Some Heuristics For Mathematical Crack Growth

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Given a boundary value problem (possibly some Euler-Lagrange equations)

$$PDE(x, t, u, \nabla u, D^2 u) = f(x, t)$$
 for $x \in D$
 $u(x, t) = g(x, t)$ on ∂D .

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Find and describe a given set (implicitly) defined by the solution, for instance a level set.

The Dirichet problem: Minimize

$$\int_{D} |\nabla u(x)|^2 dx \tag{1}$$

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among all functions $u \in W^{1,2}(D)$ such that u = g on ∂D .

The Obstacle Problem: Minimize (1) under the extra condition that

$$u(x) \ge \phi(x)$$
 for a.e. $x \in D$,

where ϕ is a given obstacle (say i $C^2(D)$) such that $\phi(x) \leq g(x)$ on ∂D .

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Six reasons why:

1. Mathematical curiosity

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- 2. For instance: hat making
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- 4. What about Riemann?
- 5. Gives me access to grants.
- 6. You are naive!

We will study a play version of Griffith's crack growth: Given a domain (reference body) $D \subset \mathbb{R}^3$ and boundary data $\mathbf{g}(x, t)$ find a pair $(\mathbf{u}, \Omega(t))$, \mathbf{u} is a function and $\Omega(t)$ a "2–dimensional set" such that:

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- ► $\mathbf{u}(\cdot, t) \in W^{1,2}(D \setminus \Omega(t)),$
- $\mathbf{u}(x,t) = \mathbf{g}(x,t)$ on ∂D ,
- $\Omega(s) \subset \Omega(t)$ for $s \leq t$,

► *F* is some given (convex, smooth, et.c.) function.

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Don't worry, we will simplify this!

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- Scalar problems: Consider u to be a scalar valued function u.Still problems.
- Restrained ("no curvature") problem: Assume that Ω is contained in a given set. Not as many problems!

Let $D = B_1^+(0) \in \mathbb{R}^3$ and g(x, t) be given boundary data. Minimize, for each $t \ge 0$,

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$$\Omega(t) \subset \{x; x_3 = 0\}$$
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- $\Omega(s) \subset \Omega(t)$ for $s \leq t$
- $u(x,t) = g(x,t) \text{ om } (\partial B_1^+(0))$
- $u(x_1, x_2, 0, t) = 0$ for $(x_1, x_2, 0) \notin \Omega(t)$.

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In particular we would want to find some sort of "Euler-Lagrange equations" for how the speed of $\Gamma(t)$ is determined by g(x, t) and $\Omega(t)$.

Problems:

The free boundary Γ(t) does appear explicitly in the minimization problem.

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- To describe the evolution of Γ(t) we would want to calculate the velocity in the normal direction η. But the normal is not apriori defined.
- "Jumps" in the crack growth.

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- 3. Showing that Γ is C^1 a.e. by integral equations.
- 4. Regularity makes it possible to attack the problem by classical calculus. (More or less.)
- 5. Discuss some issues/open questions.

Growth of solutions - a heuristic proof.

Theorem

If (u, Ω) is a minimizer of

$$\int_{D\setminus\Omega(t)}|\nabla u(x)|^2dx+\mathcal{H}^2(\Omega(t))$$

and $0\in\Gamma$ then

$$c \leq rac{\|u\|_{L^2(B^+_r(0))}}{r^{rac{n+1}{2}}} \sim rac{\|
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Consequences:

1. Better growth estimates around free boundary points.

$$u(x) = \sqrt{\frac{2}{\pi}} r^{1/2} \sin\left(\frac{\varphi}{2}\right) + o(r^{1/2})$$

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2. The measure
$$\mu = \sqrt{\frac{2}{\pi}} \mathcal{H}^1 \big|_{\Gamma}$$
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Theorem

If the normal $\eta(x)$ is well defined for some $x \in \Gamma$ then there exists a small neighbourhood, $B_r(x)$, of x such that the free boundary $\Gamma \cap B_r(x)$ is smooth.



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Consequences: This is a regularity result bit it allows us to differentiate the solution i a rigorous way which implies that we can derive the growth equations rigorously in many cases.

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- 2. $\nu(x) = 0$ when $c(x) \le \sqrt{\frac{2}{\pi}}$
- 3. whenever $\nu(x) > 0$

$$\int_{\Gamma(t)} \nu(y) \mathcal{K}(x,y) d\mathcal{H}^1(y) = \mathcal{R}(x) - \frac{3c_{3/2}(x)}{2}\nu(x)$$

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4. when
$$c_{1/2} = \sqrt{\frac{2}{\pi}}$$
 and $\nu(x) = 0$



Behavior at singular points.





Behaviour at boundary points.





Behaviour at boundary points.



