



KUNGL
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Inte
Master Pr

in System-on-Chip Design

L7b: Rule-based optimization

Reading material

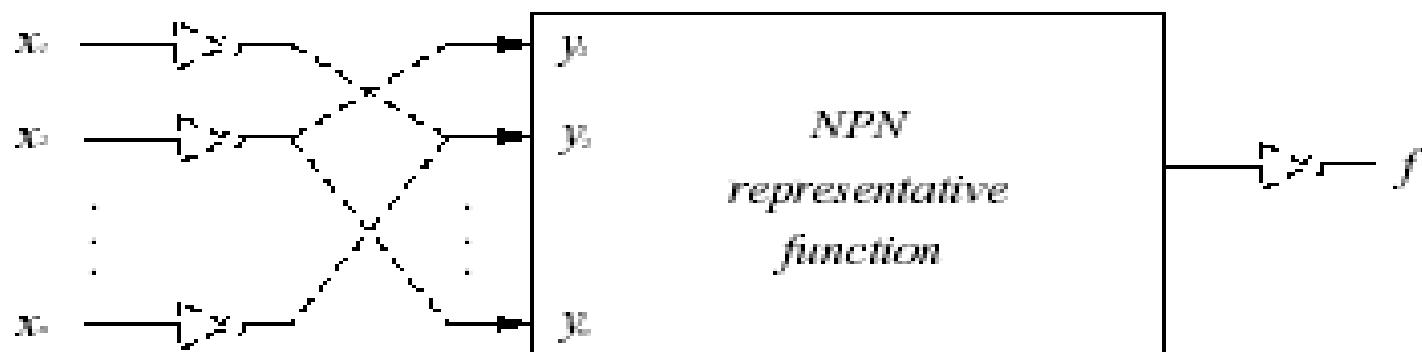
- **Fast multi-level logic optimization using local transformations**, P. Farm, E. Dubrova, *Notes of International Workshop on Logic Synthesis*, May 2003, pp. 120-126.
- **Integrated Logic Synthesis Using Simulated Annealing**, P. Farm, E. Dubrova, A. Kuehlmann), *Notes of International Workshop on Logic Synthesis*, June 7-9, 2006, Vail, Colorado, USA.

Main Idea

- The circuit is optimized by step-wise refinement
- Local transformations based on a set of replacement rules are applied at each step
- The replacement rules are generated with the help of NPN (**N**egation-**P**ermutation-**N**egation) classes of Boolean functions
- The objective is to minimize the number of gates in the circuit

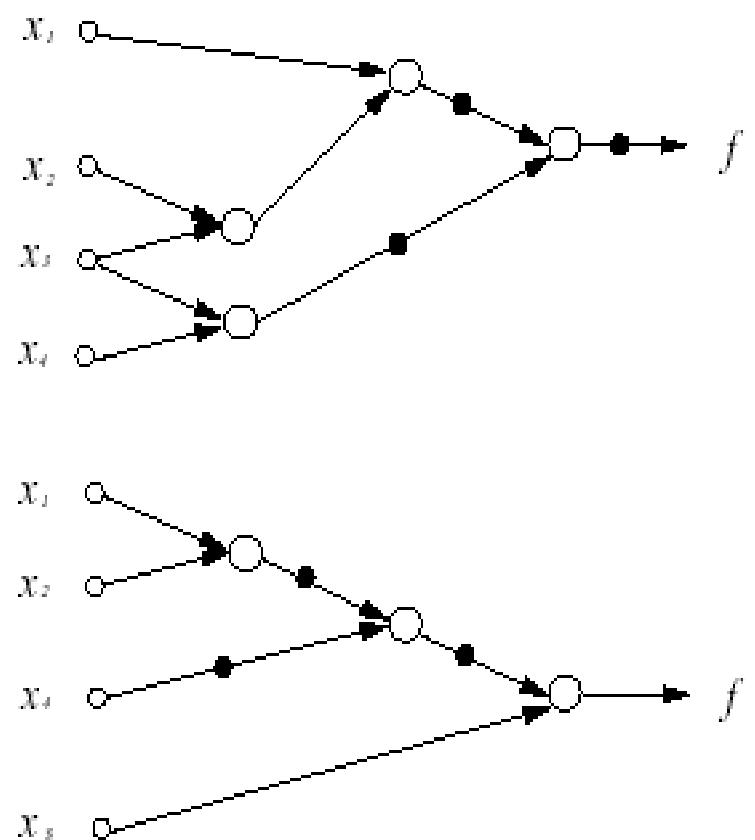
NPN classes

- Each NPN class consists of all functions which differ by:
 - Negation of some input variables x_1, \dots, x_n and/or,
 - Permutation of some input variables x_1, \dots, x_n and/or,
 - Negation of the function output



Replacement rules

- Functions belonging to the same NPN class have a minimum AND/INVERTER graph of the same size.
- Rules on how to transform a non-minimum graph to a minimum need to be defined
- Rules for removing redundancies also need to be defined



Rules are derived from axioms and properties of Boolean algebra

A3: $\forall a,b,c \in B, a \cdot (b+c) = a \cdot b + a \cdot c,$
 $a + b \cdot c = (a+b) \cdot (a+c)$

A4: $\forall a \in B, a \cdot 1 = a, a + 0 = a$

A5: $\forall a \in B, a \cdot a' = 0, a + a' = 1$

P1: $\forall a \in B, (a')' = a$

P2: $\forall a,b,c \in B, a \cdot (b \cdot c) = (a \cdot b) \cdot c, (a + b) + c = a + (b + c)$

P3: $\forall a \in B, a \cdot 0 = 0, a + 1 = 1$

P5: $\forall a,b \in B, a \cdot (a+b) = a, a + a \cdot b = a$

P6: $\forall a \in B, a \cdot a = a, a + a = a$

Completeness of rules

- By using axioms Boolean algebra, we can derive any Boolean expression representing a given Boolean function
- Therefore, by applying them as rules, we can obtain any circuit for any circuit implementing the same function
- Consequently, we can find a minimal circuit starting from any circuit if we search long enough

Simulated Annealing Algorithm

- The order of applying rules can be controlled by a simulated annealing algorithm
- A *cost* function assigns a cost to each state s of the search space S
- The set of *neighbours* is the set of states which can be obtained from $s \in S$ by a single move
- Two functions are assigned to states:
 - Selection probability
 - Acceptance probability

Simulated Annealing, cont

- Let S be a set of all possible combinational acyclic Boolean circuits implementing a Boolean function f
- At each step, the annealing algorithm considers some neighbor $s' \in S$ of the current state $s \in S$, and probabilistically decides between moving to state s' or staying in state s'
- The probabilities are selected so that the system ultimately tends to move to state the lower cost

Neighbours

- In our case, the neighbours of a state s are the states which can be obtained from s by applying one of the rules listed on p. 7
- There are also a rules which is related specifically to circuits:
 - Two isomorphic vertices can be merged into one
 - A vertex with a multiple fan-out can be divided into two vertices

Pseudo-code of annealing algorithm

```
algorithm ANNEALING( $c_1, \varepsilon$ );  
     $best\_c = c_1$ ;  
     $best\_cost = \varepsilon(c_1)$ ;  
     $(t_b, t_e, \Delta t, N\_of\_moves) = \text{INITIALIZE}(c_1, \varepsilon)$ ;  
     $t = t_b$ ;  
    while  $t > t_e$  do  
        for  $N\_of\_moves$  do  
             $c_2 = \text{SELECT}(c_1)$ ;  
            if  $\text{ACCEPT}(\varepsilon(c_1), \varepsilon(c_2), t)$  then  
                 $c_1 = c_2$ ;  
                 $cost = \varepsilon(c_2)$ ;  
                if  $cost < best\_cost$  then  
                     $best\_c = c_1$ ;  
                     $best\_cost = cost$ ;  
             $t = t - \Delta t$ ;  
end
```

The annealing schedule

- As the simulation proceeds, the temperature t is gradually reduced
 - Initially, t is set to a high value
 - Then, it is decreased at each step according to some annealing schedule
 - Finally, it becomes 0
- In the way, the system is expected to initially explore a broad region of the search space containing good solutions
- Then, it narrows and at $t = 0$ moves downhill

Convergence to optimum

- If the annealing process is scheduled correctly, it converges to optimum solution asymptotically
- In general, annealing can smoothly trade-off complex, multi-dimensional objective functions
 - Area, delay, power, etc.