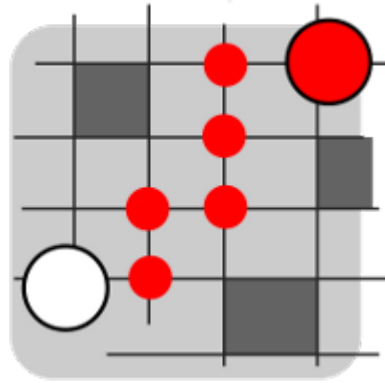


# Mobility Collector



Battery Conscious Mobile Tracking

**Adrian C. Prelipcean**, Győző Gidófalvi  
Geoinformatics, Royal Institute of Technology KTH, Sweden



ROYAL INSTITUTE  
OF TECHNOLOGY

# Outline

Location tracking

Current technological status

**Mobility Collector** - a mobile tracking platform

**Spatial** and **temporal granularity** in location-dependant data

**Robust data**  
linking spatial with physical movement

Usability of **Mobility Collector**

# Location Tracking

There is a need for **location awareness**:

a) Multi-user systems

- Studying **behavior** and **movement**
- **Extrapolating** information (prediction)

b) Single-user systems

- **Ubiquitous** (pervasive) computing
- Studying and understanding the user's **context**
- Aiding the user in **decision making**

# Tech status for location tracking

The industry's focus is on **purpose-oriented** apps

Research development is not a priority

The location listening service is **acontextual**

Temporal granularity has precedence over the spatial one

Multiple API's, different software implementation and ambiguous documentation

# Mobility Collector

A **highly configurable** tracking platform for Android devices (Android 2.0 and higher)

Research oriented and **open-source**

Equidistant and equitime **tracking options**

Contextual **battery preserving** algorithm

Configurable point- and period-based **annotations**

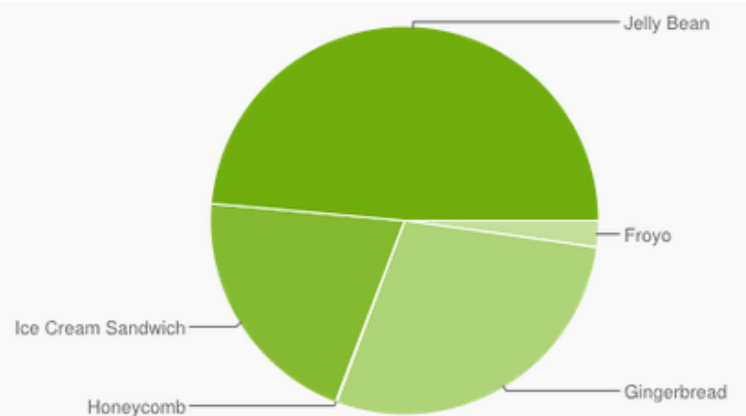
# Why Android?

## Open-source

Offers hardware and software diversity

**Mobility Collector** - minimum API 5

Version	Codename	API	Distribution
2.2	Froyo	8	2.2%
2.3.3 - 2.3.7	Gingerbread	10	28.5%
3.2	Honeycomb	13	0.1%
4.0.3 - 4.0.4	Ice Cream Sandwich	15	20.6%
4.1.x	Jelly Bean	16	36.5%
4.2.x		17	10.6%
4.3		18	1.5%



# **Tracking algorithms**

Equitime and Equidistant tracking

# Tracking parameters

## Parameters

**Sampling time** - the frequency at which the location listener will try to obtain a fix

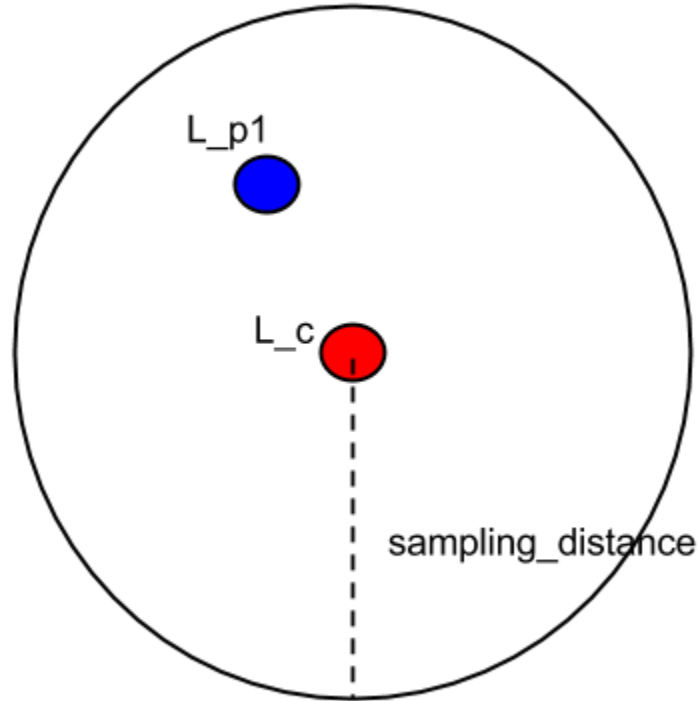
**Sampling distance** - the clustering constraint which prevents locations to be broadcasted if they are within a certain distance of the last fix



# Equitime tracking

Time:  $T_c + 30$  seconds

$L_p(1)$  gets  
broadcasted



$L_p$  - potential  
location

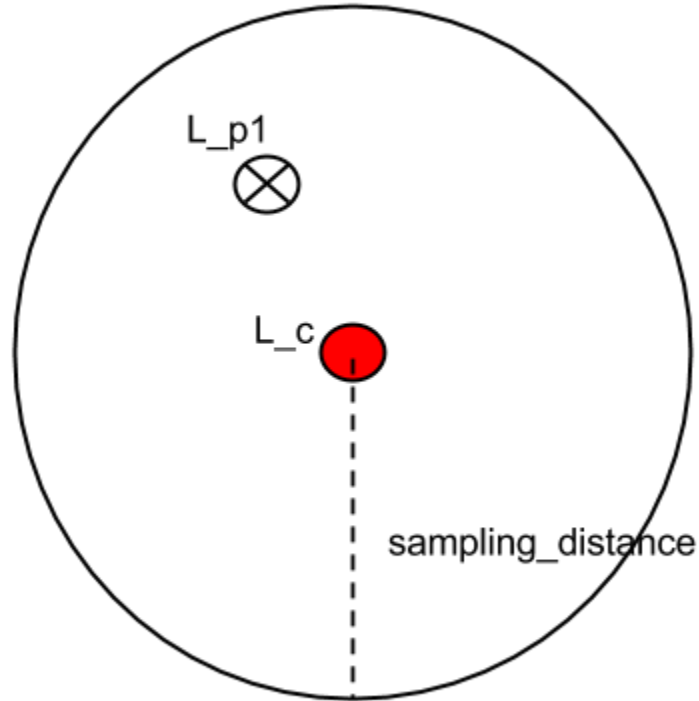
$L_c$  - current  
location

# Equitime tracking

Time:  $T_c + 30$  seconds

$L_p(1)$  gets  
broadcasted

$L_p(1)$  **fails** the  
clustering filter



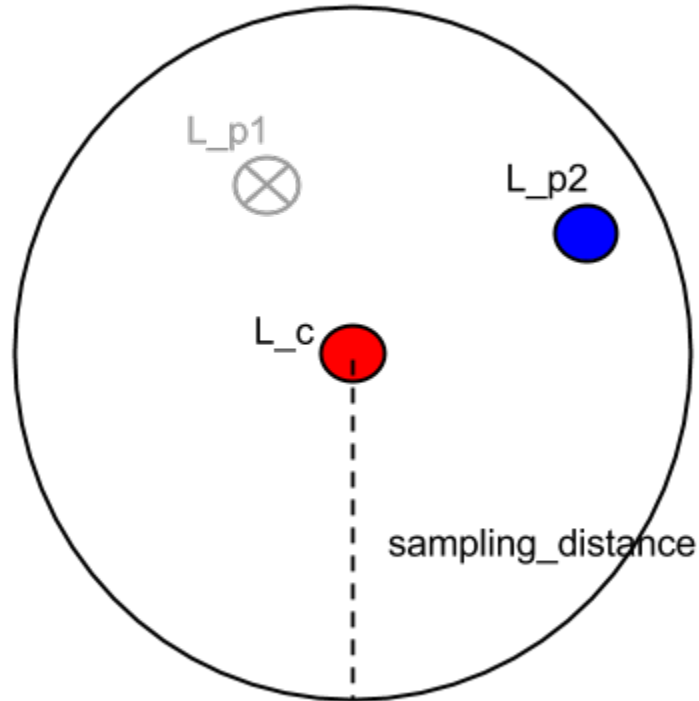
$L_p$  - potential  
location

$L_c$  - current  
location

# Equitime tracking

Time:  $T_c + 1 \text{ min}$

$L_p(2)$  gets  
broadcasted



$L_p$  - potential  
location

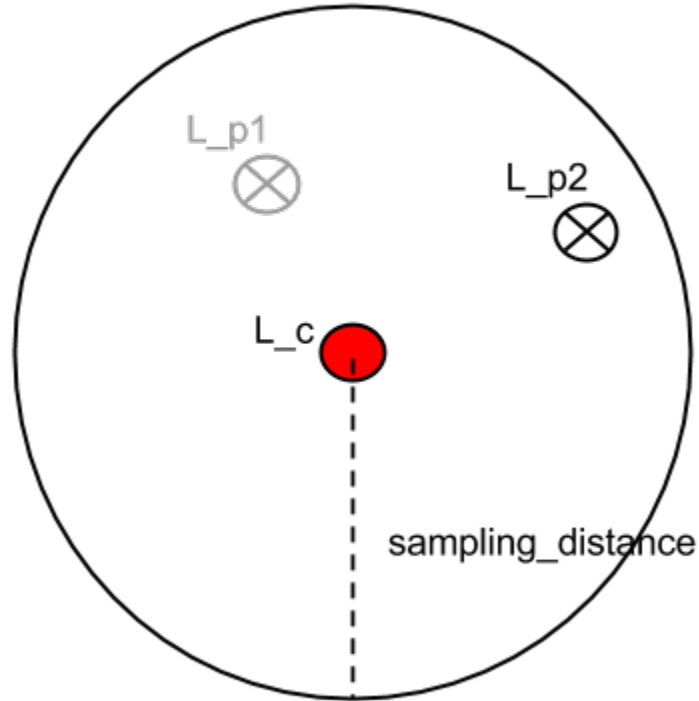
$L_c$  - current  
location

# Equitime tracking

Time:  $T_c + 1 \text{ min}$

$L_p(2)$  gets  
broadcasted

$L_p(2)$  **fails** the  
clustering filter



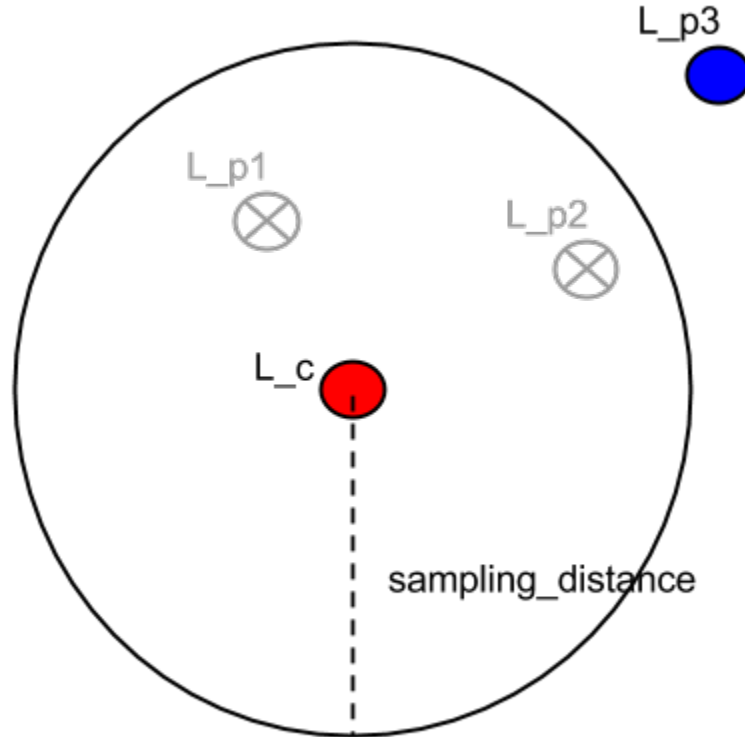
$L_p$  - potential  
location

$L_c$  - current  
location

# Equitime tracking

Time:  $T_c + 1.5 \text{ min}$

$L_p(3)$  gets  
broadcasted



$L_p$  - potential  
location

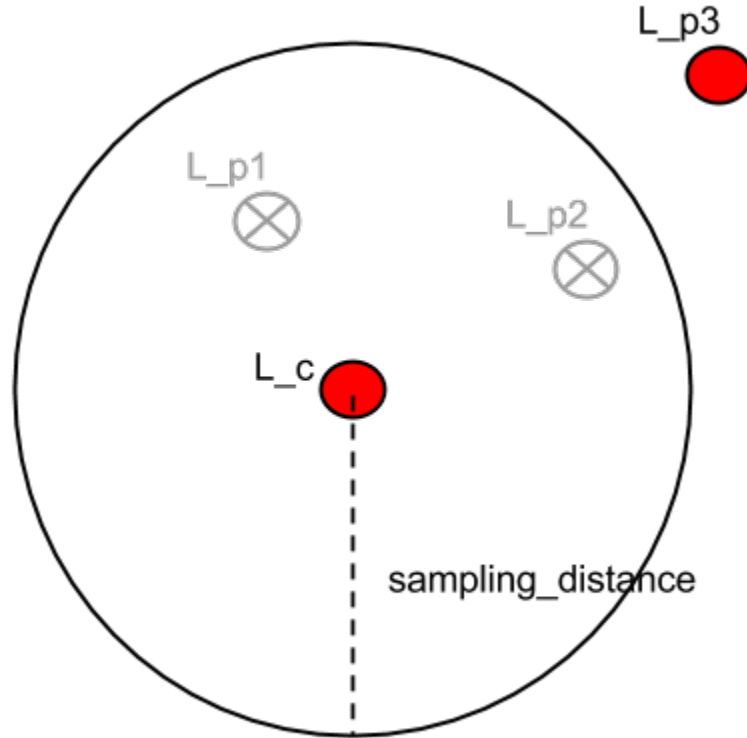
$L_c$  - current  
location

# Equitime tracking

Time:  $T_c + 1.5 \text{ min}$

$L_p(3)$  gets  
broadcasted

$L_p(3)$  **passes** the  
clustering filter



$L_p$  - potential  
location

$L_c$  - current  
location

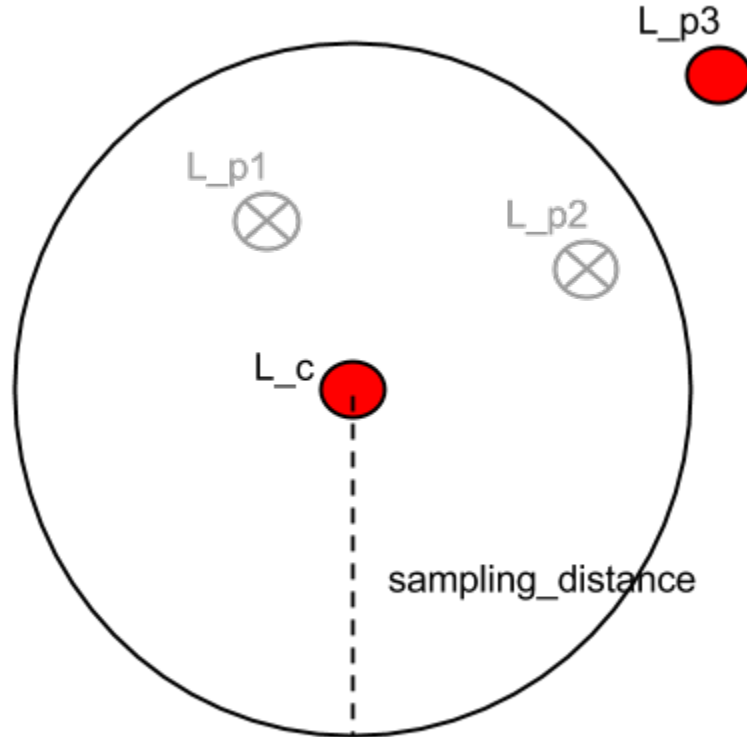
# Equitime tracking

Time:  $T_c + 1.5 \text{ min}$

$L_p(3)$  gets  
broadcasted

$L_p(3)$  **passes** the  
clustering filter

$L_p(3)$  gets **sent** to  
the programming  
interface



$L_p$  - potential  
location

$L_c$  - current  
location

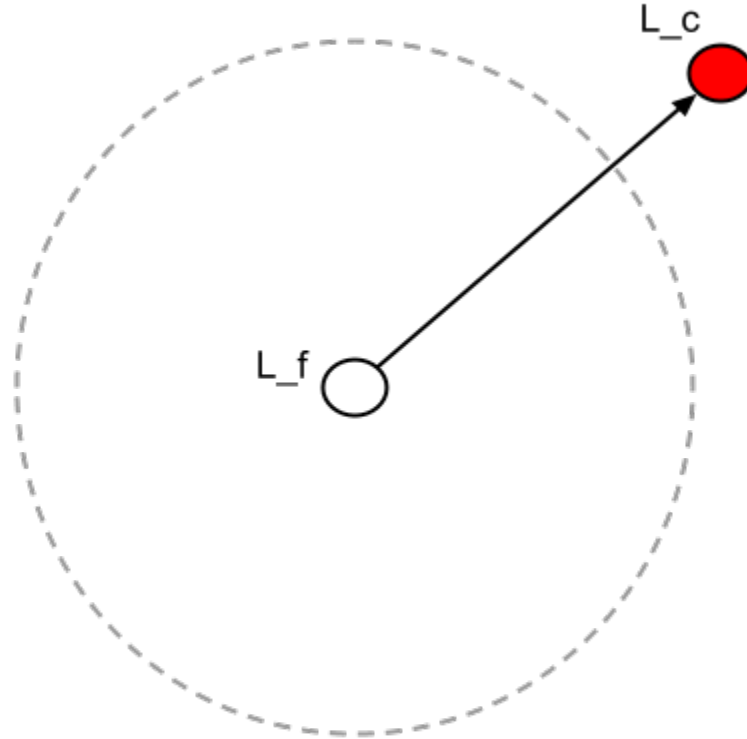
# Equitime tracking

Time:  $T_c + 1.5 \text{ min}$

$L_p(3)$  gets  
broadcasted

$L_p(3)$  **passes** the  
clustering filter

$L_p(3)$  **becomes**  
the reference for  
future fixes



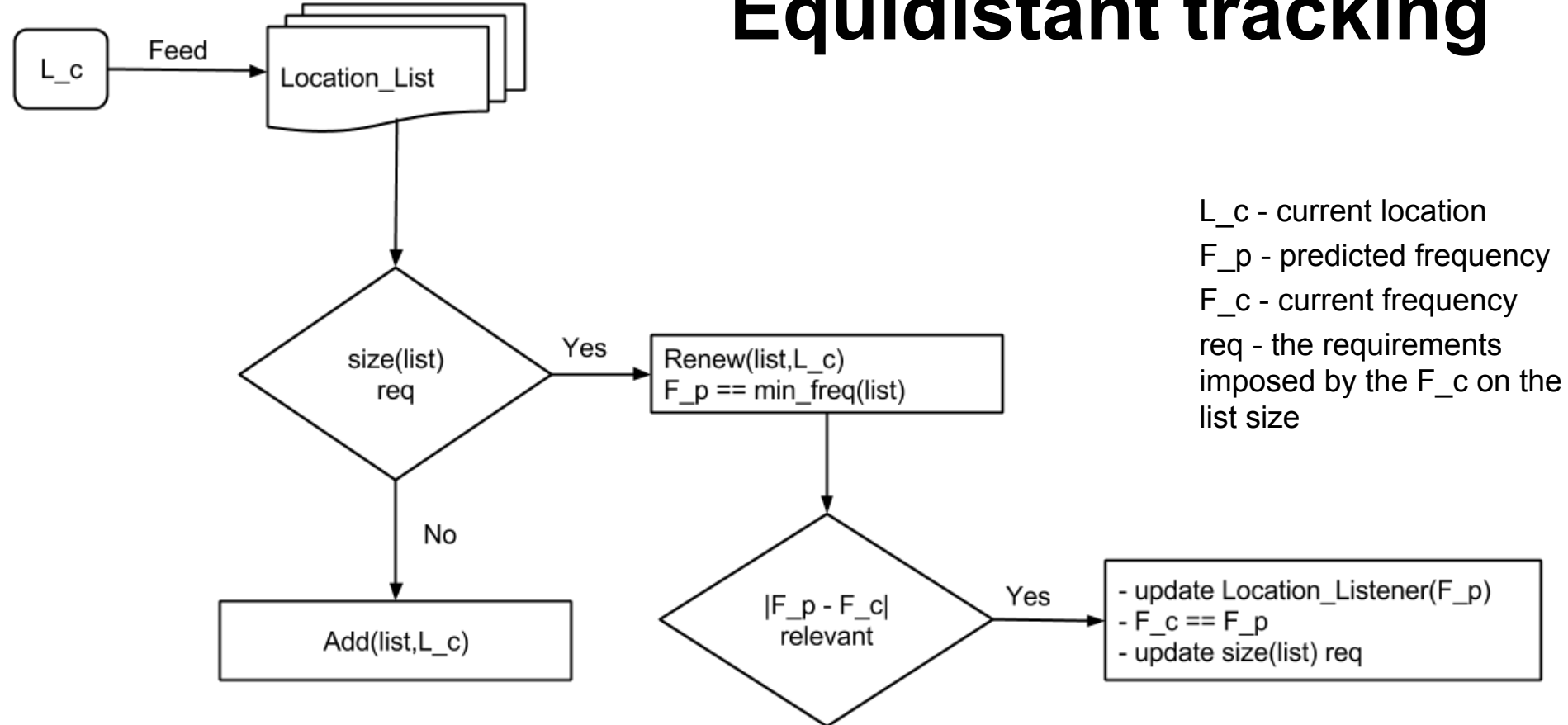
$L_p$  - potential  
location

$L_c$  - current  
location

$L_f$  - former  
instance of  $L_c$



# Equidistant tracking



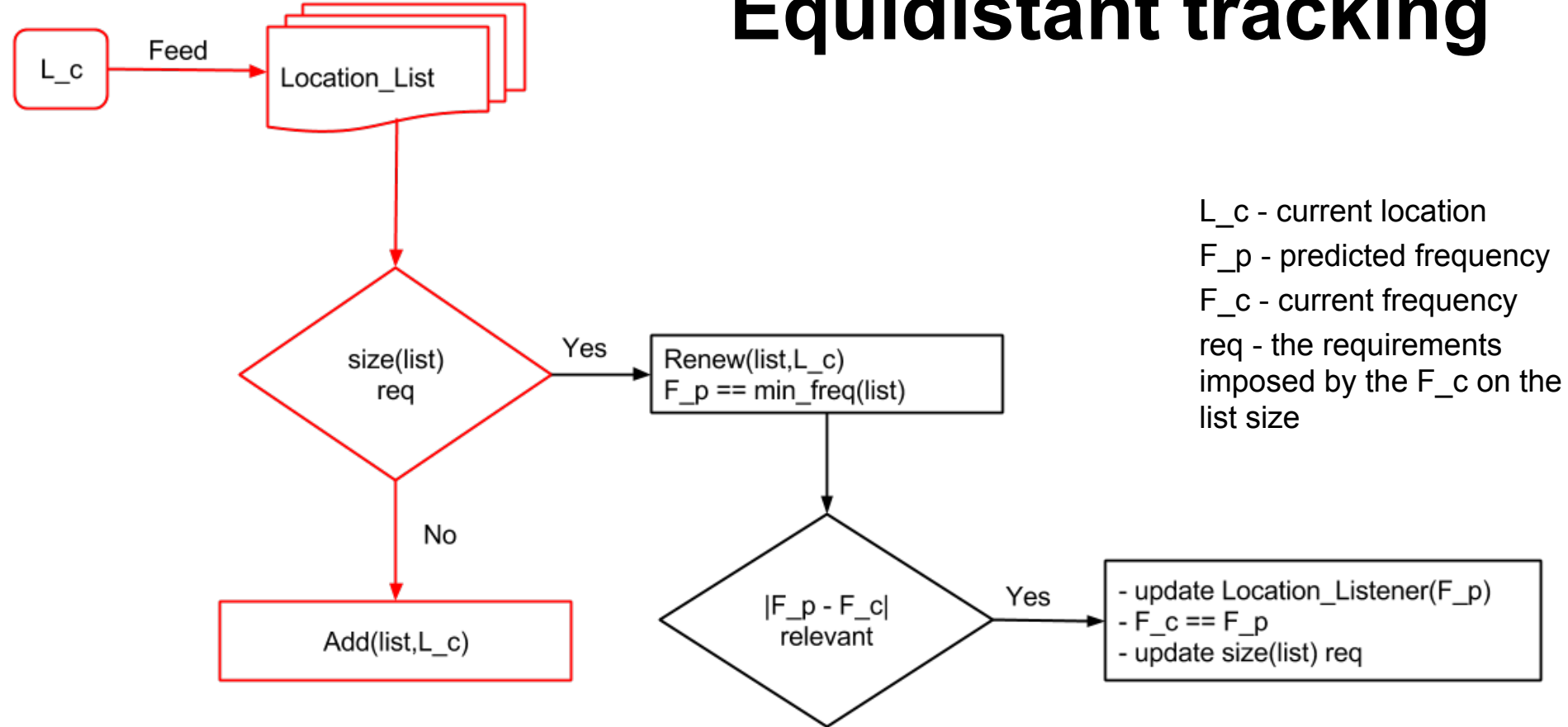
$L_c$  - current location

$F_p$  - predicted frequency

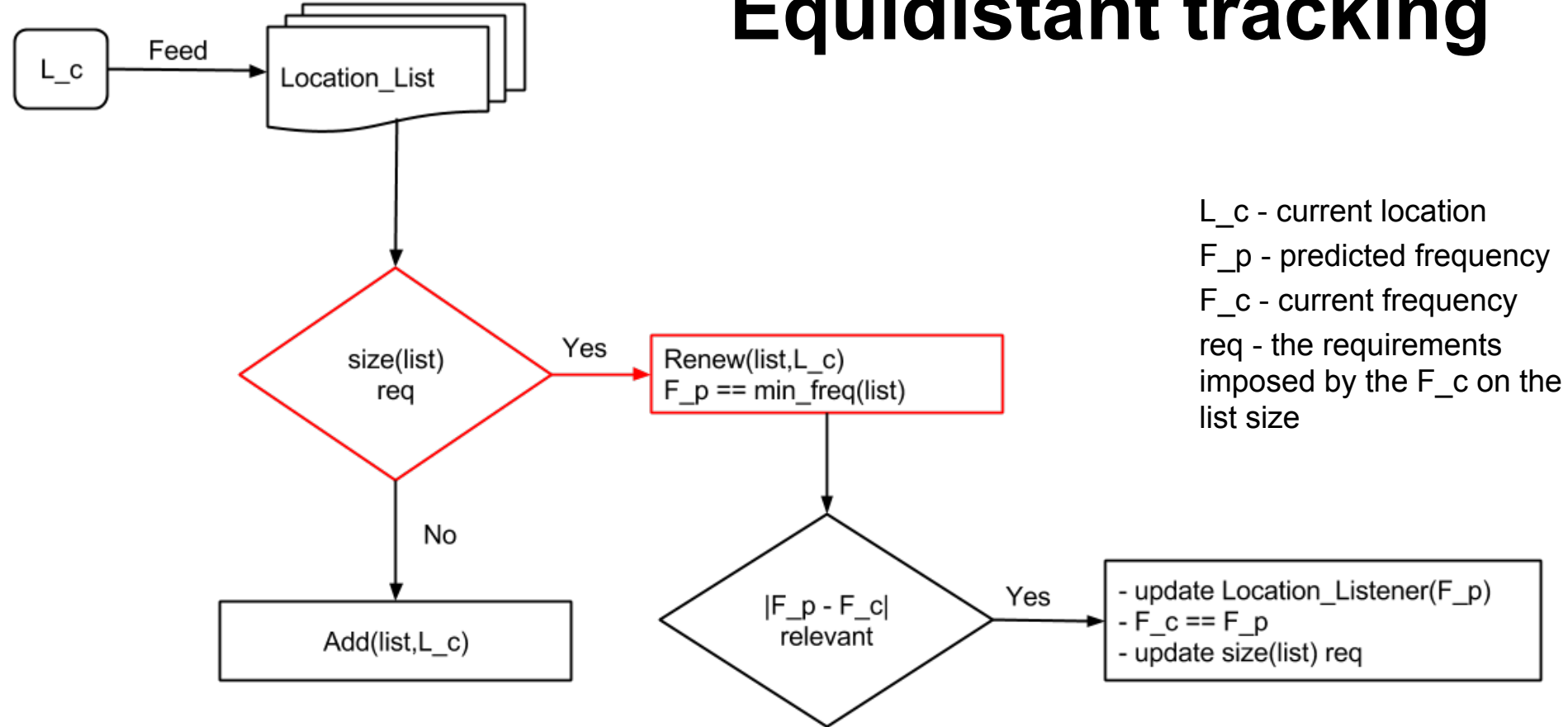
$F_c$  - current frequency

req - the requirements imposed by the  $F_c$  on the list size

# Equidistant tracking

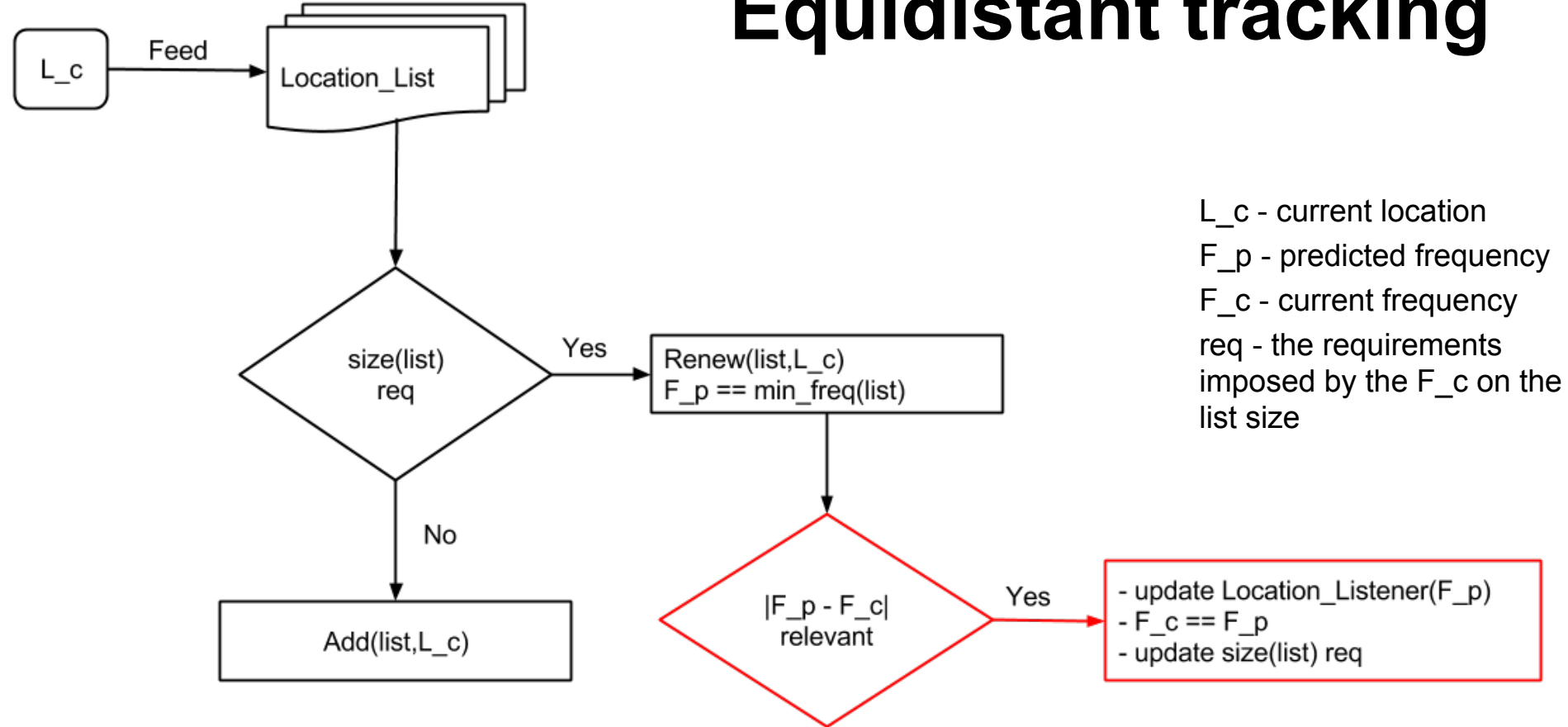


# Equidistant tracking



$L_c$  - current location  
 $F_p$  - predicted frequency  
 $F_c$  - current frequency  
req - the requirements imposed by the  $F_c$  on the list size

# Equidistant tracking



$L_c$  - current location  
 $F_p$  - predicted frequency  
 $F_c$  - current frequency  
req - the requirements imposed by the  $F_c$  on the list size

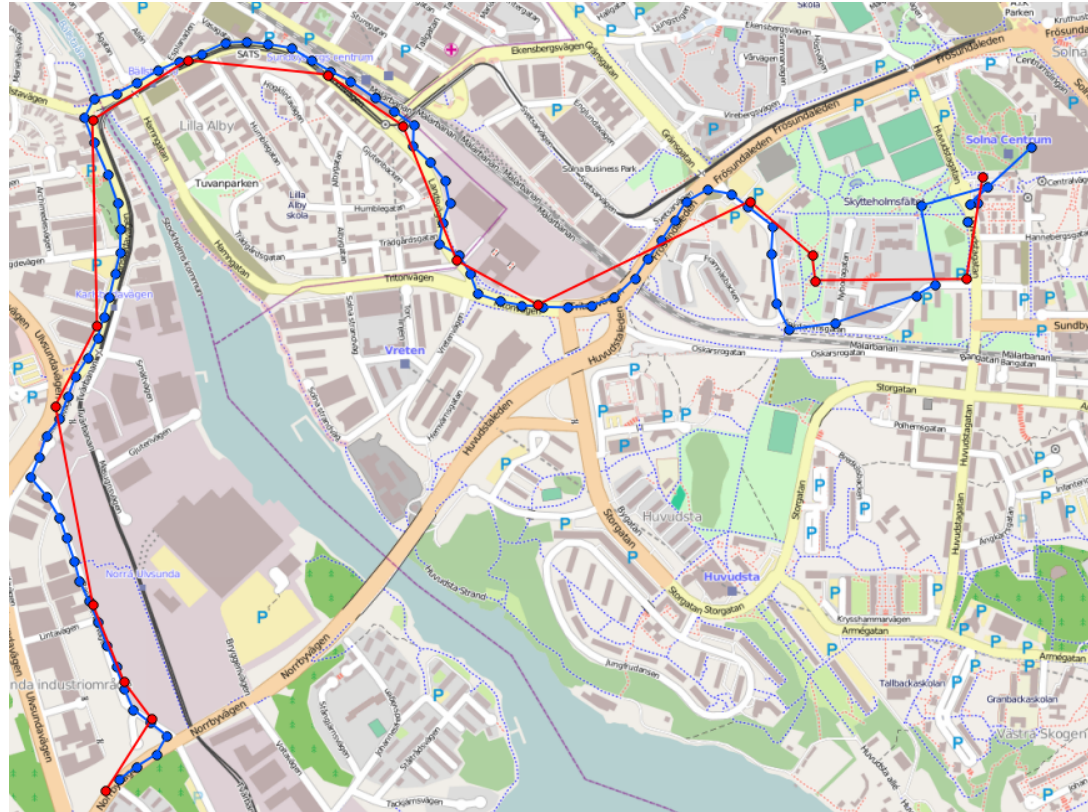
# Equitime vs. Equidistant Tracking

Equidistant(Blue)

Equitime(Red)

Sampling time = 50 s

Sampling distance = 50 m



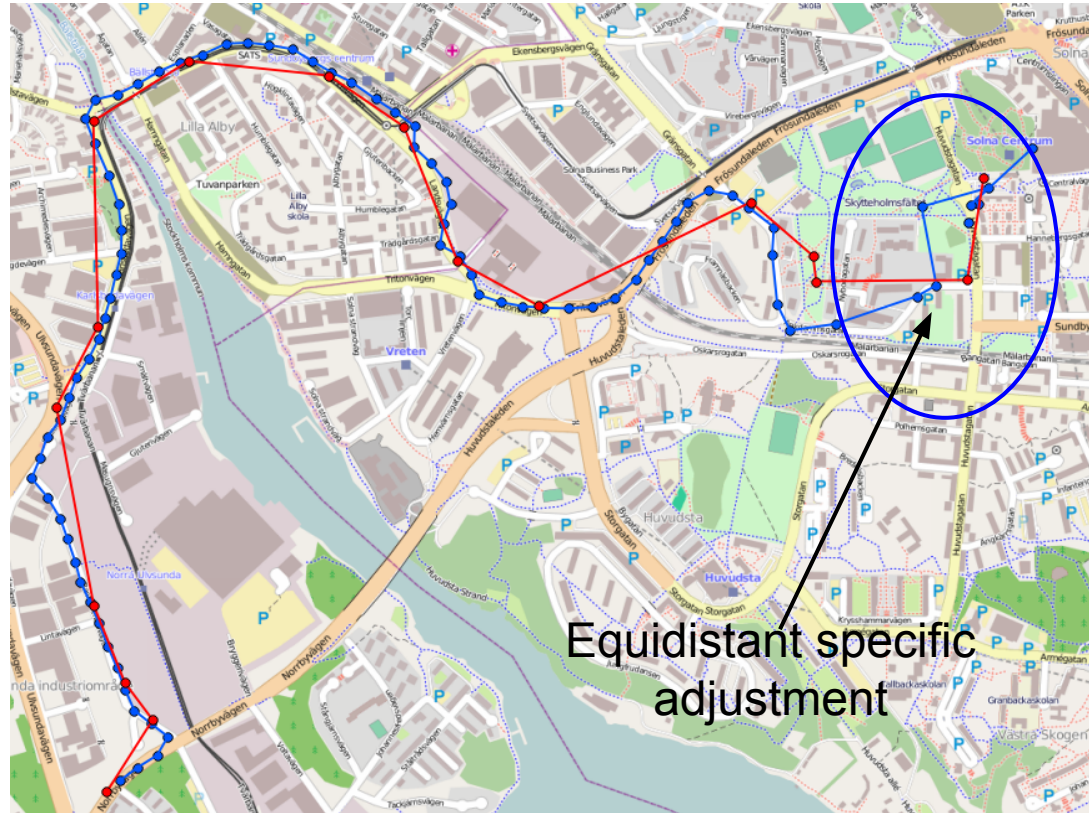
# Equitime vs. Equidistant Tracking

Equidistant(Blue)

Equitime(Red)

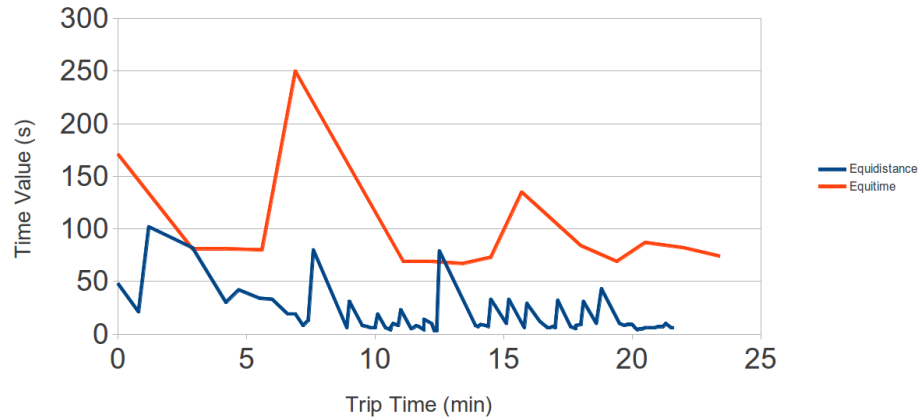
Sampling time = 50 s

Sampling distance = 50 m

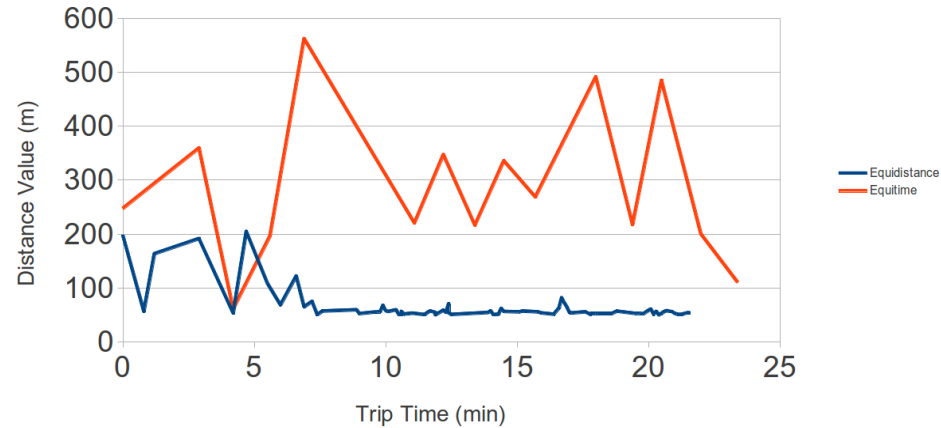


# Equitime vs. Equidistant Tracking

Time between locations

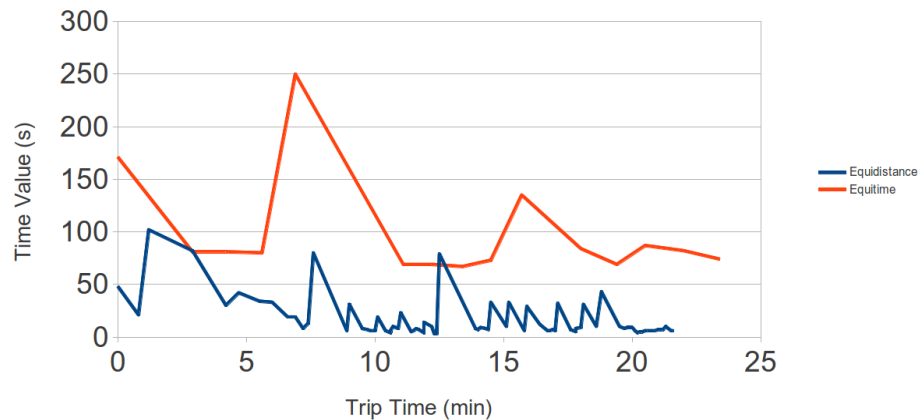


Distance between locations

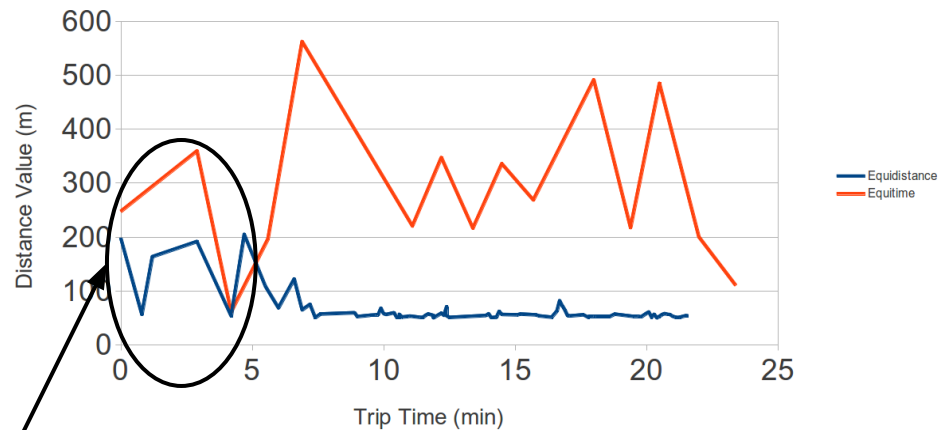


# Equitime vs. Equidistant Tracking

Time between locations



Distance between locations

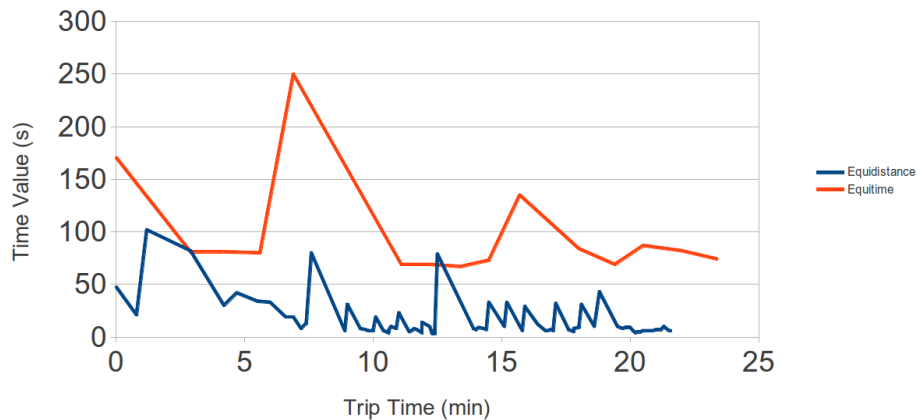


Equidistant specific  
adjustment

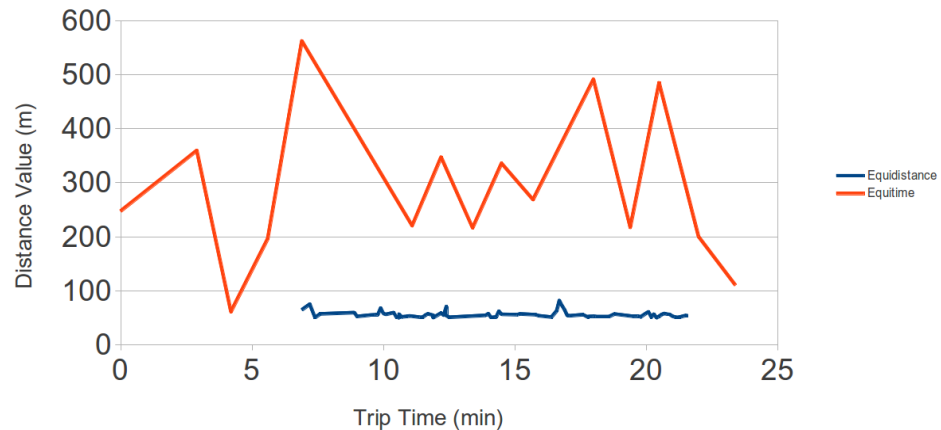


# Equitime vs. Equidistant Tracking

Time between locations



Distance between locations



# Equitime vs. Equidistant Tracking


Stats	Equitime		Equidistant		Equidistant – after initialization	
	Distance (m)	Time (s)	Distance (m)	Time (s)	Distance (m)	Time (s)
Avg	287.9	98.1	64.2	15.8	56.1	12.1
Std. Dev.	141.9	50.7	30.8	19.2	6.0	14.1
Min	61.3	67.0	50.1	3.0	50.1	3.0
Max	562.4	250.0	204.9	102.0	82.0	80.0
# of Records	15		82		73	

Sampling time = 50 s

Sampling distance = 50 m

# Equitime vs. Equidistant Tracking

Stats	Equitime		Equidistant		Equidistant – after initialization	
	Distance (m)	Time (s)	Distance (m)	Time (s)	Distance (m)	Time (s)
Avg	287.9	98.1	64.2	15.8	56.1	12.1
Std. Dev.	141.9	50.7	30.8	19.2	6.0	14.1
Min	61.3	67.0	50.1	3.0	50.1	3.0
Max	562.4	250.0	204.9	102.0	82.0	80.0
# of Records	15		82		73	

- 
1. Low number of records
  2. Time for the “actual” fix

Sampling time = 50 s

Sampling distance = 50 m

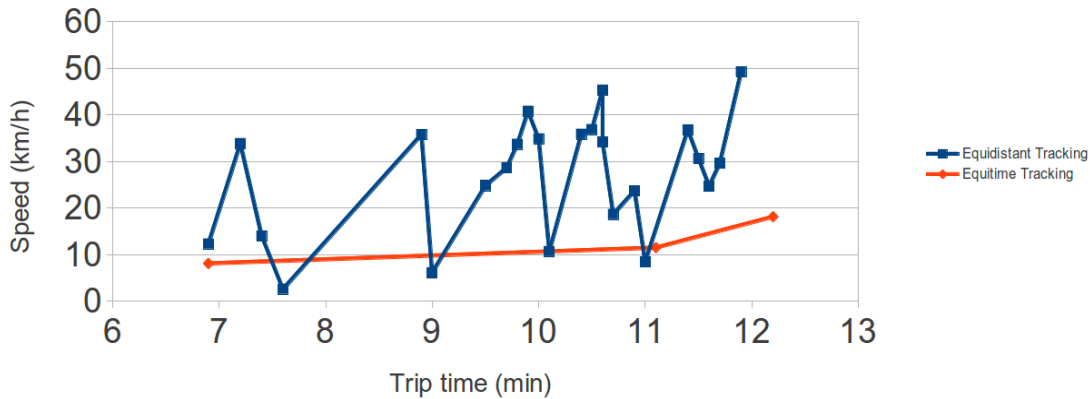
# Equitime vs. Equidistant Tracking

Stats	Equitime		Equidistant		Equidistant – after initialization	
	Distance (m)	Time (s)	Distance (m)	Time (s)	Distance (m)	Time (s)
Avg	287.9	98.1	64.2	15.8	56.1	12.1
Std. Dev.	141.9	50.7	30.8	19.2	6.0	14.1
Min	61.3	67.0	50.1	3.0	50.1	3.0
Max	562.4	250.0	204.9	102.0	82.0	80.0
# of Records	15		82		73	

Sampling time = 50 s

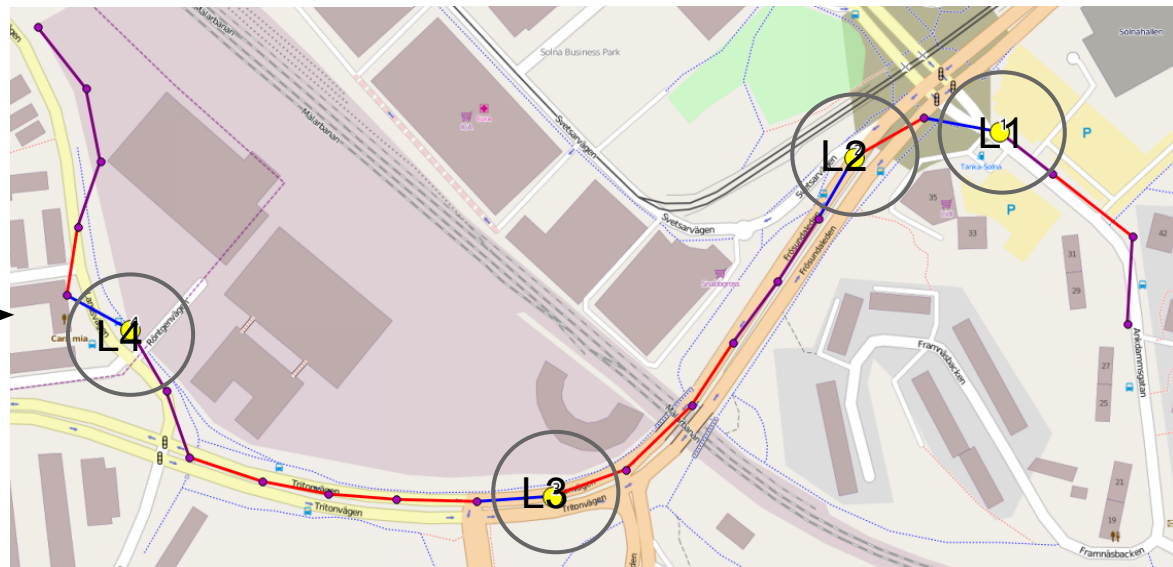
Sampling distance = 50 m

Speed fluctuations

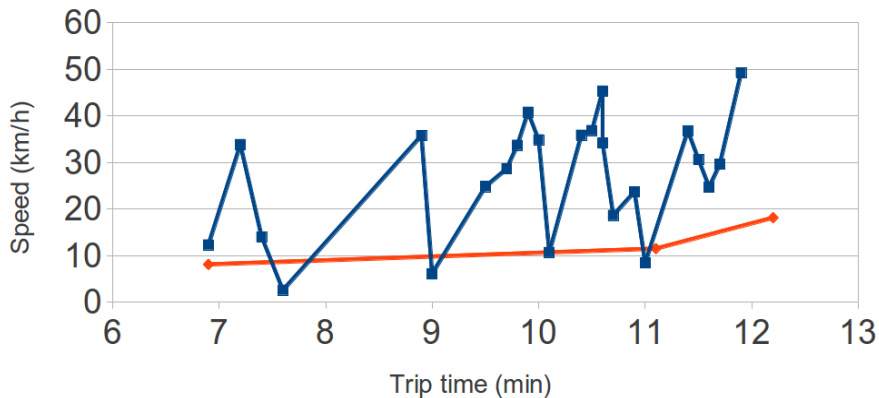


# Case study

OSM-derived semantics



Speed fluctuations



# Case study

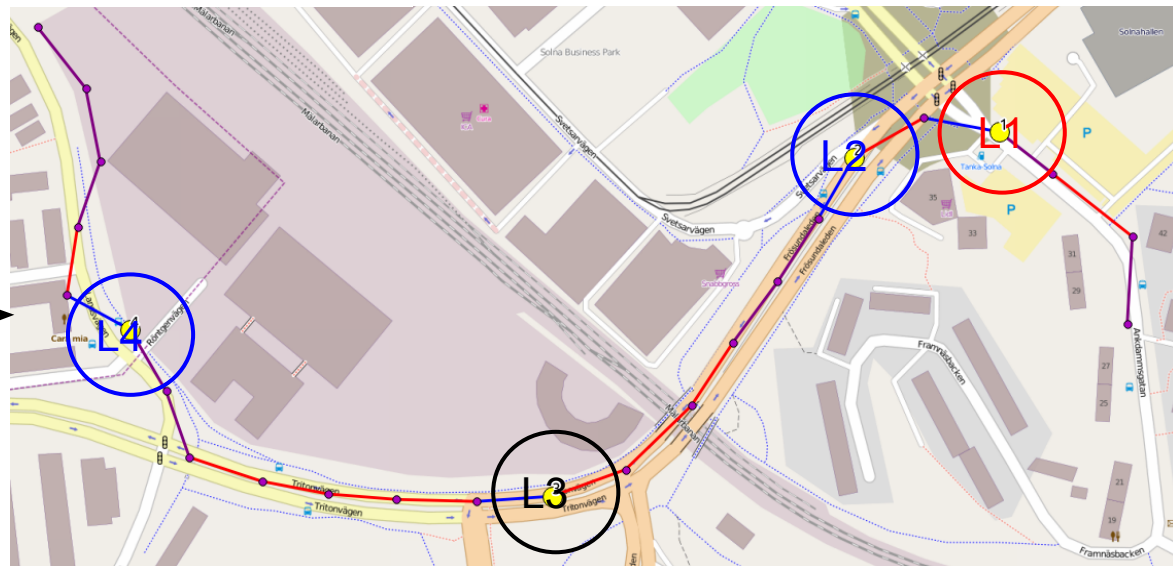
Analysis (based on proximity) result:

L1 - traffic light

L2,L4 - bus stop

L3 - no features of interest in its vicinity

OSM-derived semantics



# Equitime vs. Equidistant Tracking

## Equitime tracking

- Good for **general purpose** apps
- Spatial granularity is of little or no importance
- **Linear** battery drainage

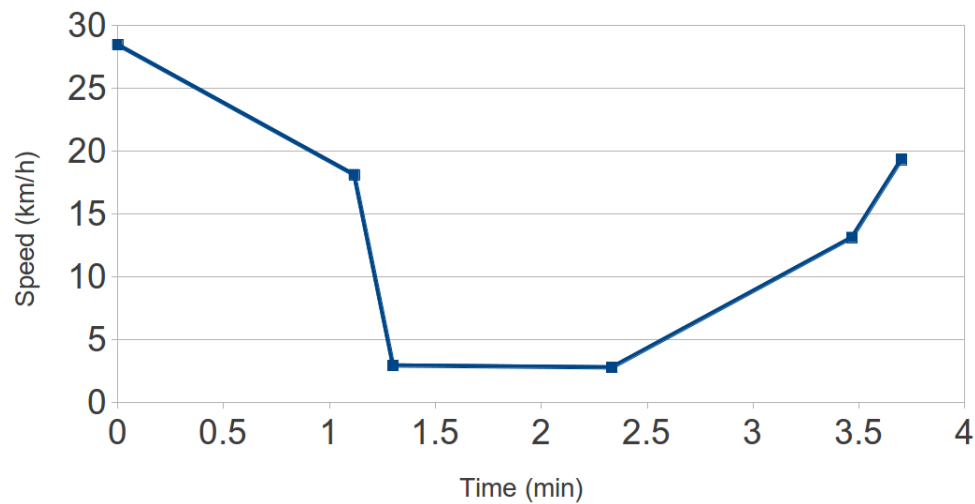
## Equidistant tracking

- Good for inferring **context**
- Spatial granularity takes precedence over the temporal one
- Battery drainage **depends on the speed** of the phone bearer

# Data (in)sufficiency

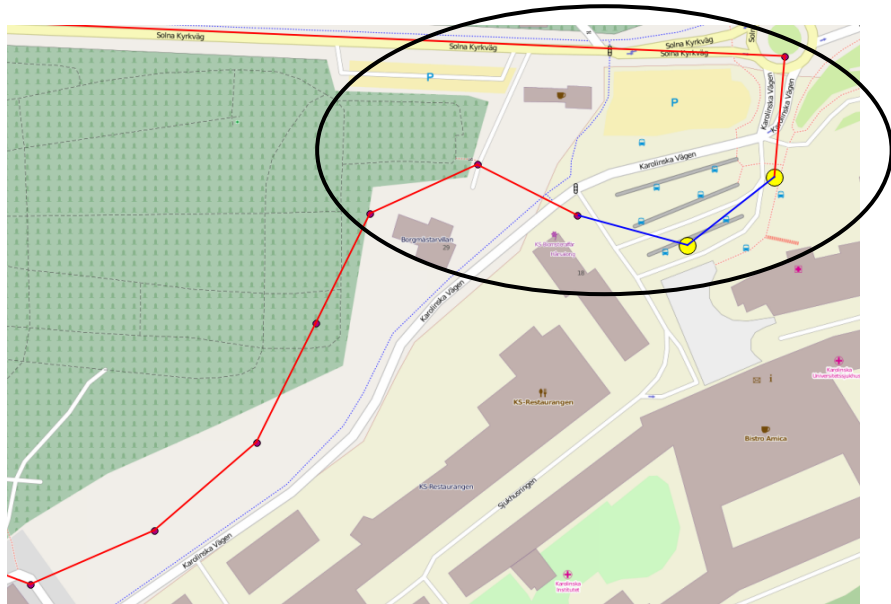


Speed fluctuation





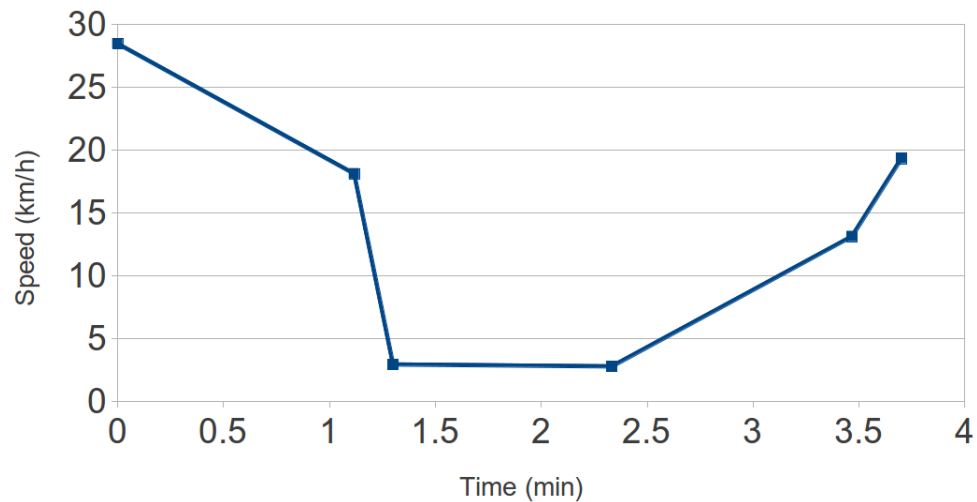
# Data (in)sufficiency



Location data  $\Leftrightarrow$  spatial displacement

Location data  $\neq$  movement

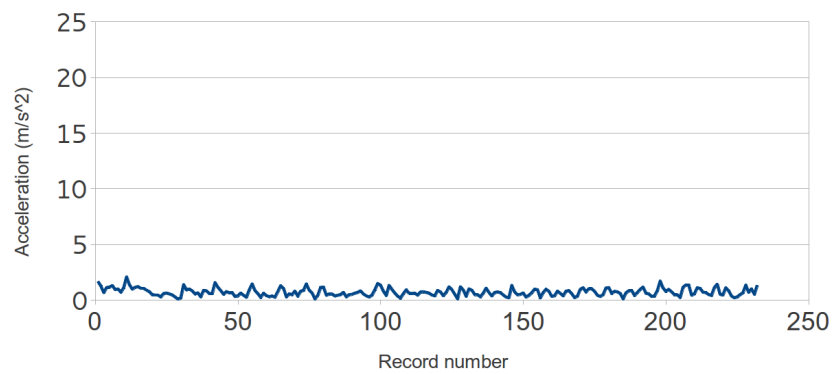
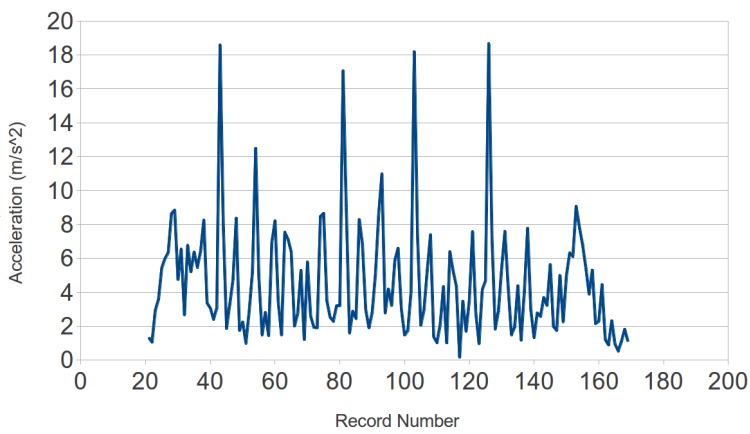
Speed fluctuation





Walking

No relevant movement



Physical context makes the data robust

# Embedded accelerometer

Basic statistics measurements (average, std. dev., min, max) for **all axis** and for **total acceleration**

Movement detection

Number of peaks

Pedometer

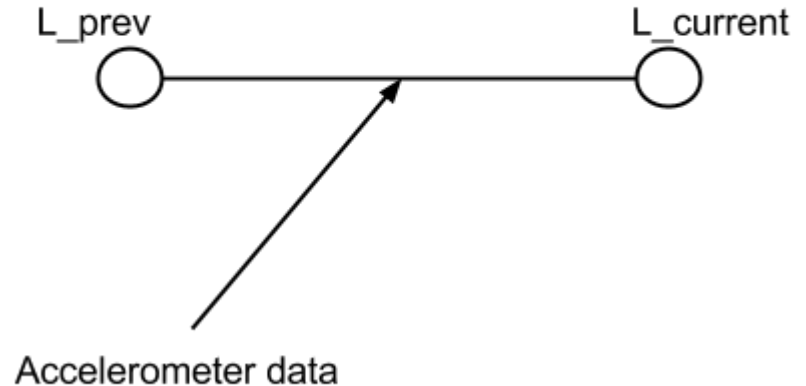
# Embedded accelerometer

Basic statistics measurements (average, std. dev., min, max) for **all axis** and for **total acceleration**

Movement detection

Number of peaks

Pedometer

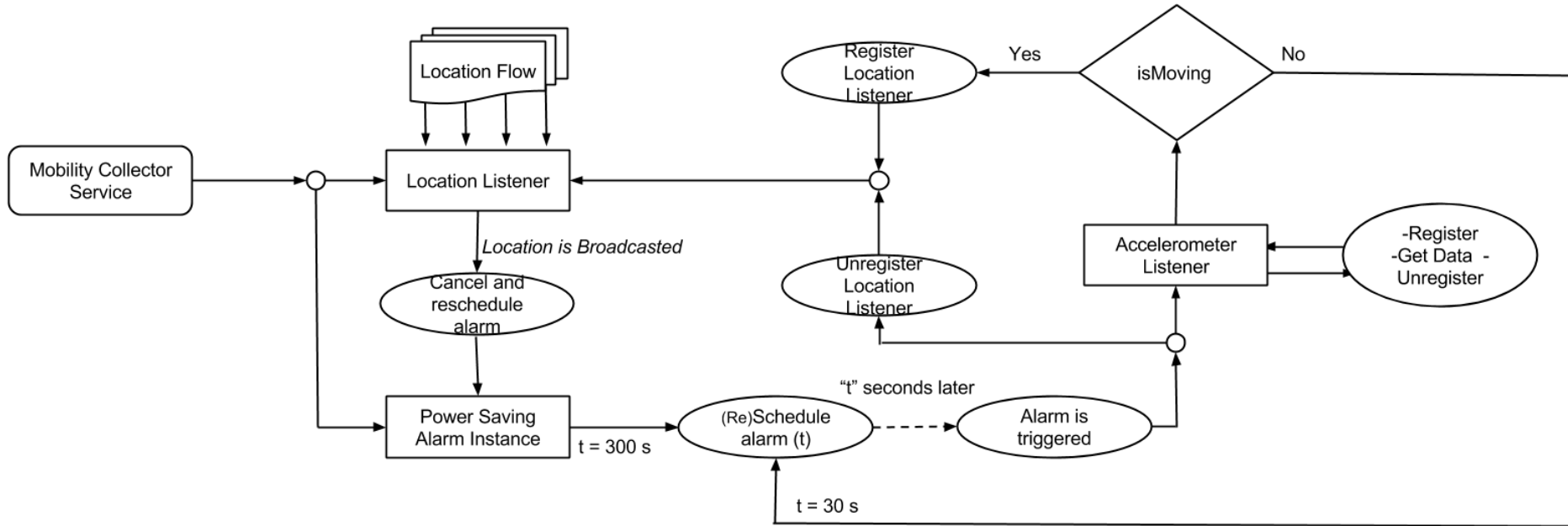


# Usability

Battery drainage **restricts** the number of candidates in most research experiments

Users should still be able to use their phones while collecting data without having to worry about a battery **overkill**

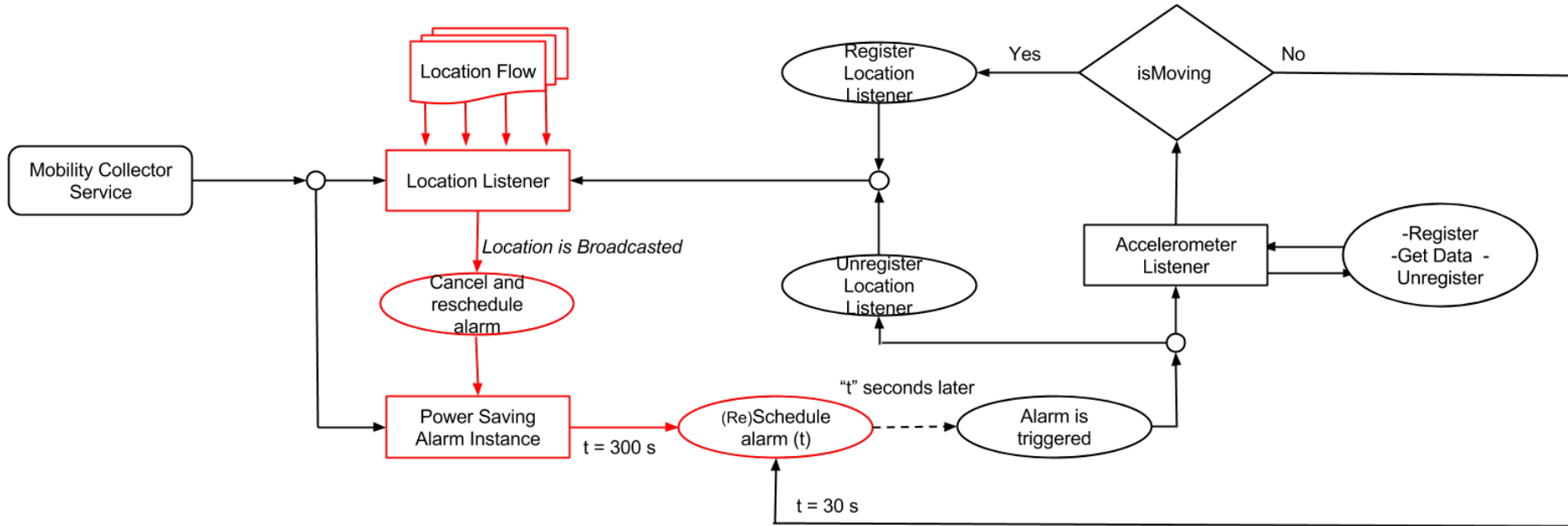
# Power Saving



The alarm has two instances:

- location instance (spatial context)
- accelerometer instance (physical context)

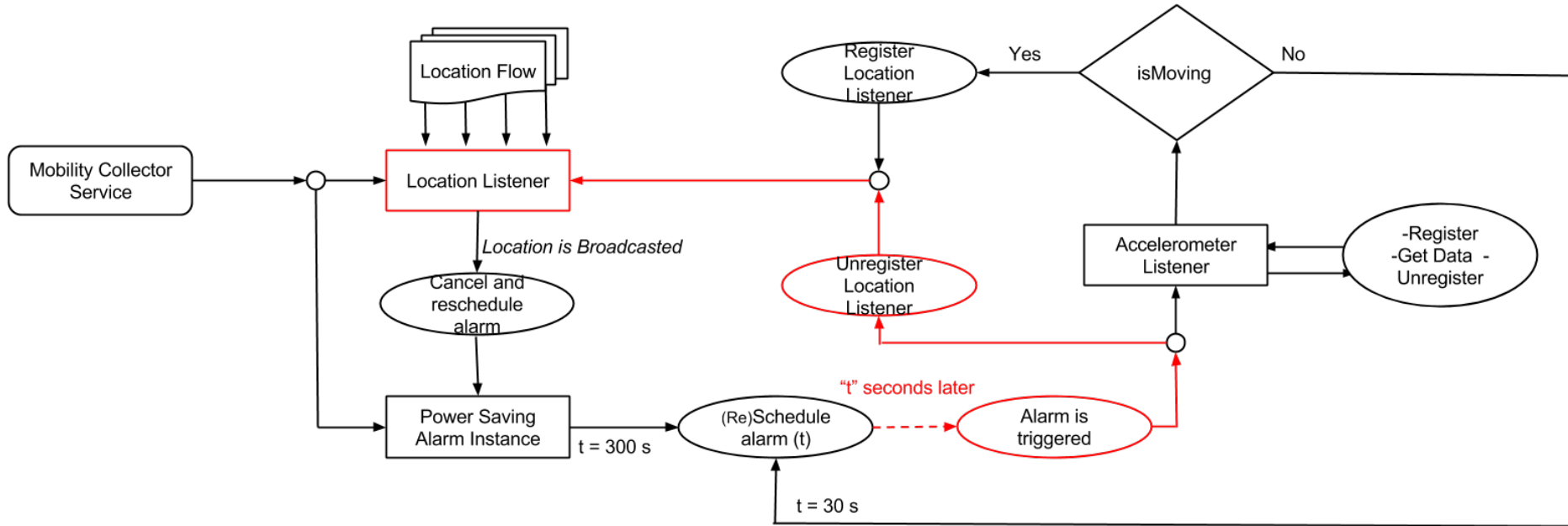
# Power Saving



The alarm has two instances:

- location instance (spatial context)
- accelerometer instance (physical context)

# Power Saving

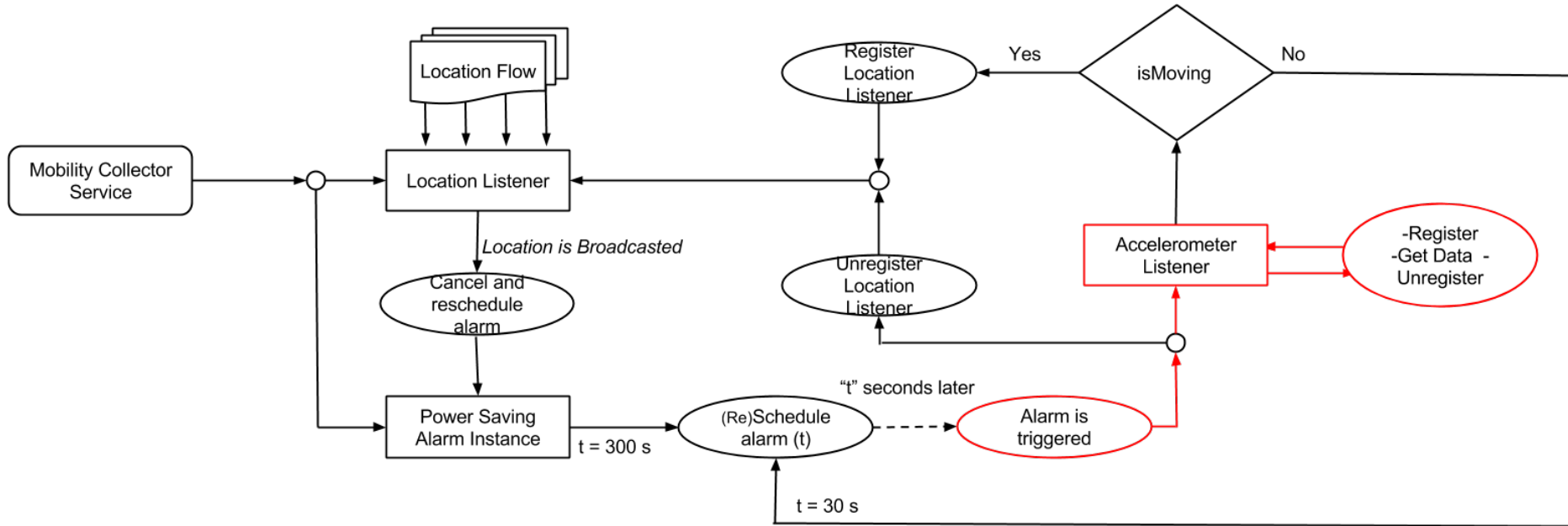


The alarm has two instances:

- location instance (spatial context)
- **accelerometer instance (physical context)**



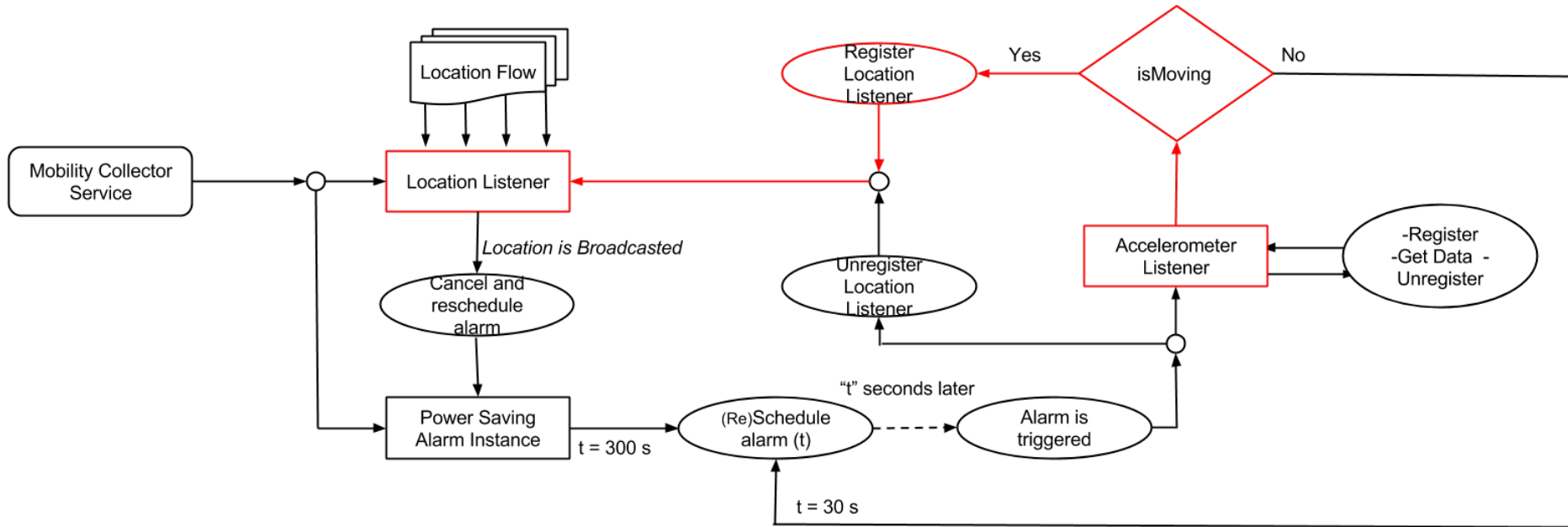
# Power Saving



The alarm has two instances:

- location instance (spatial context)
- **accelerometer instance (physical context)**

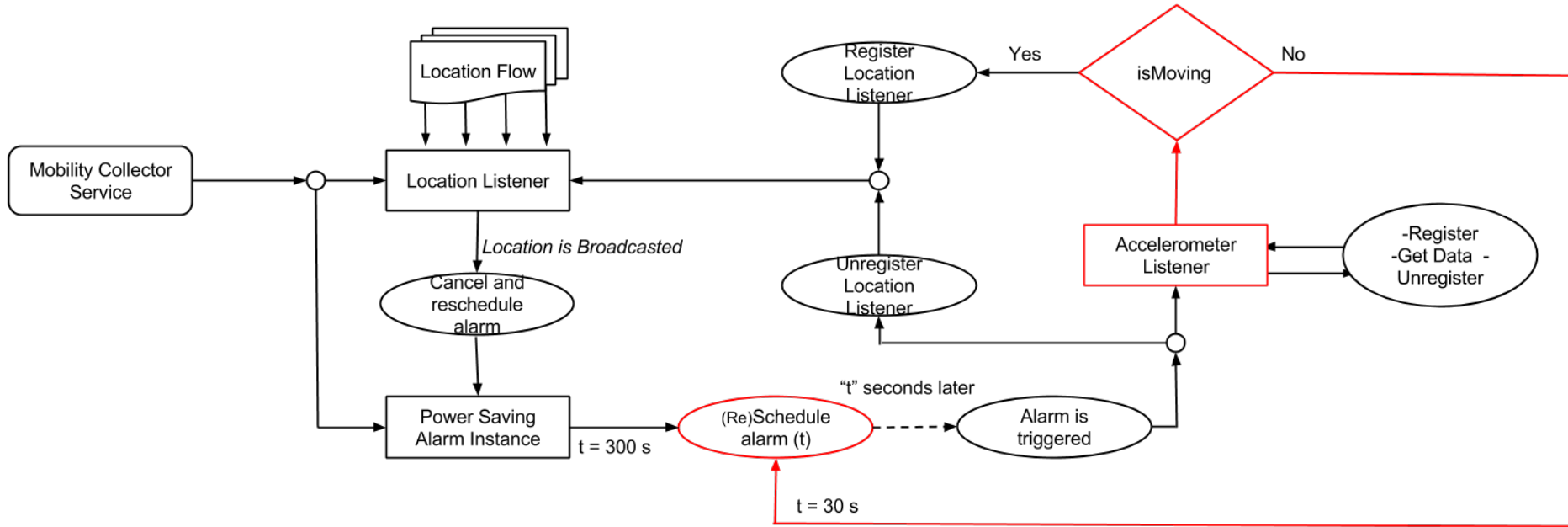
# Power Saving



The alarm has two instances:

- location instance (spatial context)
- **accelerometer instance (physical context)**

# Power Saving



The alarm has two instances:

- location instance (spatial context)
- **accelerometer instance (physical context)**

# Battery Saving Results

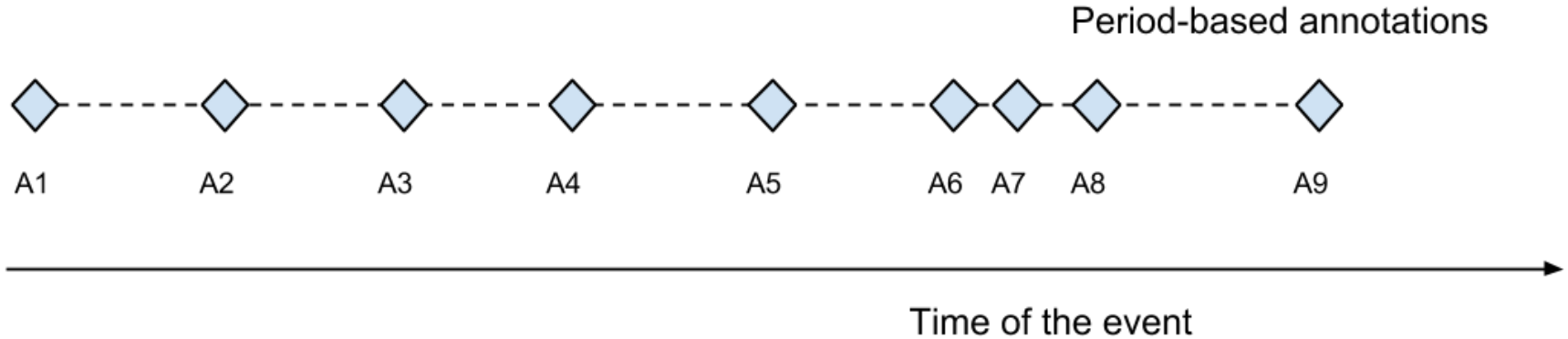


# Annotations

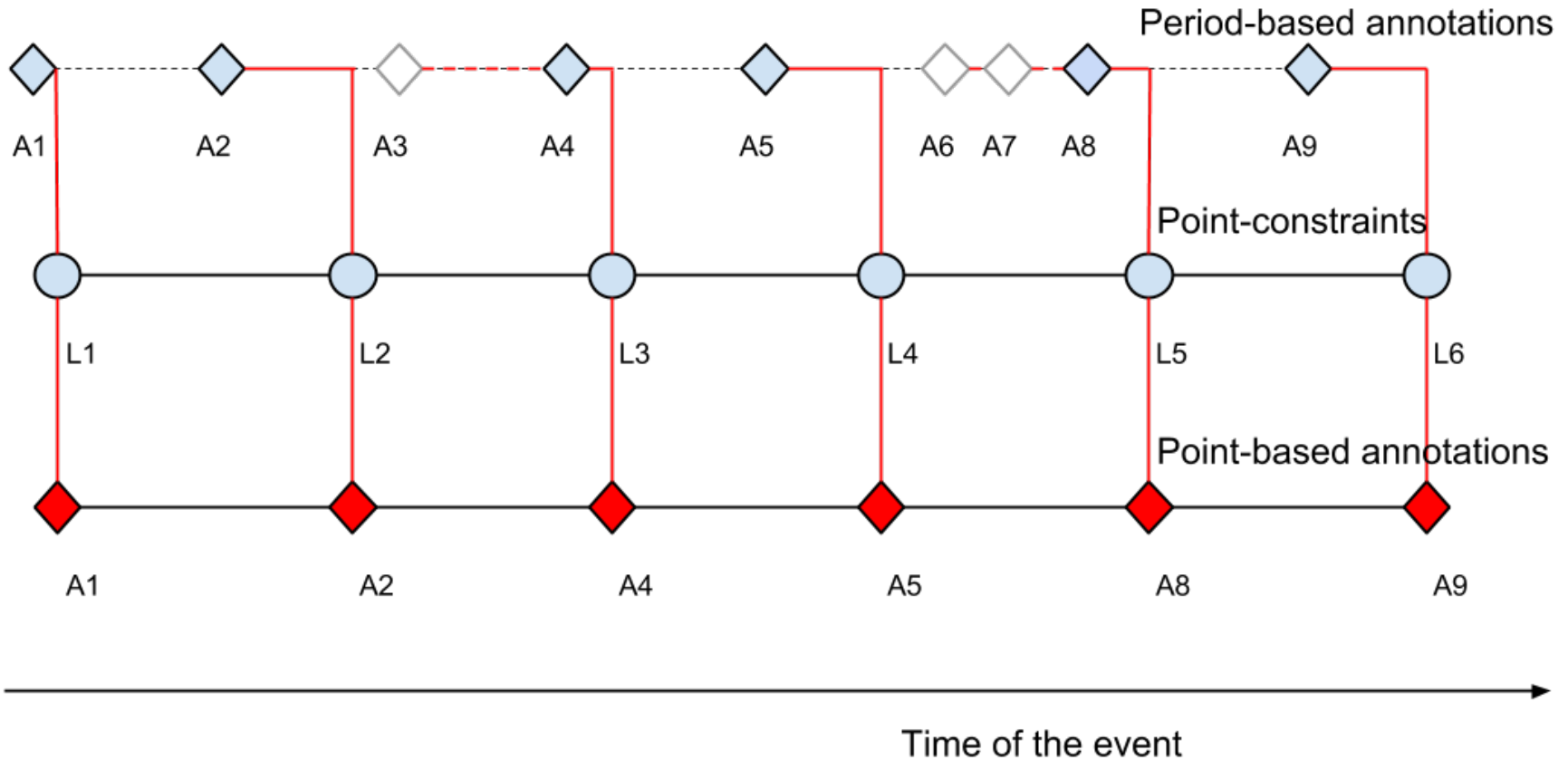
Annotations are particularly useful:

- For obtaining **training samples** for different types of classifications
- As a measure of **(re)assurance** for the correctness of particular types of algorithms
- Adding a **spatial component** to qualitative data types

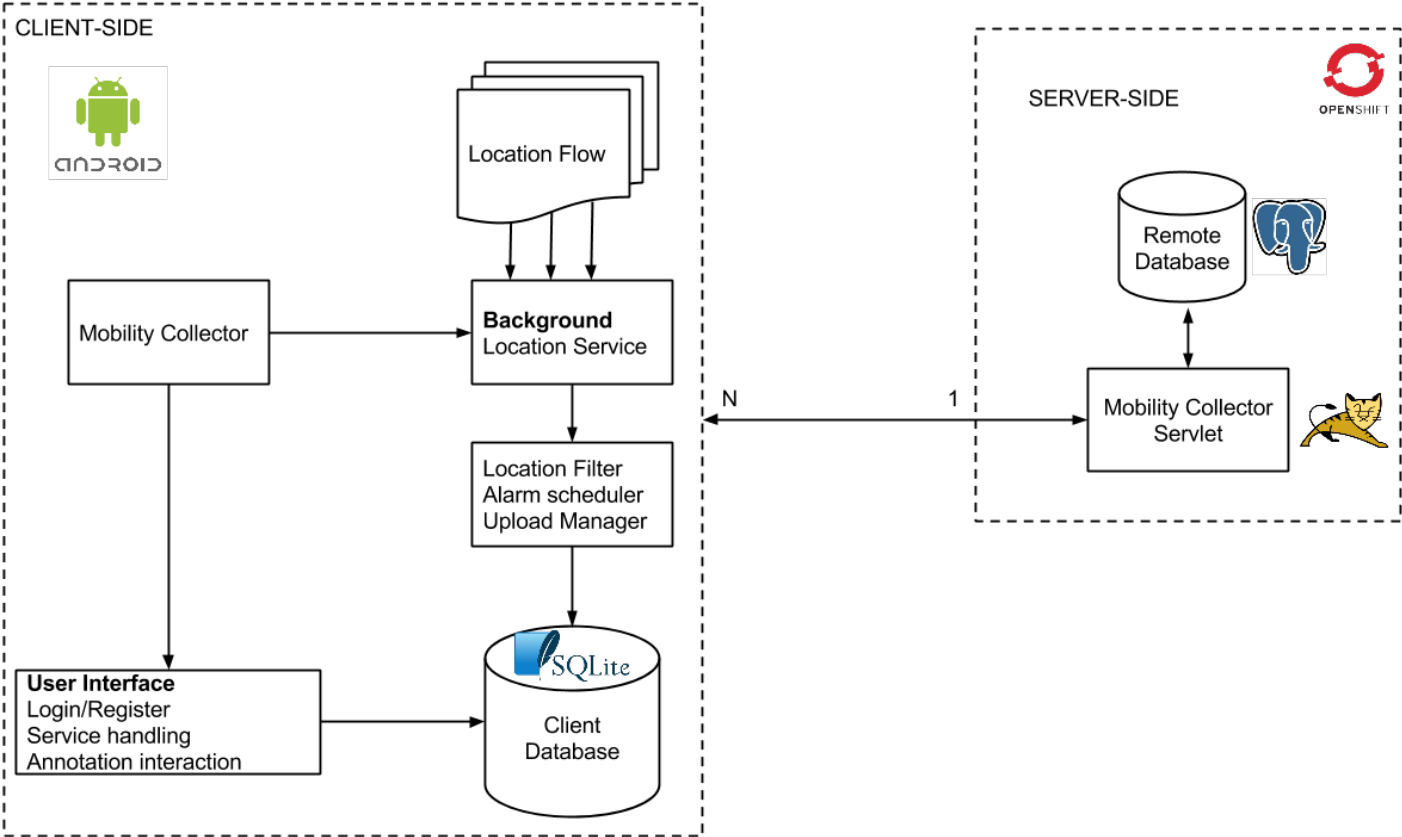
# Point- and period-based annotations



# Point- and period-based annotations
















# Architecture





## App details

About section:	<div style="border: 1px solid green; padding: 5px;">This app will mainly be used for research purposes </div>
System Architecture:	Client-Server 
Sampling type:	Equidistance 
Sampling time(seconds)	30 
Sampling distance(meters)	50 
Accuracy constraint:	35 
Accelerometer:	Yes 
Servlet URL:	http://infra.kth.se 
Trajectory annotation:	Point-based 
Enable Power-Saving:	Yes 
Auto Upload:	True 
Upload Frequency:	1 
Annotation Items:	<div style="border: 1px solid green; padding: 5px;">walking running driving </div>

# Using Mobility Collector

Service running in Alfa mode on a VM at: [http://130.237.68.66:8080/Mobility\\_Collector\\_Form/HomePage.jsp](http://130.237.68.66:8080/Mobility_Collector_Form/HomePage.jsp)

**Tutorials and future references will be posted on GitHub**

Android Application Source Code:

[https://github.com/adrianprelipcean/Mobility\\_Collector\\_Android](https://github.com/adrianprelipcean/Mobility_Collector_Android)

Apache Tomcat Servlet Source Code:

[https://github.com/adrianprelipcean/kth\\_mobility\\_collector](https://github.com/adrianprelipcean/kth_mobility_collector)

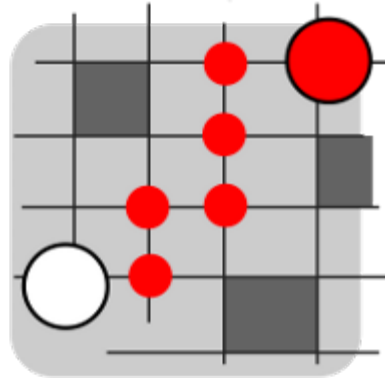
# Summary

- Location tracking, its importance and current status
- **Mobility Collector** - a mobile tracking platform
- Equitime and equidistant tracking
- Data sufficiency and robustness
- Usability of **Mobility Collector**

# Thank you!



ROYAL INSTITUTE  
OF TECHNOLOGY



## Q&A?

[acpr@kth.se](mailto:acpr@kth.se)

[adrianprelipceanc@gmail.com](mailto:adrianprelipceanc@gmail.com)