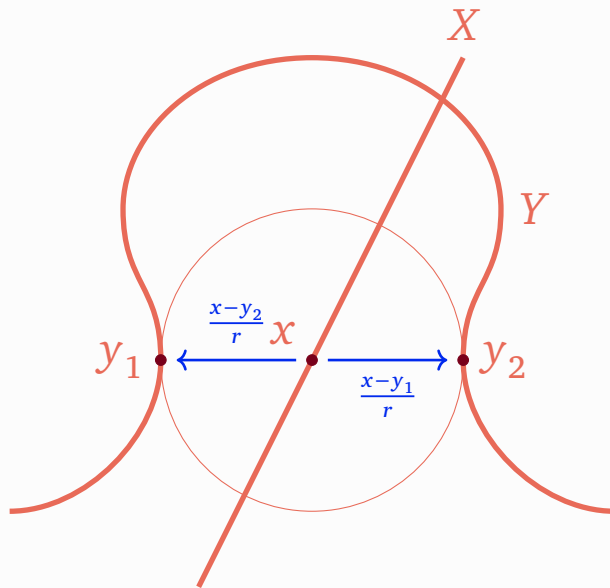
- Let  $X \subseteq \mathbf{R}^n$  be a submanifold and  $Y \subseteq \mathbf{R}^n$  a closed semialgebraic set such that  $X$  is transverse to  $Y$  (and the closure of its medial axis).
- Then the subdifferential of  $f = \text{dist}_Y|_X$  at a point  $x \in X$  is

$$\partial_x f = \text{proj}_{T_x X} \text{conv} \left\{ \frac{x - y}{\|x - y\|} \mid y \in B(x, \text{dist}_Y(x)) \cap Y \right\}.$$

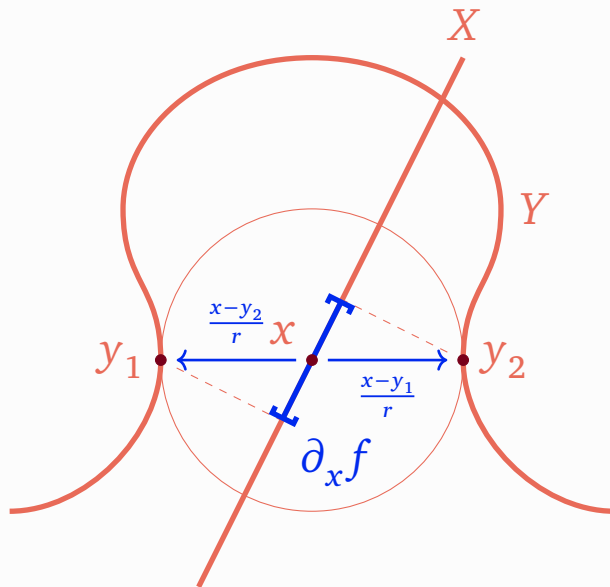
**Example:**



## Example:



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## Continuous selections

- Let  $f_0, \dots, f_m: X \rightarrow \mathbf{R}$  be continuous functions.
- A **continuous selection of**  $f_0, \dots, f_m$  is a function  $f: X \rightarrow \mathbf{R}$  if  $f$  is continuous and, for all  $x \in X$ , there exists  $i \in \{0, \dots, m\}$  such that  $f(x) = f_i(x)$ .

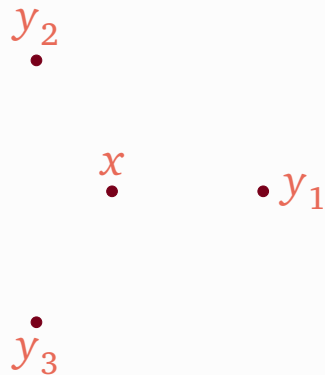
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- For all  $x \in X$ , we define its **effective index set** as

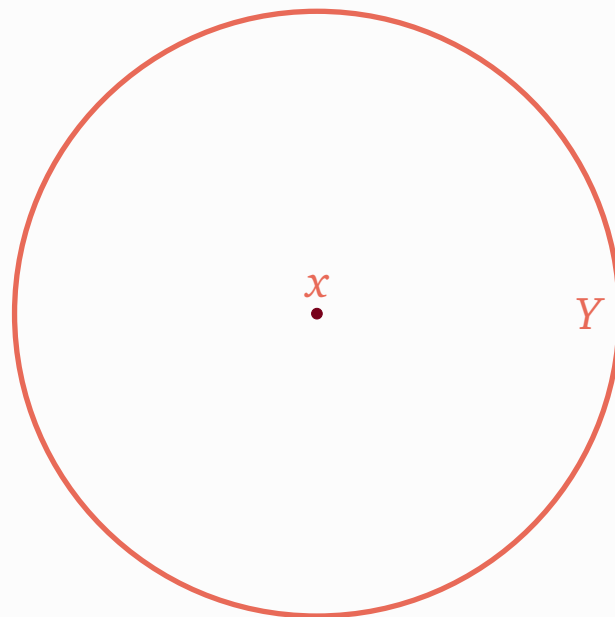
$$I(x) := \{i \in \{0, \dots, m\} \mid x \in \text{clos int}\{y \in X \mid f(y) = f_i(y)\}\}.$$

- **Fact:** the subdifferential of  $f$  at  $x$  is  $\text{conv}\{D_x f_i \mid i \in I(x)\}$ .

## Example:

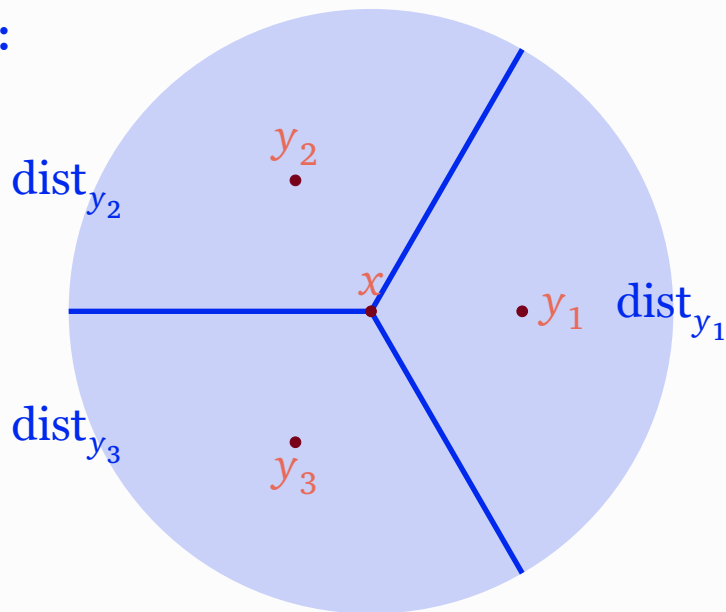


continuous selection

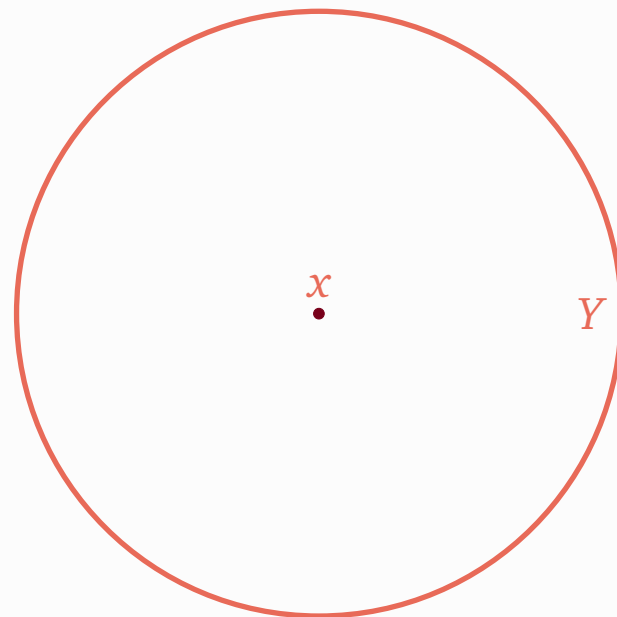


not a continuous selection

## Example:



continuous selection

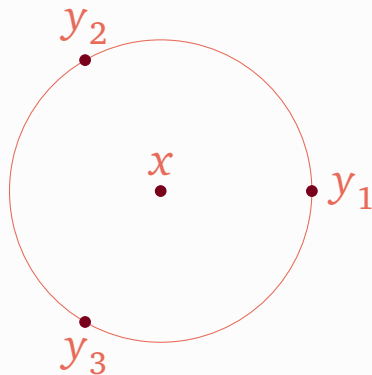


not a continuous selection

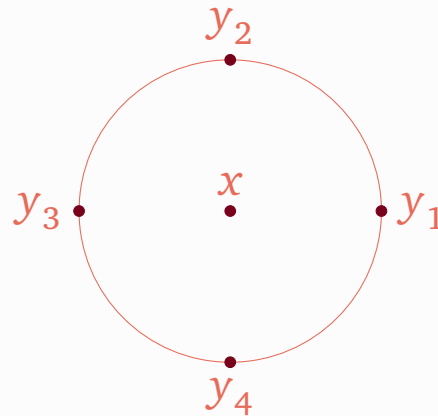
- A critical point  $x$  of  $f$  is **nondegenerate** if:
  1. for every  $i \in I(x)$ , the set of differentials  $\{D_x f_j \mid j \in I(x) \setminus \{i\}\}$  is linearly independent; and
  2. writing  $\sum_{i \in I(x)} \lambda_i D_x f_i = 0$  for the convex combination showing criticalness, the second differential of  $\sum_{i \in I(x)} \lambda_i f_i$  is nondegenerate on  $\bigcap_{i \in I(x)} \ker D_x f_i$ .

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- We denote by  $k(x) := \#I(x) - 1$  the **piecewise linear index of  $x$**  and by  $\iota(x)$  the negative inertia index of the above restricted second differential, which we call the **quadratic index of  $x$** .
  - We denote by  $C_{k,\iota}(X, Y)$  the set of nondegenerate critical points with piecewise linear index  $k$  and quadratic index  $\iota$ .

**Example:**

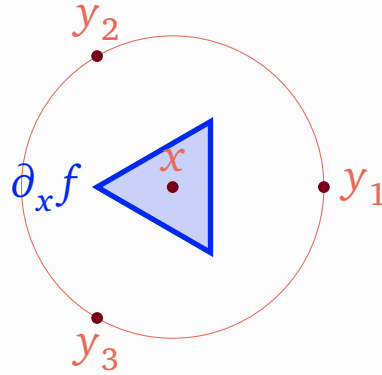


nondegenerate critical point

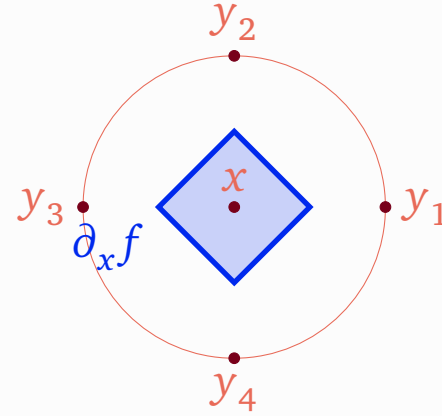


degenerate critical point

## Example:



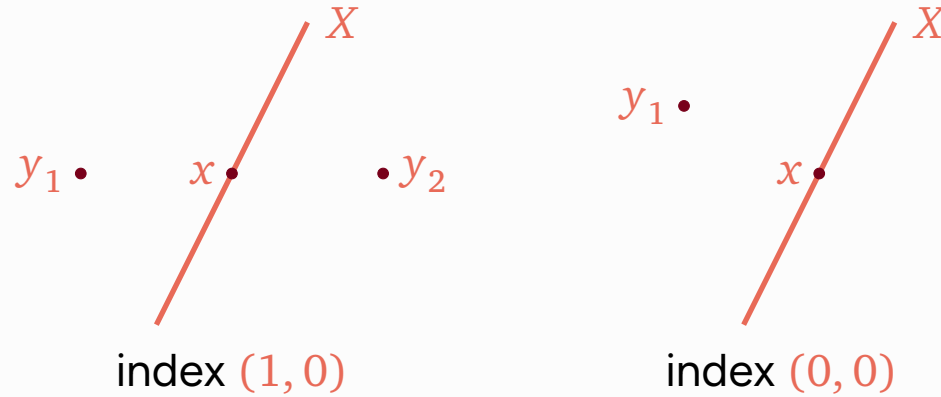
nondegenerate critical point



degenerate critical point



## Example:



## Normal forms

### Proposition [Jongen-Pallaschke 1988]

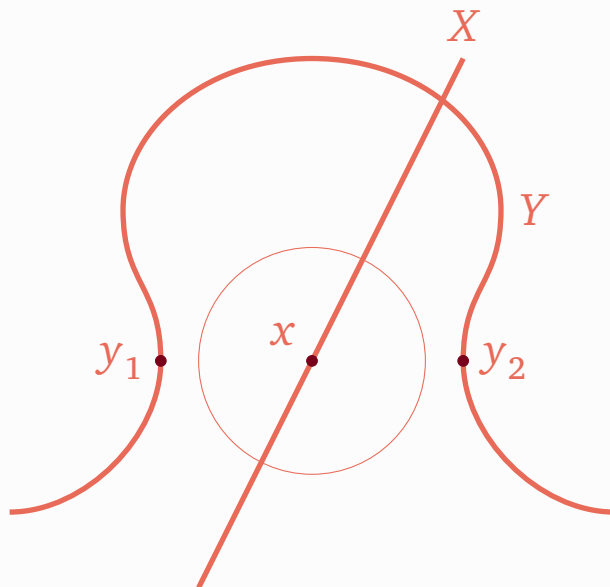
- For a continuous selection  $f: X \rightarrow \mathbf{R}$  and a nondegenerate critical point  $x \in X$  with piecewise linear index  $k$  and quadratic index  $\iota$ , there exists a neighborhood  $U$  of  $x$  and a locally Lipschitz homeomorphism  $\psi: \mathbf{R}^k \times \mathbf{R}^{n-k} \rightarrow U$  such that

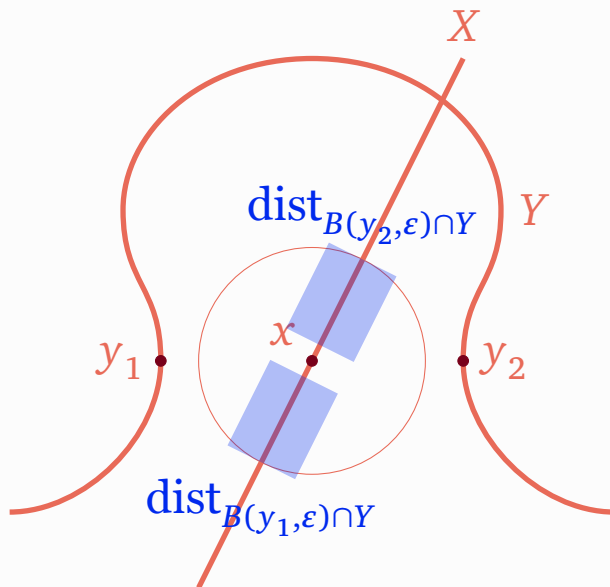
$$f(\psi(t_1, \dots, t_n)) = f(x) + \ell(t_1, \dots, t_k) - \sum_{j=k+1}^{k+\iota} t_j^2 + \sum_{j=k+\iota+1}^n t_j^2,$$

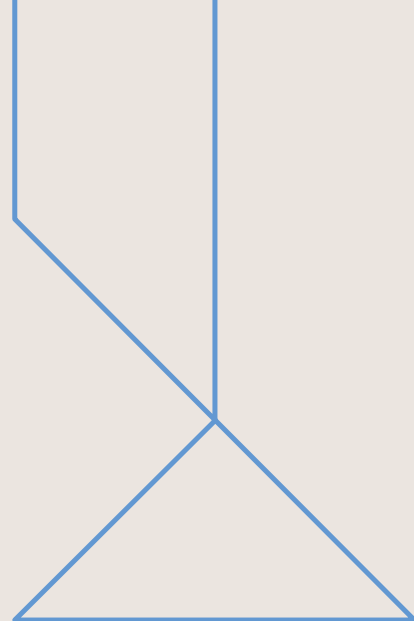
where  $\ell$  is a continuous selection of  $t_1, \dots, t_k, -(t_1 + \dots + t_k)$ .

## Proposition

- Let  $Y \subseteq \mathbf{R}^n$  be a smooth submanifold,  $\varphi: NY \rightarrow \mathbf{R}^n$  the exponential map, sending  $(y, v)$  to  $y + v$ , and  $x \in \mathbf{R}^n$  a regular value of  $\varphi$ .
- Then:
  1.  $B(x, \text{dist}_Y(x)) \cap Y$  is a finite set  $\{y_0, \dots, y_k\}$ ; and
  2.  $\text{dist}_Y|_{B(x, \delta)}$  is a continuous selection of the functions  $\text{dist}_{B(y_i, \varepsilon) \cap Y}|_{B(x, \delta)}$ .







# Morse theory for distance functions

## Between critical values

Proposition [Agrachev-Pallaschke-Scholtes 1997] actually it's Clarke

- Let  $f = \text{dist}_Y|_X$  and  $[a, b] \subseteq \mathbf{R}$  an interval containing no critical values.
- Then the space  $\{f \leq b\}$  deformation retracts to the space  $\{f \leq a\}$ .

## Passing a critical value

Proposition, follows from [Agrachev-Pallaschke-Scholtes 1997]

- Let  $X \subseteq \mathbf{R}^n$  be a smooth manifold and  $Y \subseteq \mathbf{R}^n$  a closed semialgebraic set.
- Let  $c > 0$  be a critical value of  $f = \text{dist}_Y|_X$  such that the associated critical points  $x_1, \dots, x_m$  are all nondegenerate. Then

$$H^* \left( \{f \leq c + \varepsilon\}, \{f \leq c - \varepsilon\} \right) \cong \bigoplus_{i=1}^m \tilde{H}^* \left( S^{k(x_i) + \iota(x_i)} \right).$$



# Morse inequalities

## Proposition

- Let  $X \subseteq \mathbf{R}^n$  be a smooth, compact, semialgebraic manifold and  $Y \subseteq \mathbf{R}^n$  a closed semialgebraic set such that all critical points of  $\text{dist}_Y|_X$  are nondegenerate.
- Then, for every integer  $\lambda \geq 0$ ,

$$\sum_{i=0}^{\lambda} (-1)^{i+\lambda} b_i(X) \leq \sum_{i=0}^{\lambda} (-1)^{i+\lambda} \left( b_i(X \cap Y) + \sum_{k+l=i} \#C_{k,l}(X, Y) \right),$$

where the  $b_i$  are cohomology dimensions.

- Moreover,

$$\chi(X \cap Y) + \sum_{k,l \geq 0} (-1)^{k+l} \#C_{k,l}(X, Y) = \chi(X).$$

- If  $Y$  is also smooth and compact, and  $\text{dist}_X|_Y$  has only nondegenerate critical points, then

$$\chi(Y) + \sum_{k,l \geq 0} (-1)^{k+l} \#C_{k,l}(X, Y) = \chi(X) + \sum_{k,l \geq 0} (-1)^{k+l} \#C_{k,l}(Y, X).$$



# Genericity for algebraic hypersurfaces

## Setup

- Let  $p$  and  $q$  be two real  $n$ -variable polynomials,  $X := Z(p)$ , and  $Y := Z(q)$ , and consider  $\text{dist}_Y|_X$ .

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- Let  $p$  and  $q$  be two real  $n$ -variable polynomials,  $X := Z(p)$ , and  $Y := Z(q)$ , and consider  $\text{dist}_Y|_X$ .
- We recover previously studied notions:
  - When  $p = 0$  (and so  $X = \mathbf{R}^n$ ), a critical point of piecewise linear index  $k$  is a **real geometric  $(k + 1)$ -bottleneck** [Di Rocco et al. 2023].
  - The **real bottleneck degree** is the number of such geometric  $2$ -bottlenecks.
  - When  $Y = \{y\}$  is a generic point, the number of critical points is (related to) the **Euclidean distance degree**.
- Our bounds on the number of critical points complement and generalize the known bounds on these values.

## Theorem (Parametric transversality, Hirsch 1976)

- Let  $M, N, P$  be smooth manifolds,  $W \subseteq N$  a submanifold of  $N$ , and  $F: P \times M \rightarrow N$  a smooth map.
- For all  $p$  in  $P$ , we denote by  $F_p$  the map  $F(p, -): M \rightarrow N$ .
- If  $F$  is transverse to  $W$ , then the set  $\{p \in P \mid F(p, -) \pitchfork W\}$  is residual in  $P$ .
  - In other words, for generic  $p \in P$ , the map  $F_p$  is transverse to  $W$ .
  - If  $M$  and  $W$  have small enough dimensions, then  $F_p$  misses  $W$  entirely.

## Theorem (Multijet parametric transversality)

- Now consider  $P = \mathcal{P}_d$  the space of polynomials of degree at most  $d$ ,  $M = ((\mathbf{R}^n)^k \setminus \Delta)$  the space of  $k$  distinct points in  $\mathbf{R}^n$ ,  $N = {}_k J^r(\mathbf{R}^n, \mathbf{R})$  the space of  $k$ -multijets of order  $r$ , and

$$F: \begin{cases} \mathcal{P}_d \times ((\mathbf{R}^n)^k \setminus \Delta) & \rightarrow & {}_k J^r(\mathbf{R}^n, \mathbf{R}) \\ (p, y_1, \dots, y_k) & \mapsto & \left( \frac{\partial^{|\alpha|} p}{\partial x^\alpha}(y_i) \right)_{\substack{\alpha \in \mathbf{N}^n, |\alpha| \leq r, \\ i \in \{1, \dots, k\}}} \end{cases} .$$

- Then there exists a function  $d(k, r)$  such that, for all  $d \geq d(k, r)$ , the map  $F$  is a submersion (and so is transverse to every submanifold of  $N$ ).

## Proposition

- For  $q$  generic of degree  $\geq 2$ , for all  $x \in \mathbb{R}^n$ , the set  $B(x, \text{dist}_Y(x)) \cap Y$  is a nondegenerate simplex.



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### Idea of proof:

- We follow the strategy of [Yomdin 1981].
- In particular, we use the original parametric transversality theorem.

- For all  $k \in \{0, \dots, n+1\}$ , define

$$F_k: \begin{cases} \mathcal{P}_d \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) \\ (q, x, \bar{y}) \end{cases} \begin{matrix} \rightarrow \\ \mapsto \end{matrix} \begin{matrix} {}_{k+1}J^0(\mathbf{R}^n, \mathbf{R}^2) \\ (\bar{y}, \dots, q(y_i), \dots, \|x - y_i\|^2, \dots), \end{matrix}$$

$$W_k := \left\{ (\bar{z}, \bar{s}, \bar{t}) \in {}_{k+1}J^0(\mathbf{R}^n, \mathbf{R}^2) \left| \begin{array}{l} \forall i \in \{0, \dots, k\}, s_i = 0, \\ \forall i \in \{1, \dots, k\}, t_i = t_0 \end{array} \right. \right\}.$$

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- We show  $F_k \pitchfork W_k$ , so  $F_k(q, -) \pitchfork W_k$  for generic  $q$  by parametric transversality.

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- This implies that  $y_0, \dots, y_k \in B(x, \text{dist}_Y(x)) \cap Y$  the  $\{y_i - y_0\}_{i=1}^k$  are linearly independent.

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- We show  $F_k \pitchfork W_k$ , so  $F_k(q, -) \pitchfork W_k$  for generic  $q$  by parametric transversality.
- This implies that  $y_0, \dots, y_k \in B(x, \text{dist}_Y(x)) \cap Y$  the  $\{y_i - y_0\}_{i=1}^k$  are linearly independent.
- The case  $k = n+1$  implies that  $B(x, \text{dist}_Y(x)) \cap Y$  has at most  $n+1$  elements, and these elements thus form a nondegenerate simplex.

## Theorem

- For  $p$  and  $q$  generic of degree  $\geq 3$ , there are a finite number of critical points.
- The number of critical points with piecewise linear index  $k$  is bounded above by  $c(k, n) \deg(p)^n \deg(q)^{n(k+1)}$ .

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- The number of critical points with piecewise linear index  $k$  is bounded above by  $c(k, n) \deg(p)^n \deg(q)^{n(k+1)}$ .

### Idea of proof:

- We follow a similar approach to [Di Rocco et al. 2023], defining necessary algebraic equations for critical points.
- The set of polynomials and points satisfying these equations is our  $W$ , and we apply parametric transversality.
- The upper bound follows from a bound on the Betti numbers of an algebraic set [Basu-Rizzie 2018].

- Specifically, we define

$$F^1: \begin{cases} \mathcal{P}_{d_1} \times \mathcal{P}_{d_2} \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) \times \mathbf{R}^{k+3} & \rightarrow J^1(\mathbf{R}^n, \mathbf{R}) \times {}_{k+1}J^1(\mathbf{R}^n, \mathbf{R}) \times \mathbf{R}^{k+3} \\ (p, q, x, \bar{y}, \bar{\lambda}, \mu, r) & \mapsto (x, p(x), \nabla p(x), \bar{y}, q(\bar{y}), \\ & \nabla q(\bar{y}), \bar{\lambda}, \mu, r) \end{cases},$$

$$W^1 := \left\{ \begin{array}{l} (x, s, u) \in J^1(\mathbf{R}^n, \mathbf{R}), \\ (\bar{y}, \bar{t}, \bar{v}) \in {}_{k+1}J^1(\mathbf{R}^n, \mathbf{R}), \\ \bar{\lambda} \in \mathbf{R}^{k+1}, \\ \mu, r \in \mathbf{R} \end{array} \left| \begin{array}{l} x = \mu u + \sum_{i=0}^k \lambda_i y_i, \\ \sum_{i=0}^k \lambda_i = 1, \\ s = 0, \\ \forall i \in \{0, \dots, k\}, t_i = 0, \\ \forall i \in \{0, \dots, k\}, \|x - y_i\|^2 = r^2, \\ \forall i \in \{0, \dots, k\}, \text{rk}(x - y_i, v_i) \leq 1 \end{array} \right. \right\}.$$

- The intersection  $\text{im } F^1(p, q, -) \cap W^1$  defines **algebraic  $k$ -critical points**.



## Proposition

- For  $p$  and  $q$  generic of degrees  $\geq 3$  and  $\geq 4$ , respectively, the distance function  $\text{dist}_Y|_X$  is a continuous selection around each of its critical points.

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### Idea of proof:

- We show that each critical point is a regular value of the exponential map.

- We define

$$F^2: \begin{cases} \mathcal{P}_{d_1} \times \mathcal{P}_{d_2} \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) \times \mathbf{R}^{k+3} & \rightarrow J^1(\mathbf{R}^n, \mathbf{R}) \times_{k+1} J^2(\mathbf{R}^n, \mathbf{R}) \times \mathbf{R}^{k+3} \\ (p, q, x, \bar{y}, \bar{\lambda}, \mu, r) & \mapsto (x, p(x), \nabla p(x), \bar{y}, q(\bar{y}), \\ & \nabla q(\bar{y}), H(q)(\bar{y}), \bar{\lambda}, \mu, r) \end{cases}$$

$$W^2 := \left\{ \begin{array}{l} (x, s, u) \in J^1(\mathbf{R}^n, \mathbf{R}), \\ (\bar{y}, \bar{t}, \bar{v}, \bar{H}) \in_{k+1} J^2(\mathbf{R}^n, \mathbf{R}), \\ \bar{\lambda} \in \mathbf{R}^{k+1}, \\ \mu, r \in \mathbf{R} \end{array} \left| \begin{array}{l} (x, s, u, \bar{y}, \bar{t}, \bar{v}, \bar{\lambda}, \mu, r) \in W^1, \\ \forall i \in \{0, \dots, k\}, \\ \text{rk}[(I_n + rH_i)(I_n - v_i v_i^\top), v_i] < n \end{array} \right. \right\}.$$

- The extra condition on  $W^2$  translates to being a regular value for the exponential map.

### Theorem

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### Idea of proof:

- We define necessary algebraic equations for degenerateness.
- Fact:** Degenerate critical points satisfy certain algebraic equations related to the second fundamental form of  $Y$ , which, at a point  $y \in Y$ , can be expressed as

$$\Pi_y: \begin{cases} T_y Y \times T_y Y \rightarrow N_y Y = \mathbf{R} \nabla q(y) \\ (v, w) \mapsto -\frac{\nabla q(y)}{\|\nabla q(y)\|} v^\top H(q)(y) w. \end{cases}$$

- We define

$$F^3: \begin{cases} \mathcal{P}_{d_1} \times \mathcal{P}_{d_2} \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) \times \mathbf{R}^{k+3} & \rightarrow J^2(\mathbf{R}^n, \mathbf{R}) \times_{k+1} J^2(\mathbf{R}^n, \mathbf{R}) \times \mathbf{R}^{k+3} \\ (p, q, x, \bar{y}, \bar{\lambda}, \mu, r) & \mapsto (x, p(x), \nabla p(x), H(p)(x), \bar{y}, \\ & q(\bar{y}), \nabla q(\bar{y}), H(q)(\bar{y}), \bar{\lambda}, \mu, r) \end{cases}$$

$$W^3 := \left\{ \begin{array}{l} (x, s, u, G) \in J^2(\mathbf{R}^n, \mathbf{R}), \\ (\bar{y}, \bar{t}, \bar{v}, \bar{H}) \in_{k+1} J^2(\mathbf{R}^n, \mathbf{R}), \\ \bar{\lambda} \in \mathbf{R}^{k+1}, \\ \mu, r \in \mathbf{R} \end{array} \left| \begin{array}{l} (x, s, u, \bar{y}, \bar{t}, \bar{v}, \bar{\lambda}, \mu, r) \in W^1, \\ \forall i \in \{0, \dots, k\}, \nu_i := \frac{v_i}{\|v_i\|} \in \mathbf{R}^n, \\ \forall i, Q_i := (I_n - \nu_i \nu_i^\top) \frac{H_i}{\|v_i\|} (I_n - \nu_i \nu_i^\top) \in \mathbf{R}^{n \times n}, \\ \forall i, \tilde{H}_i := \frac{-Q_i}{1-rQ_i} \in \mathbf{R}^{n \times n}, \\ V := [\frac{u}{\|u\|}, \nu_0, \dots, \nu_k] \in \mathbf{R}^{n \times (k+2)}, \\ L := I_n - V(V^\top V)^{-1} V^\top \in \mathbf{R}^{n \times n}, \\ \text{rk} \left( \mu L^\top G L + r \sum_{i=0}^k \lambda_i L^\top \tilde{H}_i L \right) \leq n - k - 3 \end{array} \right. \right\}.$$

## Summary

- We (re)develop Morse theory for distance functions between subsets of  $\mathbf{R}^n$  using the notion of **continuous selections**.
- We establish that the nondegeneracy of distance functions between algebraic hypersurfaces is generic using a **multijet parametric transversality theorem**.
- We also compute bounds for the number of critical points of such functions, which **generalize bounds** on the bottleneck degree and the Euclidean distance degree.
  - Our results should hold in the complex case as well.

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