

# Outline of Part IV

- Games and equilibria
- Nash dynamics
- Fictitious play
- No-regret dynamics
- Trail and error learning

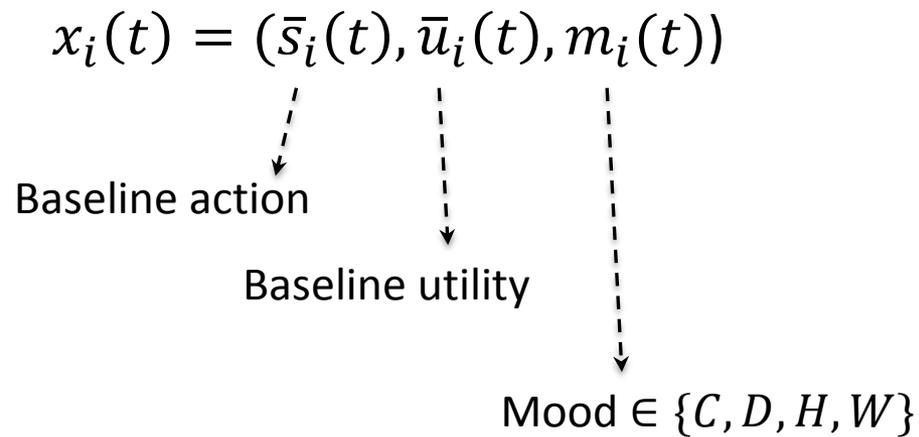
# Learning by trials and errors (Young, 2008)

# Algorithm

- **Marden et al.:** experiment rarely, and compare with the average payoff received over long periods. Adopt the new action when it leads to significantly better payoff.
  - Work for weakly acyclic games (convergence to NEs)
- New idea: experimentations triggered by decreases in payoffs
  - Convergence to NEs in games where a pure NE exists
  - Proof of convergence: uses Freidlin-Wentzell perturbation theory
  - Hereafter, synchronous moves

# Algorithm

**Idea:** enrich the *state* of agent



# Algorithm: content

At the beginning of each time period  $t$ : if  $m_i(t) = C$

- Play benchmark action w.p.  $1-\epsilon$ 
  - If  $u_i(a) > \bar{u}_i$ , become hopeful
  - If  $u_i(a) = \bar{u}_i$ , be content
  - If  $u_i(a) < \bar{u}_i$ , become watchful
- Explore and play  $a_i$  randomly chosen
  - If  $u_i(a) > \bar{u}_i$ , adopt  $a_i$  and update your benchmarks
  - If  $u_i(a) \leq \bar{u}_i$ , don't change anything

# Algorithm: watchful

At the beginning of each time period  $t$ : if  $m_i(t) = W$ , play benchmark action

- If  $u_i(a) > \bar{u}_i$ , become hopeful
- If  $u_i(a) = \bar{u}_i$ , be content
- If  $u_i(a) < \bar{u}_i$ , become discontent

Don't change the benchmarks

# Algorithm: hopeful

At the beginning of each time period  $t$ : if  $m_i(t) = H$ , play benchmark action

- If  $u_i(a) > \bar{u}_i$ , become content, update  $\bar{u}_i = u_i(a)$
- If  $u_i(a) = \bar{u}_i$ , become content
- If  $u_i(a) < \bar{u}_i$ , become watchful

# Algorithm: discontent

At the beginning of each time period  $t$ : if  $m_i(t) = D$ , play a random action  $a_i$

- Become content; adopt the new action and update the benchmarks with probability  $\phi(u_i(a), \bar{u}_i)$
- Remain discontent with probability  $1 - \phi(u_i(a), \bar{u}_i)$

# Convergence

- Assume that the game has at least one pure NE, and denote by  $\Omega^*$  the set of pure NEs.

**Theorem** *For any  $\delta > 0$ , there exists  $\epsilon$  such that:*

$$\liminf_{t \rightarrow \infty} \frac{1}{t} \sum_{i=0}^{t-1} 1_{\{s(i) \in \Omega^*\}} \geq 1 - \delta$$

# Perturbed Markov chains

Idea from **Young**, *The evolution of conventions*, *Econometrica* 1993

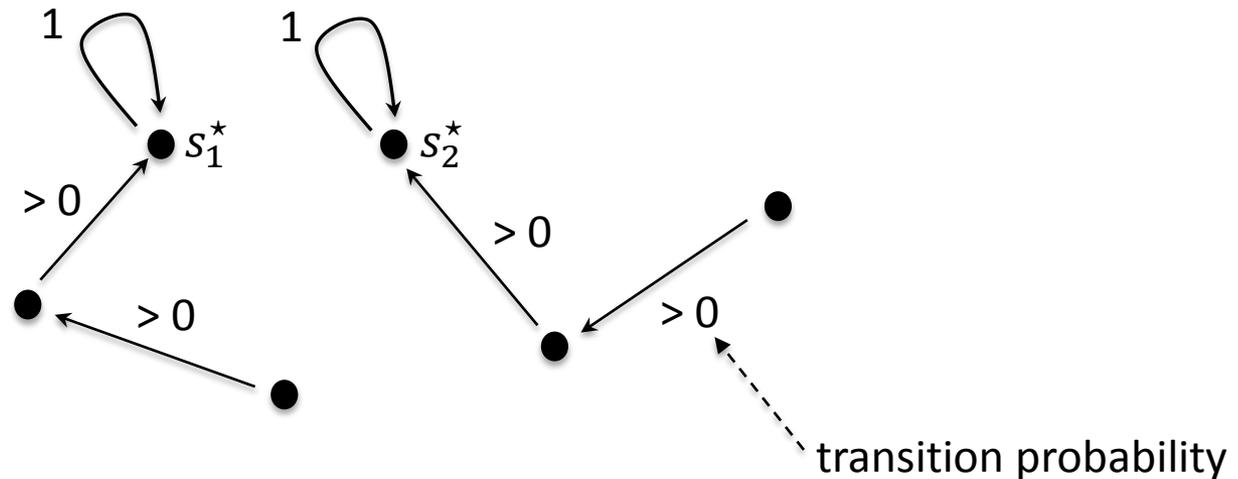
**Step 1.** Construct a Markov chain absorbed in states maximizing social welfare

**Step 2.** Perturb the Markov chain to achieve irreducibility

**Step 3.** Show that in steady-state, the perturbed Markov chain concentrates on socially optimal states

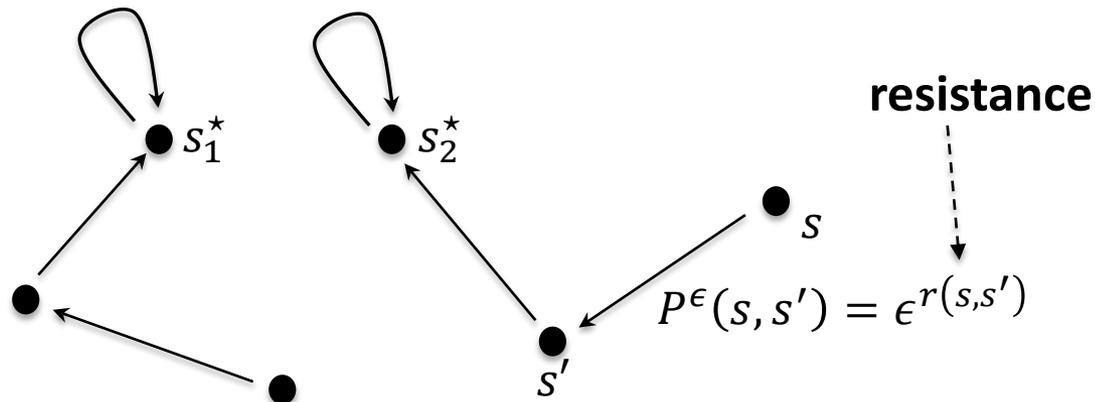
# Transient Markov chain

Let  $\Omega^*$  be the set of socially optimal states.



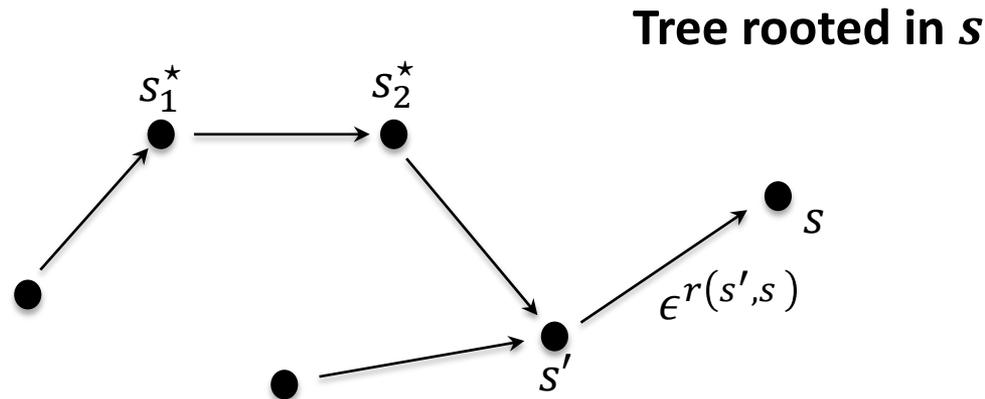
# Resistance, rooted trees, potential

Step 2. Irreducible perturbed Markov chain



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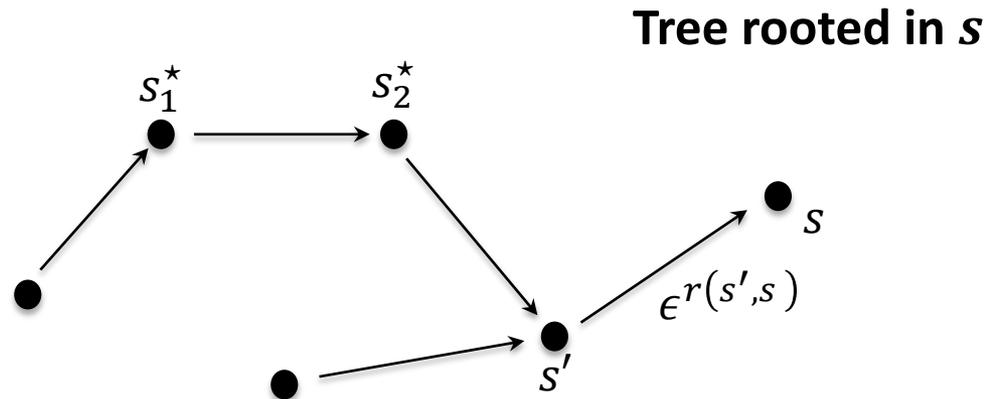


Steady-state distribution: 
$$\pi^\epsilon(s) \sim \sum_{T \in \text{Tree}_s} \epsilon^{\sum_{(s_1, s_2) \in T} r(s_1, s_2)}$$

**Potential of  $s$ :** 
$$\gamma(s) = \min_{T \in \text{Tree}_s} \sum_{(s_1, s_2) \in T} r(s_1, s_2)$$

# Resistance, rooted trees, potential

**Lemma** *When  $\epsilon \rightarrow 0$ ,  $\pi^\epsilon$  concentrates on states with minimal potential.*



Steady-state distribution:

$$\pi^\epsilon(s) \sim \sum_{T \in \text{Tree}_s} \epsilon^{\sum_{(s_1, s_2) \in T} r(s_1, s_2)}$$

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