

Krylov methods for large-scale generalized Sylvester equations with low-rank commuting coefficients

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Framework

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- We consider (\star) . Our assumptions:

$$AN_i - N_i A = U_i \tilde{U}_i^T, \quad BM_i - M_i B = Q_i \tilde{Q}_i^T$$

Outline

- Neumann series expansion
- Krylov method: exploiting the low rank commutation
- Low rank numerical solutions
- Numerical experiments

Neumann series expansion

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Solution as a Neumann series

Let $\mathcal{L}(X) := AX + XB^T$ and $\Pi(X) := \sum_{i=1}^m N_i XM_i^T$. Assume $\|\mathcal{L}^{-1}\Pi\| < 1$, then the unique solution satisfies

$$X = \sum_{j=0}^{\infty} (-1)^j Y_j$$

where $\mathcal{L}(Y_0) = C_1 C_2^T$ and $\mathcal{L}(Y_{j+1}) = \Pi(Y_j)$

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Proof:

$$X = (I + \mathcal{L}^{-1}\Pi)^{-1}\mathcal{L}^{-1}(C_1 C_2^T) = \sum_{j=0}^{\infty} (-1)^j (\mathcal{L}^{-1}\Pi)^j \mathcal{L}^{-1}(C_1 C_2^T)$$

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- Error:

$$\|X - X_N\| \leq \|\mathcal{L}^{-1}(C)\| \frac{\|\mathcal{L}^{-1}\Pi\|^{N+1}}{1 - \|\mathcal{L}^{-1}\Pi\|}$$

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Krylov method: exploiting the low rank commutation

Projection method for Sylvester equations

$$AX + XB^T = C_1 C_2^T$$

Given $\mathcal{K}_{k-1} \subset \mathcal{K}_k \subset \mathbb{R}^n$, $\mathcal{H}_{k-1} \subset \mathcal{H}_k \subset \mathbb{R}^n$ nested subspaces, the approximation is computed as the product of low-rank matrices,

$$X_k = V_k Z_k W_k^T$$

V_k and W_k are orthogonal and s.t. $\text{span}(V_k) = \mathcal{K}_k$, $\text{span}(W_k) = \mathcal{H}_k$.
 Z_k satisfy (Galerkin orth. condition)

$$\tilde{A}_k Z_k + Z_k \tilde{B}_k^T = \tilde{C}_1 \tilde{C}_2^T$$

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Our choice: $\mathcal{K}_k = \mathbf{EK}_k^\square(A, C_1)$, $\mathcal{H}_k = \mathbf{EK}_k^\square(B, C_2)$.

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Observation

There are $S_1, S_2 \in \mathbb{C}^{n \times kr}$ s.t.

$\text{span}(S_1) \subseteq \mathbf{EK}_k^\square(A, C_1)$, $\text{span}(S_2) \subseteq \mathbf{EK}_k^\square(B, C_2)$

$$X_k = S_1 S_2^T$$

Theorem: low rank commuting and Krylov spaces

Consider the generalized Sylvester equation

$$AX + XB^T + NXM^T = C_1 C_2^T$$

such that $\text{com}(A, N) = U\tilde{U}^T$ and $\text{com}(B, M) = Q\tilde{Q}^T$.

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such that $\text{com}(A, N) = U\tilde{U}^T$ and $\text{com}(B, M) = Q\tilde{Q}^T$. Let \tilde{Y}_i be the low-rank numerical solution of

$$AY_0 + Y_0 B^T = C_1 C_2^T$$

$$AY_{j+1} + Y_{j+1} B^T = N\tilde{Y}_j M^T,$$

obtained with the Extended Krylov method with k iterations.

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$$\hat{C}_1^{(N)} = [C_1, NC_1, \dots, N^N C_1, U, NU, \dots, N^{N-1} U]$$

$$\hat{C}_2^{(N)} = [C_2, MC_2, \dots, M^N C_2, Q, MQ, \dots, M^{N-1} Q]$$

Sketch/Illustration of the proof

Lemma

Assume that $A \in \mathbb{R}^{n \times n}$ is nonsingular and let $N \in \mathbb{R}^{n \times n}$ such that $\text{com}(A, N) = U\tilde{U}^T$ with $U, \tilde{U} \in \mathbb{R}^{n \times s}$. Let $C \in \mathbb{R}^{n \times r}$, then

$$N \cdot \mathbf{EK}_d^\square(A, C) \subseteq \mathbf{EK}_d^\square(A, [NC, U])$$

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Projection method for generalized Sylvester equations

$$AX + XB^T + NXM^T = C_1 C_2^T$$

Given $\mathcal{K}_{k-1} \subset \mathcal{K}_k \subset \mathbb{R}^n$, $\mathcal{H}_{k-1} \subset \mathcal{H}_k \subset \mathbb{R}^n$ nested subspaces, the approximation is computed as the product of low-rank matrices,

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Low rank numerical solutions

Low rank approximations

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Theorem [Grasedyck '04]: low rank Sylvester eq.

Let $\mathcal{L}(X) = C_1 C_2^T$. Then there exists an \bar{X} such that

$$\text{rank}(\bar{X}) \leq (2k+1)r$$

$$\|X - \bar{X}\| \leq K(\mathcal{L}) e^{-\pi\sqrt{k}}$$

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Let X_N be the matrix obtained by truncating the Neumann series. Then there exists an \bar{X}_N such that

$$\text{rank}(\bar{X}_N) \leq (2k+1)r + N(2k+1)^{N+1} m^N r$$

$$\|X_N - \bar{X}_N\| \leq K(\mathcal{L}, N) e^{-\pi\sqrt{k}}$$

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Similar result for $\Pi(X)$ low rank [Benner,Breiten '13]

Numerical experiments

MIMO: multiple input multiple output

Application: bilinear systems (stability)

$$AX + XA^T + \gamma^2(N_1 X N_1^T + N_2 X N_2^T) = CC^T$$

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$$A = \begin{pmatrix} -5 & 2 & & \\ 2 & \ddots & \ddots & \\ & \ddots & 2 & -5 \end{pmatrix} \quad N_1 = \begin{pmatrix} 0 & -3 & & \\ 3 & \ddots & \ddots & \\ & \ddots & 3 & -1 \\ & & 0 & 0 \end{pmatrix}$$

MIMO: multiple input multiple output

Application: bilinear systems (stability)

$$AX + XA^T + \gamma^2(N_1 X N_1^T + N_2 X N_2^T) = CC^T$$

- $\gamma > 0$ small
-

$$A = \begin{pmatrix} -5 & 2 & & \\ 2 & \ddots & \ddots & \\ & \ddots & 2 & -5 \end{pmatrix} \quad N_1 = \begin{pmatrix} 0 & -3 & & \\ 3 & \ddots & \ddots & \\ & \ddots & 3 & -1 \\ & & 0 & 0 \end{pmatrix}$$

- $N_2 = -N_1 + I$

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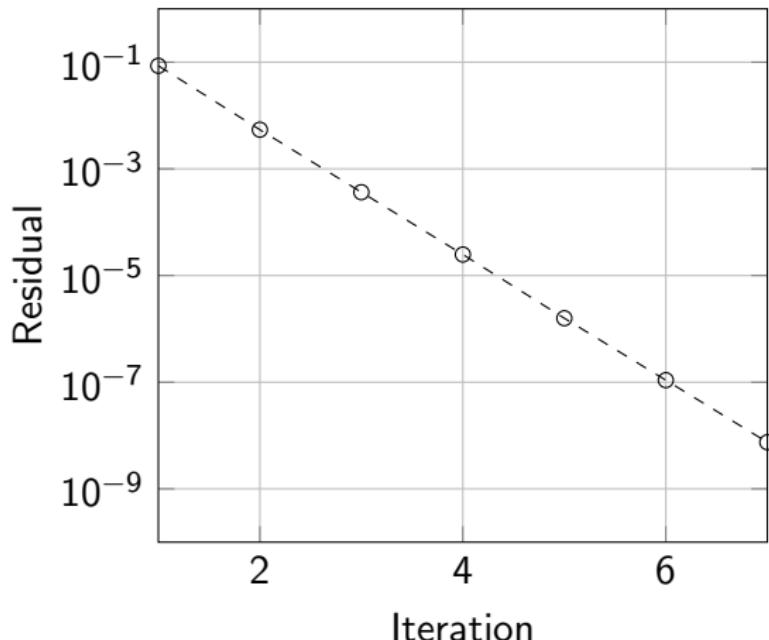
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- $N_2 = -N_1 + I$
- $\text{com}(A, N_1) = -\text{com}(A, N_2) = 12[e_1, e_n][e_1, -e_n]^T$
- $\mathbf{EK}_d^\square(A, [C, N_1 C, [e_1, e_n]])$

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MIMO: comparison with other methods

	γ	Its.	Memory	rank(X)	Lin. solves
Ext. Krylov (low rank-comm)	1/6	8	7.32MB	64	48
BilADI ¹ (4 Wach. shifts)	1/6	15	5.18MB	68	591
BilADI (8 \mathcal{H}_2 -opt. shifts)	1/6	14	5.18MB	68	522
GLEK ²	1/6	13	16.78MB	52	1549
Ext. Krylov (low rank-comm)	1/5	8	7.32MB	72	48
BilADI (4 Wach. shifts)	1/5	20	5.95MB	78	990
BilADI (8 \mathcal{H}_2 -opt. shifts)	1/5	20	5.95MB	78	987
GLEK	1/5	17	20.30MB	59	2309
Ext. Krylov (low rank-comm)	1/4	10	9.16MB	89	60
BilADI (4 Wach. shifts)	1/4	30	7.25MB	95	1978
BilADI (8 \mathcal{H}_2 -opt. shifts)	1/4	33	7.25MB	95	2269
GLEK	1/4	30	33.42MB	118	5330

¹[Benner,Breiten '13]

²[Shank,Simoncini,Szyld '16]

Poisson problem: generalized Sylvester equation

Poisson–Chi problem

$$\Delta u + \chi u = f$$

$$(x, y) \in [0, 1] \times \mathbb{R}$$

$$u(x, 0) = u(x, 1) = 0$$

homogeneous Dirichlet b.c.

$$u(x, y + 1) = u(x, y)$$

periodic b.c.

- f : source term (separable function)
-

$$\chi(x, y) = \begin{cases} 1 & x, y > 1/2 \\ 0 & \text{otherwise} \end{cases}$$

Poisson problem: generalized Sylvester equation

Poisson–Chi problem

$$\Delta u + \chi u = f$$

$$(x, y) \in [0, 1] \times \mathbb{R}$$

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homogeneous Dirichlet b.c.

$$u(x, y + 1) = u(x, y)$$

periodic b.c.

Discretization

$$AX + XB^T + DXD^T = C_1 C_2^T$$

- A : Circulant tridiagonal with elements $n^2(1, -2, 1)$
- B : Toeplitz tridiagonal with elements $n^2(1, -2, 1)$
- C_1, C_2 low rank, $D = \begin{pmatrix} 0 & 0 \\ 0 & I \end{pmatrix}$

Poisson problem: generalized Sylvester equation

Poisson–Chi: Sylvester equation

$$AX + XB^T + DXD^T = C_1 C_2^T$$

Properties

- $AD = DA + v_1 w_1^T - w_1 v_1^T - v_2 w_2^T + w_2 v_2^T$
- $BD = DB + v_1 w_1^T - w_1 v_1^T$
- $D^2 = D$
- A : singular

Let $U = [v_1, v_2, w_1, w_2]$ and $Q = [v_1, w_1]$ then

$$\mathcal{K}_d = \mathbf{EK}_d^\square(A, [C_1, DC_1, \dots, D^N C_1, U, N, \dots, D^{N-1} U])$$

$$\mathcal{H}_d = \mathbf{EK}_d^\square(B, [C_2, DC_2, \dots, D^N C_2, Q, DQ, \dots, D^{N-1} Q])$$

Poisson problem: generalized Sylvester equation

Poisson–Chi: Sylvester equation

$$AX + XB^T + DXD^T = C_1 C_2^T$$

Properties

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Poisson problem: generalized Sylvester equation

Poisson–Chi: Sylvester equation

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but A is singular...

Poisson problem: generalized Sylvester equation

Poisson–Chi: Sylvester equation

$$(A + I)X + XB^T + DXD^T - X = C_1 C_2^T$$

Properties

- $AD = DA + v_1 w_1^T - w_1 v_1^T - v_2 w_2^T + w_2 v_2^T$
- $BD = DB + v_1 w_1^T - w_1 v_1^T$
- $D^2 = D$
- A : singular

Let $U = [v_1, v_2, w_1, w_2]$ and $Q = [v_1, w_1]$ then

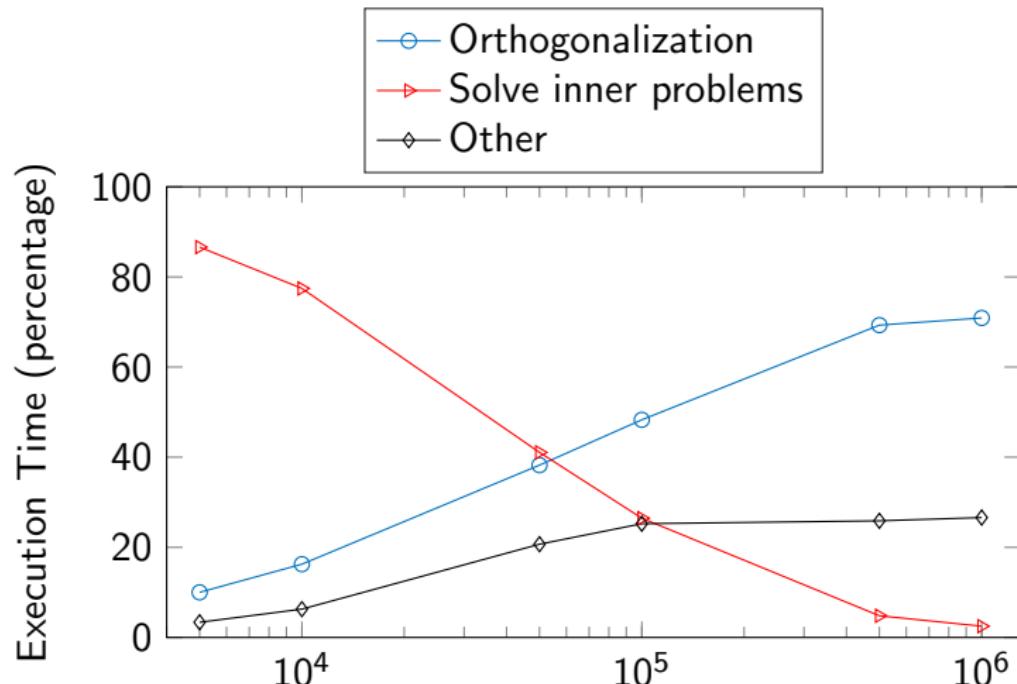
$$\mathcal{K}_d = \mathbf{EK}_d^\square(A + I, [C_1, DC_1, U, DU])$$

$$\mathcal{H}_d = \mathbf{EK}_d^\square(B, [C_2, DC_2, Q, DQ])$$

Poisson problem: generalized Sylvester equation

Poisson–Chi: Sylvester equation (shifted)

$$(A + I)X + XB^T + DXD^T - X = C_1 C_2^T$$



Conclusion

Scientific contributions:

- ☞ New low rank method for generalized Sylvester equations
- ☞ Structured exploitation for Extended Krylov method
- ☞ Characterization of the low rank numerical solutions

Future of this project:

- Preprint available soon