

## **Introduction to Model Order Reduction**

Ph.D. course, 7.0 credits

In engineering and science it is often desirable to use the simplest possible mathematical model that "does the job". First-principles modeling or system identification commonly result in unnecessarily high-dimensional mathematical models. Model (order) reduction concerns systematic approximation of such models. There are many advantages of working with models with a low-dimensional state space. For example, low-dimensional models are easier to analyze and much faster to simulate. Model reduction methods have successfully been used to solve large-scale problems in areas such as control engineering, signal processing, image compression, fluid mechanics, and power systems. In this Ph.D. course, we give an introduction to some powerful available reduction techniques, as well as to the required underlying mathematics.

Course webpage: <a href="http://people.kth.se/~hsan/modred.htm">http://people.kth.se/~hsan/modred.htm</a>

## Course goals

After finishing the course, the Ph.D. student will

- be able to distinguish between difficult and simple model reduction problems:
- have a thorough understanding of Principle Component Analysis (PCA)/Singular Value Decomposition (SVD);
- understand the interplay between linear operators on Hilbert spaces, controllability, observability, and model reduction;
- · know the theory behind balanced truncation and Hankel norm approximation;
- know how convex optimization and Linear Matrix Inequalities (LMIs) can be used to solve model reduction problems;
- know the basics of the behavioral modeling approach and dissipative systems theory; and
- be able to reduce systems while preserving dissipativity properties, and reduce linear feedback controllers while taking the overall system performance into account.

## Instructors

Henrik Sandberg (course responsible), KTH Automatic Control Lab (hsan@kth.se)

Bart Besselink, KTH Automatic Control Lab (bart.besselink@ee.kth.se)

Madhu N. Belur, Department of Electrical Engineering, IIT Bombay (belur@ee.iitb.ac.in)

# **Prerequisites**

Basic linear systems theory (state-space realizations, Laplace transforms etc.), matrix theory, and basic MATLAB-programming.

## Grading

Grade (pass/fail) is based turn-in exercises (50%) and written exam (50%).

### Exercises

- Exercises handed out with each lecture.
- At the end of the course, at least 75% of the exercises should have been solved and turned in on time.
- Exercises for Lectures 1-4 due April 17.
- Exercises for Lectures 5-8 due May 12.

### Exam

- A 24h take-home exam.
- You decide when to take it, but it should be completed at the latest 3 months after course ends.
- No cooperation allowed.
- Problems similar to exercises.

### Course literature

Research papers and parts of the books

- Antoulas, A.C., "Approximation of Large-Scale Dynamical Systems", Society for Industrial and Applied Mathematics, 2005.
- Obinata, G. and Anderson, B.D.O., "Model Reduction for Control System Design", Springer-Verlag, London, 2001.
- Luenberger, D.G., "Optimization by Vector Space Methods", Wiley, 1969.
- Green, M. and Limebeer, D.J.N, "Linear Robust Control", Dover, 2012.
- Doyle, J.C., Francis, B., and Tannenbaum, A., "Feedback Control Theory", Macmillan Publishing Co., 1990.

# Program (dates and times subject to change)

Date	Time	Event	Room	Lecturer	Topic
2014-03-	13:15-	Lecture			Introduction. The model reduction problem.
31	15:00	1	Q13	HS	introduction. The model reduction problem.
2014-04-	13:15-	Lecture			
02	15:00	2	L41	HS	Model truncation, singular perturbation.
2014-04-	10:15-	Exercise			Review of linear systems and Hilbert spaces
04	12:00	1	Q24	HS	etc.
2014-04-	13:15-	Lecture			POD/PCA/SVD-based reduction.
07	15:00	3	Q24	BB	FOD/FCA/3VD-based reduction.
2014-04-	13:15-	Lecture			Gramians and balanced realizations.
09	15:00	4	Q24	BB	Grannans and balanced realizations.
2014-04-	13:15-	Exercise			
24	15:00	2	Q24	HS/BB	Exercises due April 17
2014-04-	13:15-	Lecture			Balanced truncation and weighted
25	15:00	5	Q24	BB	extensions.
2014-04-	10:15-	Lecture			Controller reduction and linear matrix
28	12:00	6	Q24	BB	inequalities (LMIs).
2014-05-	10:15-	Lecture			Optimal model order reduction in the Hankel
05	12:00	7	Q13	HS	norm.
2014-05-	15:15-	Lecture			Optimal model order reduction in the H2/H-
07	17:00	8	Q24	HS	infinity norms.
2014-05-	10:15-	Lecture			Behavioral approach, kernel representations
09	12:00	9	Q13	MB	Benavioral approach, kerner representations
2014-05-	13:15-	Lecture			Controllability, passivity, dissipativity,
12	15:00	10	Q13	MB	storage functions
2014-05-	10:15-	Lecture			Maximum and minimum storage functions
14	12:00	11	Q24	MB	Waximum and minimum storage functions
2014-05-	10:15-	Exercise			
16	12:00	3	Q13	HS/BB	Exercises due May 12
2014-05-	13:15-	Lecture			The LQ problem, H-infinity-norm as
19	15:00	12	Q13	MB	dissipativity
2014-05-	10:15-	Lecture			Passivity preserving model reduction
21	12:00	13	L41	MB	r assivity preserving model reduction
2014-05-	10:15-	Lecture			
26	12:00	14	Q13	MB	Dissipativity preserving model reduction
2014-05-	10:15-	Exercise			
28	12:00	4	M24	MB	