



# Computational Game Theory

## Lecture 5

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# Today 's topics

- Efficiency of equilibria
- Potential games
- Super/submodular games



# Nash equilibrium vs. Social optimum



- Strategic game  $G = \langle N, (A_i), (u_i) \rangle$
- Social optimum – best possible outcome

$$U = \max_a SWF(u_1(a), u_2(a), \dots, u_{|N|}(a))$$

- Social welfare function  $SWF$  can be
  - Utilitarian  $SWF = \Sigma$  (no fairness)
  - Bernoulli-Nash  $SWF = \Pi$  (proportional fairness)
  - Rawls  $SWF = \min$  (max-min fairness)

# Inefficiency of equilibria



- Nash equilibria  $a^*$  are in general not social optimum
- Price of Anarchy (pure)

$$PoA = \frac{\max_{a \in A} SWF(u_1(a), \dots, u_{|N|}(a))}{\min_{a^*} SWF(u_1(a^*), \dots, u_{|N|}(a^*))}$$

- Price of Stability (pure)

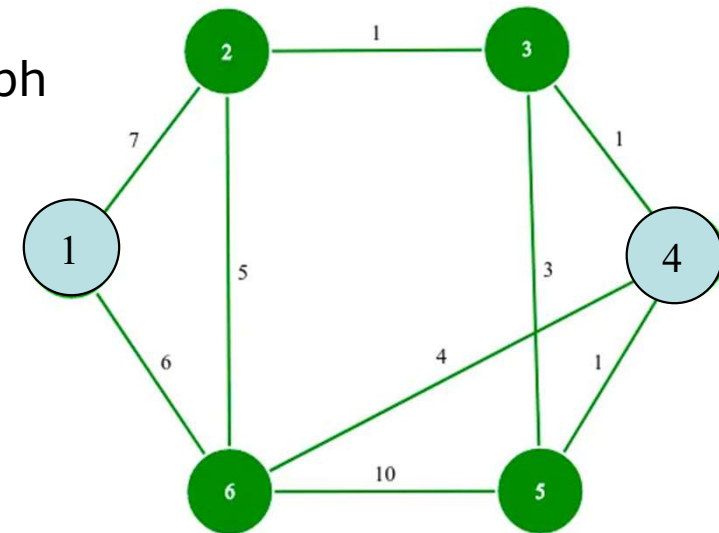
$$PoS = \frac{\max_{a \in A} SWF(u_1(a), \dots, u_{|N|}(a))}{\max_{a^*} SWF(u_1(a^*), \dots, u_{|N|}(a^*))}$$

- Mixed and Bayes-Nash PoA and PoS exist
- Extension to adversarial setting – Price of Malice

# Steiner problem in networks



- Digraph  $(V, E)$ 
  - Edge costs  $c_e \geq 0 \quad \forall e \in E$
- Set of pairs of vertices  $N = (s_i, t_i)_{i=1..n}$ 
  - For all  $(s_i, t_i)$   $t_i$  is reachable from  $s_i$
  - Set of paths from  $s_i$  to  $t_i$  is  $A_i$
  - All possible combinations of paths  $A = \bigcup_{i=1..n} A_i$
- Construct minimum weight subgraph
$$\min_{a \in A} \sum_{e \in a} c_e$$
- Applications
  - Routing in networks
  - VLSI design
- NP-hard in general



# Shapley network design game

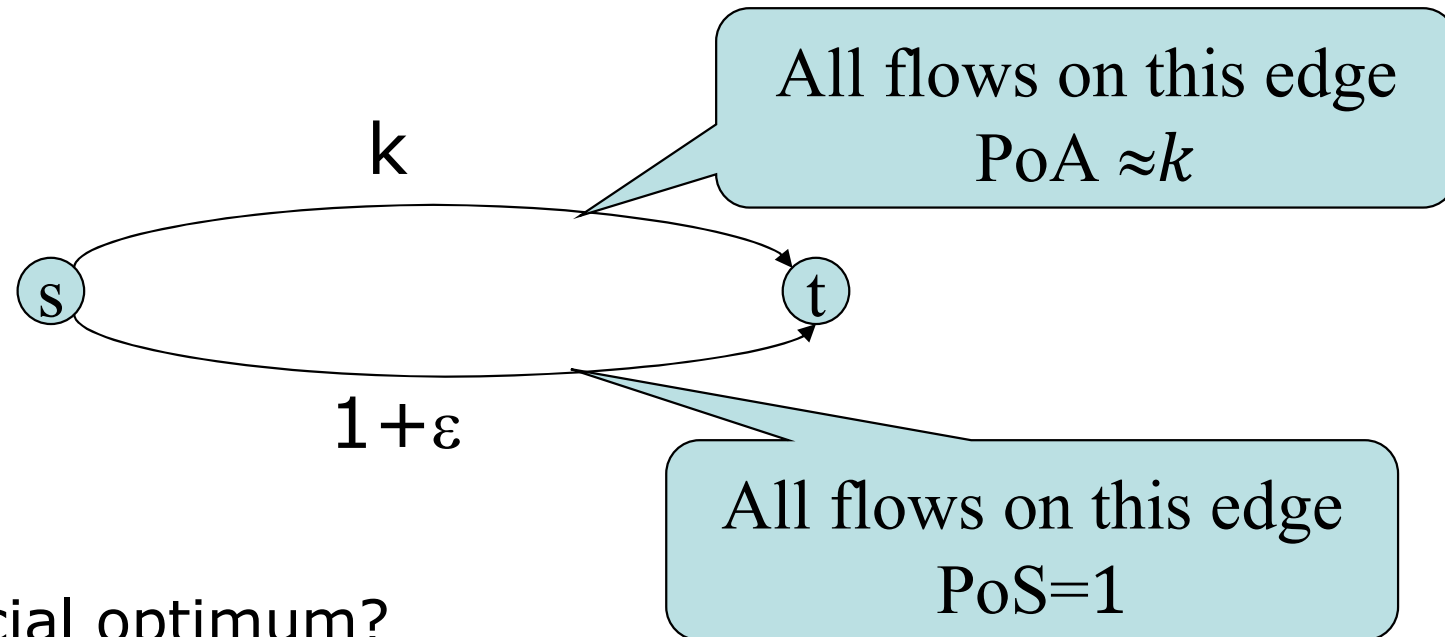


- Digraph  $(V, E)$ 
  - Edge costs  $c_e \geq 0 \quad \forall e \in E$
- Set of players  $N$ 
  - Player  $i \in N$  wants to build a network such that  $t_i$  is reachable from  $s_i$
- Sets of actions  $A_i$ 
  - $a_i \in A_i$  is a path  $(s_i, t_i)$  in  $(V, E)$
- Constructed network is  $\cup_{i \in N} a_i$
- Cost function of player  $i$  in the constructed network
$$\text{cost}_i(a) = \sum_{e \in a_i} c_e / k_e$$
  - $k_e = \#$  of players for which  $e \in a_i$
  - Shapley cost sharing mechanism (fair)



# First example

- $|N| = k$
- Source and destination the same for all



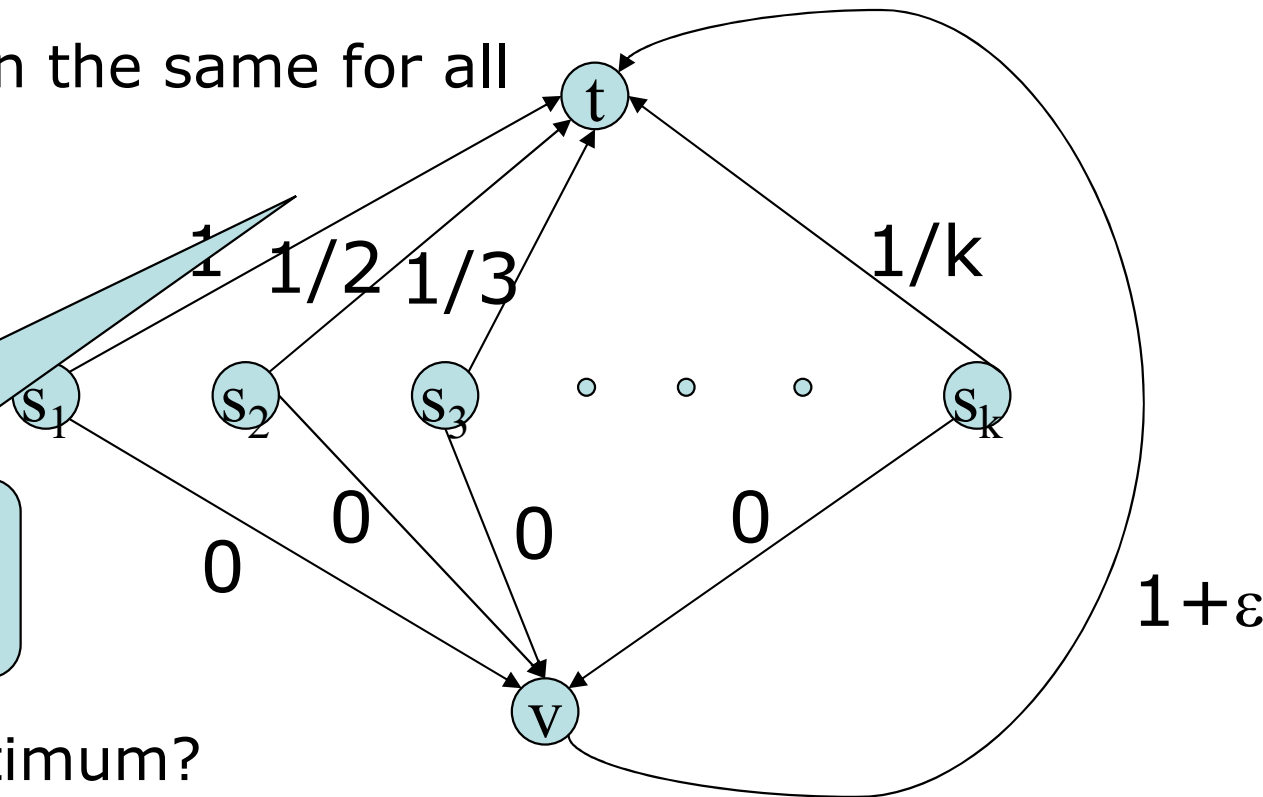
- Social optimum?
- Nash equilibria?
  - Price of Anarchy vs. Stability?

## Second example

- $|N|=k$
- Destination the same for all



All flows this way  
 $\text{PoA}=\text{PoS} \approx H_k$



- Social optimum?
- Nash equilibria?
  - Price of Anarchy and Stability?



# Claim

- Pure strategy equilibria always exist in the Shapley network design game



# Exact potential games



- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a finite strategic game and  $A = \prod_{i \in N} A_i$ .

A function  $\psi: A \rightarrow \mathbb{R}$  is an **exact potential** for  $G$  if

$$\psi(a_{-i}, b_i) - \psi(a_{-i}, a_i) = u_i(a_{-i}, b_i) - u_i(a_{-i}, a_i) \\ \forall a \in A, \forall a_i, b_i \in A_i$$

- A game  $G = \langle N, (A_i), (u_i) \rangle$  is called an **exact potential game** if it admits an exact potential.

# An example

- Prisoner's dilemma



	Do not confess	Confess
Do not confess	6,6	0,9
Confess	9,0	1,1

- And its exact potential

0	3
3	4



# Weighted potential games

- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a finite strategic game and  $A = \prod_{i \in N} A_i$ .
- A function  $\psi: A \rightarrow \mathbb{R}$  is a **weighted potential** for  $G$  if

$$\psi(a_{-i}, b_i) - \psi(a_{-i}, a_i) = w_i (u_i(a_{-i}, b_i) - u_i(a_{-i}, a_i)) \\ \forall a \in A, \forall a_i, b_i \in A_i, w_i > 0$$

- A game  $G = \langle N, (A_i), (u_i) \rangle$  is called a **weighted potential game** if it admits a weighted potential.
- Inclusion
  - Every exact potential game is a weighted potential game.



# Ordinal potential games

- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a finite strategic game and  $A = \prod_{i \in N} A_i$ .
- A function  $\psi: A \rightarrow \mathbb{R}$  is an **ordinal potential** for  $G$  if

$$\psi(a_{-i}, b_i) - \psi(a_{-i}, a_i) > 0 \Leftrightarrow u_i(a_{-i}, b_i) - u_i(a_{-i}, a_i) > 0 \\ \forall a \in A, \forall a_i, b_i \in A_i$$

- A game  $G = \langle N, (A_i), (u_i) \rangle$  is called an **ordinal potential game** if it admits an ordinal potential.
- Inclusion
  - Every weighted potential game is an ordinal potential game.

# Another example

- Battle of the Sexes



	Theatre	Sports
Sports	3,2	0,0
Theatre	0,0	2,3

- And its ordinal potential

2	0
0	2



# Existence of equilibria

- Let  $\Psi$  be an ordinal potential for  $G = \langle N, (A_i), (u_i) \rangle$ . The equilibrium set of  $G$  coincides with that of  $\langle N, (A_i), (\Psi) \rangle$ . That is,  
$$a \in A \text{ is a NE of } G \Leftrightarrow \Psi(a_{-i}, a_i) \geq \Psi(a_{-i}, a_i') \text{ for } a_i' \in A_i$$
  
If  $\Psi$  admits a maximum value in  $A$ , then  $G$  possesses a pure strategy Nash equilibrium.
- Proof:  
$$\psi(a_{-i}, b_i) - \psi(a_{-i}, a_i) > 0 \Leftrightarrow u_i(a_{-i}, b_i) - u_i(a_{-i}, a_i) > 0$$
  
$$\forall a \in A, \forall a_i, b_i \in A_i$$
  
Consider  $a \in A$  for which  $\Psi(a)$  is maximal.  
For any  $a' = (a_{-i}, a_i')$  we have  $\Psi(a_{-i}, a_i) \geq \Psi(a_{-i}, a_i')$  and hence  
$$u_i(a_{-i}, a_i) \geq u_i(a_{-i}, a_i')$$
- Consequence  
Every finite ordinal potential game possesses a pure-strategy Nash equilibrium

## Example continued: SND game



- Consider the SND game  $\langle N, (A_i), (u_i) \rangle$
- Define for each  $e \in E$

$$\Psi_e(a) = c_e H_{k_e}$$

$k_e = \#$  of players for which  $e \in a_i$

$$H_k = \sum_{j=1}^k \frac{1}{j}$$

- Define the function

$$\Psi(a) = \sum_e \Psi_e(a)$$

- Claim:  $\Psi(a)$  is an exact potential for the SND game



# Example continued: SND game II



- Let  $a=(a_i)_{i=1..k}$ ,  $a_i' \neq a_i$  be an alternate path for player  $i$ , and  $a'=(a_{-i}, a_i')$ . Then

$$\Psi(a) - \Psi(a') = u_i(a') - u_i(a)$$

- Proof

$$e \in a_i, e \in a_i' \text{ or } e \notin a_i, e \notin a_i' \rightarrow \begin{cases} \psi_e(a) = \psi_e(a') \\ c_e / k_e|_{a_i} = c_e / k_e|_{a_i'} \end{cases}$$

$$e \in a_i, e \notin a_i' \rightarrow \begin{cases} \psi_e(a') = \psi_e(a) - c_e / k_e \\ u_i(a') = u_i(a) + c_e / k_e \end{cases}$$

$$e \notin a_i, e \in a_i' \rightarrow \begin{cases} \psi_e(a') = \psi_e(a) + c_e / (k_e + 1) \\ u_i(a') = u_i(a) - c_e / (k_e + 1) \end{cases}$$

- Furthermore

$$\text{cost}(a) \leq \Psi(a) \leq H_k \text{cost}(a)$$

# Price of stability



- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a finite strategic game with exact potential  $\Psi$  such that

$$\frac{\text{cost}(a)}{C} \leq \Psi(a) \leq D \text{cost}(a)$$

for some constants  $C, D > 0$ . Then  $\text{PoS} \leq C \times D$ .

- Proof
  - Let  $a^* \in A$  be a local maximizer of  $\Psi \Rightarrow a^*$  is NE
  - Let  $\hat{a}$  be a global maximizer of  $\Psi$

$$\left. \begin{array}{l} D \text{cost}(\hat{a}) \geq \Psi(\hat{a}) \\ \Psi(\hat{a}) \geq \Psi(a^*) \\ \Psi(a^*) \geq \frac{\text{cost}(a^*)}{C} \end{array} \right\} \Longrightarrow \begin{array}{l} D \text{cost}(\hat{a}) \geq \Psi(\hat{a}) \geq \Psi(a^*) \geq \frac{\text{cost}(a^*)}{C} \\ C \times D \text{cost}(\hat{a}) \geq \text{cost}(a^*) \\ C \times D \geq \frac{\text{cost}(a^*)}{\text{cost}(\hat{a})} \end{array}$$

# Improvement path



- A **path** in  $A$  is a sequence  $\gamma=(a^0,a^1,...)$  such that for every  $k \geq 1$  there is a **unique** player  $i$  such that  $a^k = (a_{-i}^{k-1}, a_i')$  for some  $a_i' \neq a_i^{k-1}$ 
  - Initial point of  $\gamma$  is  $a^0$
  - For finite  $\gamma$  last element called terminal point
- A path  $\gamma=(a^0,a^1,...)$  is an **improvement path** w.r.t. game  $G=<N,(A_i),(u_i)>$  if for all  $k \geq 1$   $u_i(a^k) > u_i(a^{k-1})$ , where player  $i$  is the unique deviator at step  $k$ .
  - path generated by *myopic* players
  - “Nash” or “asynchronous better reply” dynamics



# Finite improvement property

- The strategic game  $G = \langle N, (A_i), (u_i) \rangle$  has the **finite improvement property** (FIP) if every improvement path  $\gamma = (a^0, a^1, \dots)$  is finite.
- Every finite ordinal potential game has the FIP.
- Proof
  - By definition  $\psi(a^0) < \psi(a^1) < \dots$
  - Since  $A$  is finite, the improvement path must be finite
- In any finite ordinal potential game the asynchronous better reply dynamic always converges to a Nash equilibrium

# Generalized Ordinal Potential



- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a finite strategic game, and  $A = \prod_{i \in N} A_i$ . A function  $\psi: A \rightarrow \mathbb{R}$  is a generalized ordinal potential for  $G$  if

$$u_i(a_{-i}, b_i) - u_i(a_{-i}, a_i) > 0 \Rightarrow \psi(a_{-i}, b_i) - \psi(a_{-i}, a_i) > 0 \\ \forall a \in A, \forall a_i, b_i \in A_i$$

	L	R
T	1,0	2,0
B	2,0	0,1

0	3
1	2

- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a finite strategic game.  $G$  has the FIP property iff  $G$  has a generalized ordinal potential.

# Infinite potential games



- A strategic game  $G = \langle N, (A_i), (u_i) \rangle$  is a bounded game if  $(u_i)_{i \in N}$  are bounded
- Every bounded infinite weighted potential game possesses an  $\varepsilon$ -equilibrium point for every  $\varepsilon > 0$
- Proof:
  - $\Psi$  is bounded because  $u_i$  is bounded, hence
$$\exists a' \in A \text{ s.t. } \Psi(a') > \sup_{a \in A} \Psi(a) - \varepsilon$$

# Approximate finite improvement



- A path  $\gamma=(a^0,a^1,\dots)$  is an  $\varepsilon$ -improvement path for the strategic game  $G=<N,(A_i),(u_i)>$  if for all  $k\geq 1$   $u_i(a^k)>u_i(a^{k-1})+\varepsilon$ , where  $i$  is the unique deviator at step  $k$ .
  - $\varepsilon$ -Nash dynamics
- The strategic game  $G=<N,(A_i),(u_i)>$  has the approximate FIP property if for  $\forall\varepsilon>0$  every  $\varepsilon$ -improvement path is finite.
- Every bounded infinite potential game has the approximate FIP property.

# Continuous potential games



- A strategic game  $G = \langle N, (A_i), (u_i) \rangle$  is continuous if  $A_i$  are topological spaces, and  $u_i$  are continuous w.r.t  $A = \prod_{i \in N} A_i$ .
- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a continuous exact potential game with compact action sets.  $G$  possesses a pure strategy Nash-equilibrium.



# Construction of the potential

- Let  $G = \langle N, (A_i), (u_i) \rangle$ ,  $A_i \subset \mathbb{R}$  compact,  $u_i$  continuously differentiable and  $\Psi: A \rightarrow \mathbb{R}$ .

Then  $\Psi$  is a potential for  $G$  iff  $\Psi$  is continuously differentiable and

$$\frac{\partial u_i}{\partial a_i} = \frac{\partial \Psi}{\partial a_i} \quad \forall i \in N$$



# Congestion games



- Set of players  $N = \{1, \dots, n\}$
- Primary factors  $T = \{1, \dots, t\}$
- Action set  $A_i = \{1, \dots, a_{ij}\} \subseteq 2^T$ 
  - Action  $a_i \subseteq T$
- Cost of action  $a_i$

$$\text{cost}_i(a_{-i}, a_i) = \sum_{\tau \in a_i} \overset{\swarrow}{c}_\tau(k_\tau),$$

Same for all players!

where  $k_\tau = \#$  of players using factor  $\tau$  in  $a$

# Congestion games



- Every congestion game is an exact potential game with potential

$$\Psi(a) = \sum_{\tau \in T} \sum_{y=1}^{k_{\tau}} c(y)$$

- Every finite potential game is isomorphic to a congestion game.

R.W. Rosenthal, "A Class of Games Possessing Pure-Strategy Nash Equilibria," vol. 2, Int. J. Game Theory, pp. 65–67, 1973  
D. Monderer, L.S. Shapley, "Potential Games", Games and Economic Behavior vol. 14., pp. 124-143, 1996

# Examples of congestion games



- Selfish routing games
  - Non-atomic
    - Multipath allowed
  - Atomic non-weighted
    - Single path only
    - Same amount of traffic for all players
- Market sharing games
- Load balancing games

# Minimum cut problem



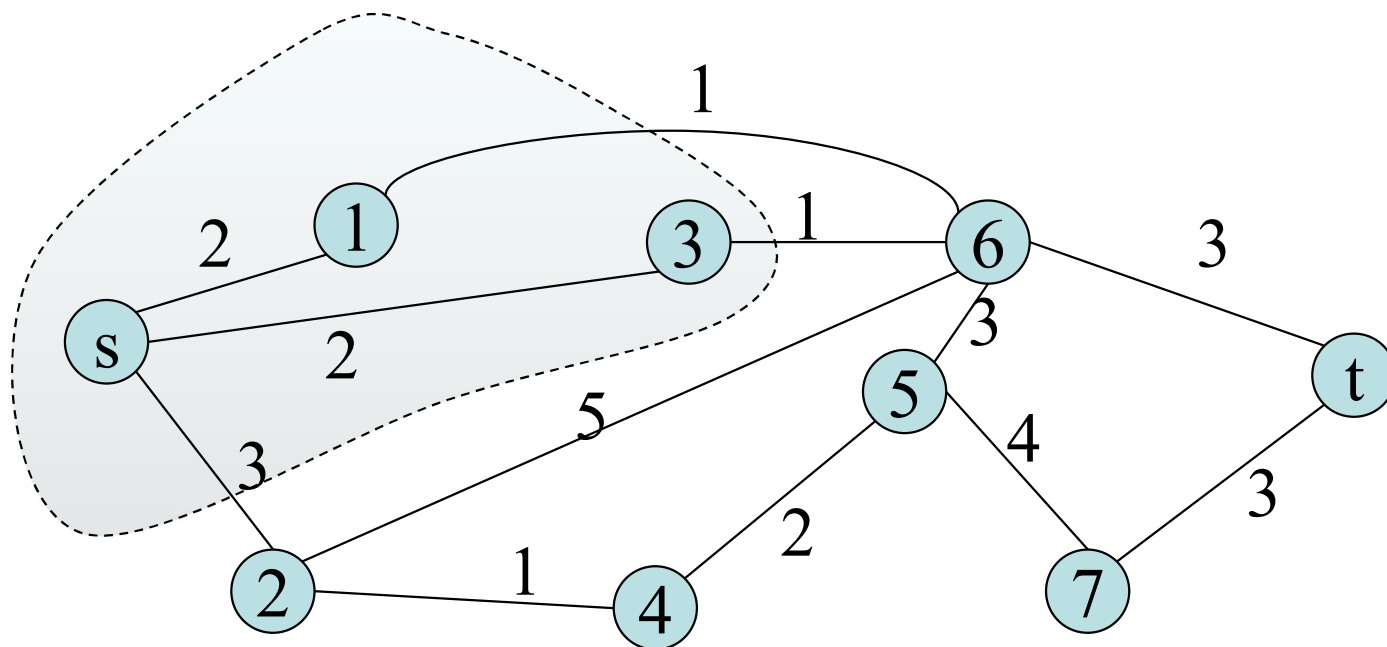
- Network of nodes  $V \cup \{s\} \cup \{t\}$ ,  $|V|=m$
- Capacity  $c(w,z) \geq 0$  for every pair of nodes  
 $(w,z) \in V \cup \{s\} \cup \{t\} \times V \cup \{s\} \cup \{t\}$

- Let  $X \subseteq V$  then  $X \cup \{s\}$  is a *cut*
- Cut capacity

$$f(X) = \sum_{w \in X \cup s} \sum_{z \notin X \cup s} c(w,z)$$

- $X^* \cup \{s\}$  is *minimum cut* if  $X^* \subseteq V$  and  
 $f(X^*) \leq f(X) \quad \forall X \subseteq V$

# Minimum cut problem



- Min-cut:  $\{1, 3, s\}$

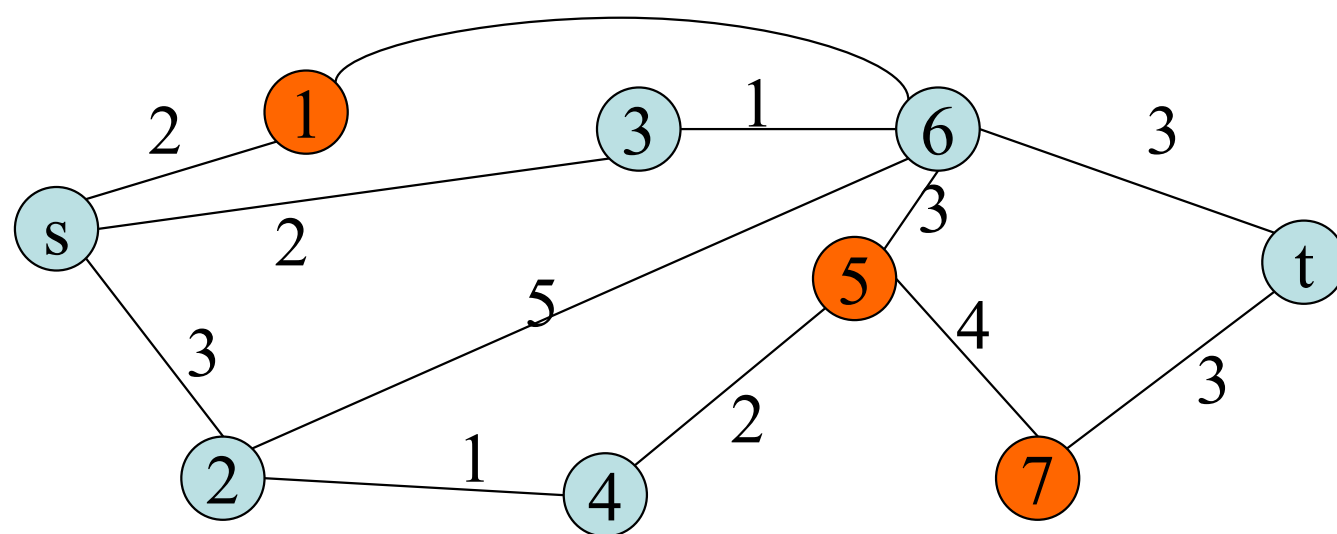


# Minimum cut game

- Set of players  $N$ ,  $|N|=n$ 
  - $V = \cup_{i=1..n} V_i$ ,  $V_i \cap V_j = \emptyset$  for  $\forall i \neq j$ ,  $|V_i|=m_i$
- Action set  $A_i = \{X_i : X_i \subseteq V_i\}$
- Capacity function  $c_i(w, z)$  (player specific)
- Objective of player  $i$ 
$$\min_{a_i} f_i(X) = f_i(X_i \cup (\cup_{i \neq j} X_j))$$
- Claim: The minimum cut game has a pure strategy Nash equilibrium.

# Minimum cut game

- $N = \{1, 2\}$ ,  $V_1 = \{1, 5, 7\}$ ,  $V_2 = \{2, 3, 4, 6\}$



- Min-cut:  $\{1, 3, s\}$
- NE:  $X_1 = \{1\}$ ,  $X_2 = \{3\}$



# Lattices and Sublattices



- A partially ordered set  $(A, \geq)$  is a lattice if
  - for  $a, b \in A \exists c \in A$  s.t.  $a \vee b = c$  ( $c \geq a, c \geq b$ , *join*)
  - for  $a, b \in A \exists c \in A$  s.t.  $a \wedge b = c$  ( $a \geq c, b \geq c$ , *meet*)
- A sublattice of a lattice  $L$  is a subset of  $L$  and itself a lattice with respect to the same  $\wedge$  and  $\vee$  operators.
- If  $A$  is a nonempty compact sublattice of  $R^m$ , it has a greatest and a least element.
  - the sublattice  $A$  is bounded
  - componentwise partial ordering

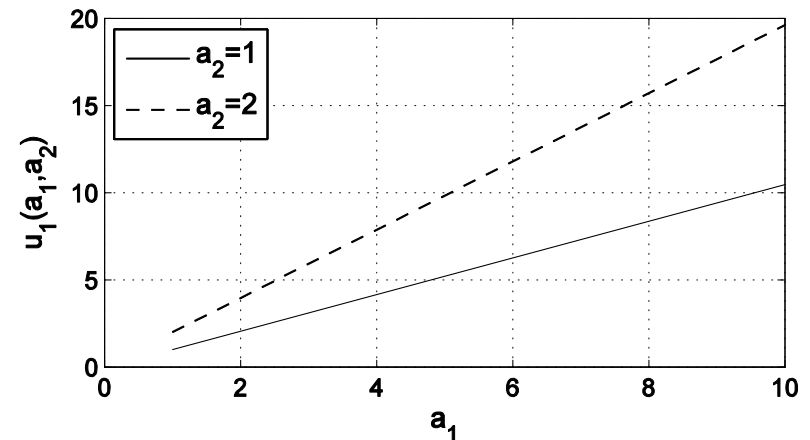
G. Birkhoff, "Lattice theory", American Mathematical Society, 1967

# Increasing Differences



- Let  $X, T$  be posets,  $S \subseteq X \times T$ ,  $S_t = \{x \mid (x, t) \in S\}$ 
  - $u_i(a)$  has increasing differences in  $(a_i, a_j)$  if for  $(a'_i, a'_j) \in S$  such that  $a'_i \geq a_i$  and  $a'_j \geq a_j$ 

$$u_i(a'_i, a'_j) - u_i(a_i, a'_j) \geq u_i(a'_i, a_j) - u_i(a_i, a_j)$$
- Let  $A_i$  be poset,  $A \subseteq \times A_i$ 
  - $u_i(a)$  has increasing differences on  $A$  if it has increasing differences in all  $(a_i, a_j)$  for  $i \neq j$  and fixed  $a_{-i,j}$
- Twice differentiable
 
$$\frac{\partial^2 u_i}{\partial a_l \partial a_k} \geq 0 \quad \forall k, l$$
- Example
  - $f: \mathbb{R} \rightarrow \mathbb{R}$  convex
 
$$u_i(a) = f(\Pi_{i=1}^{|N|} a_i)$$
    - *Strictly increasing*



# Supermodular Functions



- $u_i(a_{-i}, a_i)$  is supermodular on  $A_i$  (lattice) if for  $a_i, a_i^* \in A_i$  and  $\forall a_{-i} \in A_{-i}$ 

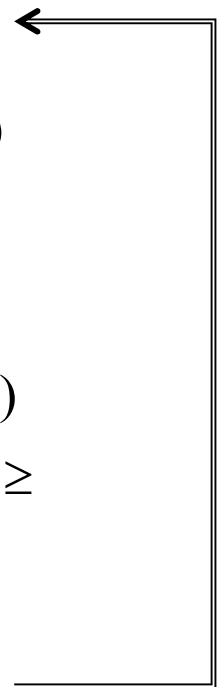
$$u_i(a_{-i}, a_i) + u_i(a_{-i}, a_i^*) \leq u_i(a_{-i}, a_i \wedge a_i^*) + u_i(a_{-i}, a_i \vee a_i^*)$$
- $u_i(a_{-i}, a_i)$  is strictly supermodular on  $A_i$  if for  $a_i, a_i^* \in A_i$  and  $\forall a_{-i} \in A_{-i}$ 

$$u_i(a_{-i}, a_i) + u_i(a_{-i}, a_i^*) < u_i(a_{-i}, a_i \wedge a_i^*) + u_i(a_{-i}, a_i \vee a_i^*)$$

whenever  $a_i$  and  $a_i^*$  are not comparable w.r.t  $\geq$
- $u_i(a)$  is supermodular on  $A$  (lattice) if for  $a, a^* \in A$

$$u_i(a) + u_i(a^*) \leq u_i(a \wedge a^*) + u_i(a \vee a^*)$$

Substitute:  
 $a = (a_{-i}, a_i)$ ,  
 $a^* = (a_{-i}, a_i^*)$



# Submodular Functions



- $u_i(a_{-i}, a_i)$  is submodular on  $A_i$  (lattice)  
if for  $a_i, a_i^* \in A_i$  and  $\forall a_{-i} \in A_{-i}$   
$$u_i(a_{-i}, a_i) + u_i(a_{-i}, a_i^*) \geq u_i(a_{-i}, a_i \wedge a_i^*) + u_i(a_{-i}, a_i \vee a_i^*)$$
- Alternative definition
  - Let  $f$  be set function defined on  $S$ , and  $X \subseteq Y \subseteq S$ . Then  $f$  is submodular if  $\forall x \in S \setminus Y$   
$$f(X \cup \{x\}) - f(X) \geq f(Y \cup \{x\}) - f(Y)$$
- Example
  - Let  $Q$  matrix with column set  $B$ . For  $X \subseteq B$  let  $r(X)$  be the rank of matrix formed by  $X$ .  $r(X)$  is submodular.

# Why Sub/Supermodularity?



- Let  $f: 2^E \rightarrow R$  monotone submodular set function.

$$\begin{aligned} & \max_S f(S) \\ & \text{s.t. } |S| \leq k \\ & \quad S \subseteq E \end{aligned}$$

- Greedy algorithm
  - $S^G = \emptyset$
  - *while*  $|S^G| < k$
  - $e = \operatorname{argmax}_{e \in E} |f(S^G \cup e) - f(S^G)|$
  - $S^G = S^G \cup e$
  - *end*
- Theorem:  $\frac{f(S^G)}{f(S^*)} \geq 1 - \frac{1}{e}$

Cornuejols, Fisher, Nemhauser “Location of Bank Accounts to Optimize Float: An Analytic Study of Exact and Approximate Algorithms”, Management Science, 1977

# Simple examples



- Let  $f: R \rightarrow R$  be a convex function and
$$u_i(a) = f(\Pi_{i=1}^{|N|} a_i)$$
  - $u_i(a)$  is supermodular
- Let  $A$  and  $B$  be finite sets and  $f(A) = g(|A|)$ 
  - $f$  supermodular  $\Leftrightarrow g$  convex
$$f(A) + f(B) \leq f(A \cup B) + f(A \cap B)$$
    - Example:  $g(x) = x^2$

# Supermodularity $\Rightarrow$ Increasing differences

- Let  $A_i$  lattice,  $A$  sublattice of  $\times A_i$
- If  $u_i(a)$  is supermodular on  $A$  then it has increasing differences on  $A$



take  $a'_i \geq a_i$  and  $a'_{-i} \geq a_{-i}$  and  $x = (a_{-i}, a'_i)$ ,  $y = (a'_{-i}, a_i)$

$$u_i(x) + u_i(y) \leq u_i(x \wedge y) + u_i(x \vee y)$$

$$x \vee y = (a'_{-i}, a'_i) \quad x \wedge y = (a_{-i}, a_i)$$



$$u_i(a'_{-i}, a'_i) - u_i(a'_{-i}, a_i) \geq u_i(a_{-i}, a'_i) - u_i(a_{-i}, a_i)$$

# Partial Ordering of Sublattices



- Let  $X, Y$  be nonempty sublattices of  $E^n$

- Partial ordering  $\leq^p$

$$X \leq^p Y \quad \text{if} \quad x \wedge y \in X \text{ and } x \vee y \in Y \quad \forall x \in X, y \in Y$$



- Let  $X_y$  be collection of nonempty sublattices of  $E^n$  for  $y \in Y \subseteq E^m$ 
  - $X_y$  is ascending on  $Y$  if  $X_y \leq^p X_w$  for  $y \leq w$
- Let  $X_y$  be lower/upper contour set on sublattice of  $E^n$ 
  - $X_y$  is ascending in  $y$

D.M. Topkis, "Equilibrium points in nonzero-sum n-person submodular games", SIAM J. Control and Optimization 17(6), pp.773-787, 1979.

György Dán, <https://people.kth.se/~gyuri>



# Topkis's Theorem



- Let  $D$  be a lattice (independent of  $\theta$ , or ascending in  $\theta$ ). If  $f$  has increasing differences in  $(x, \theta)$  and is supermodular in  $x$  then

$$x^* = \arg \max_{x \in D} f(x, \theta)$$

is increasing in the strong set order.

D.M. Topkis, "Equilibrium points in nonzero-sum  $n$ -person submodular games", SIAM J. Control and Optimization 17(6), pp.773-787, 1979.

# Supermodular games



- Strategic game  $G = \langle N, (A_i), (u_i) \rangle$  is (strictly) supermodular if
  - $A_i$  is a non-empty sublattice of a Euclidean space
  - $u_i$  has (strictly) increasing differences in  $(a_{-i}, a_i)$
  - $u_i$  is (strictly) supermodular on  $A_i$

# Existence of equilibria



- Let  $G = \langle N, (A_i), (u_i) \rangle$  be a supermodular game,
  - $A_i$  compact, and
  - $u_i$  upper-semicontinuous in  $a_i$  for each  $a_{-i}$ ,then the set of pure strategy NE is nonempty and possesses greatest and least elements.

Upper-semicontinuity:

$$\limsup_{x \rightarrow x_0} f(x) \leq f(x_0)$$

D.M. Topkis, "Equilibrium points in nonzero-sum n-person submodular games", SIAM J. Control and Optimization 17(6), pp.773-787, 1979.

# Example – Min-cut game rev.



- Set of actions  $A_i = 2^{V_i}$  (power set of  $V_i$ )
  - Lattice with respect to inclusion, union, intersection
- $f(X)$  is submodular on  $A$ 
$$f(S) + f(T) \geq f(S \cap T) + f(S \cup T)$$
$$f(S) + f(T) - f(S \cap T) - f(S \cup T) =$$
$$= c(A(S : T)) + c(A(T : S)) \geq 0$$

where  $A(X : Y) = \{(i, j) \in E : i \in X, j \in Y\}$
- $f_i(X)$  is submodular on  $X_i$

D.M. Topkis, "Ordered optimal solutions",  
PhD thesis, U. of Stanford, 1968

# Convergence to Equilibria



- Let  $G$  be a supermodular game and let
  - $A_i$  compact,
  - $u_i$  upper-semicontinuous on  $A_i(a_{-i}) \ \forall a_{-i} \in A_i$
  - (the best response correspondences  $B_i(a_{-i})$  have the ascending property)

then the best response dynamic converges to a pure Nash equilibrium (starting from least element)

- Similar result holds for submodular games (descending property)

D.M. Topkis, "Equilibrium points in nonzero-sum  $n$ -person submodular games", SIAM J. Control and Optimization 17(6), pp.773-787, 1979.

# Super- and submodular games



- Supermodular games
  - Strategic complements
  - Minimum cut game (e.g., choosing activities)
  - Facility location problem
  - Steiner tree in a graph (minimum spanning tree)
- Submodular games
  - Strategic substitutes
- Mixture of submodular and supermodular
  - S-modular

# Literature



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